

Provable Submodular Minimization using Wolfe's Algorithm

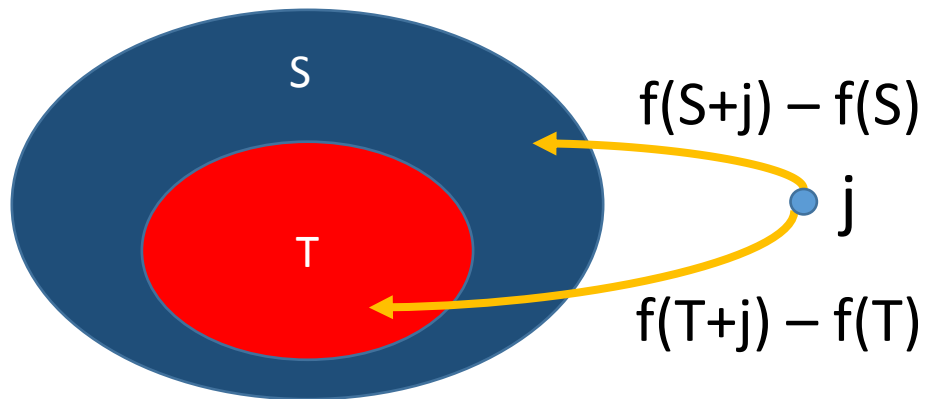
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Submodular Functions

- f : Subsets of $\{1,2,\dots,n\} \rightarrow$ integers
- **Diminishing Returns Property.**

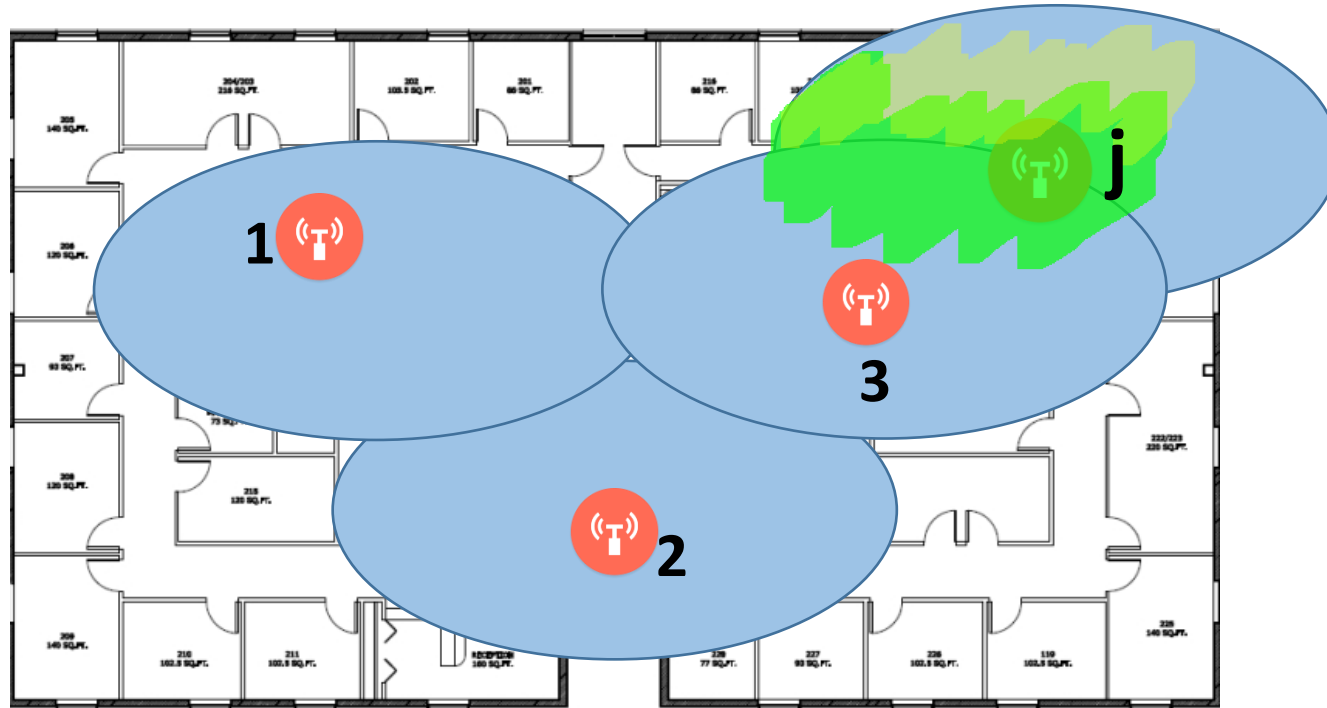


For all S , for all $T \subseteq S$,
for all j not in S :

$$f(S + j) - f(S) \leq f(T + j) - f(T)$$

- f may or may not be **monotone**.

Sensor Networks



Universe: Sensor Locations. $f(A)$ = “Area covered by sensors”

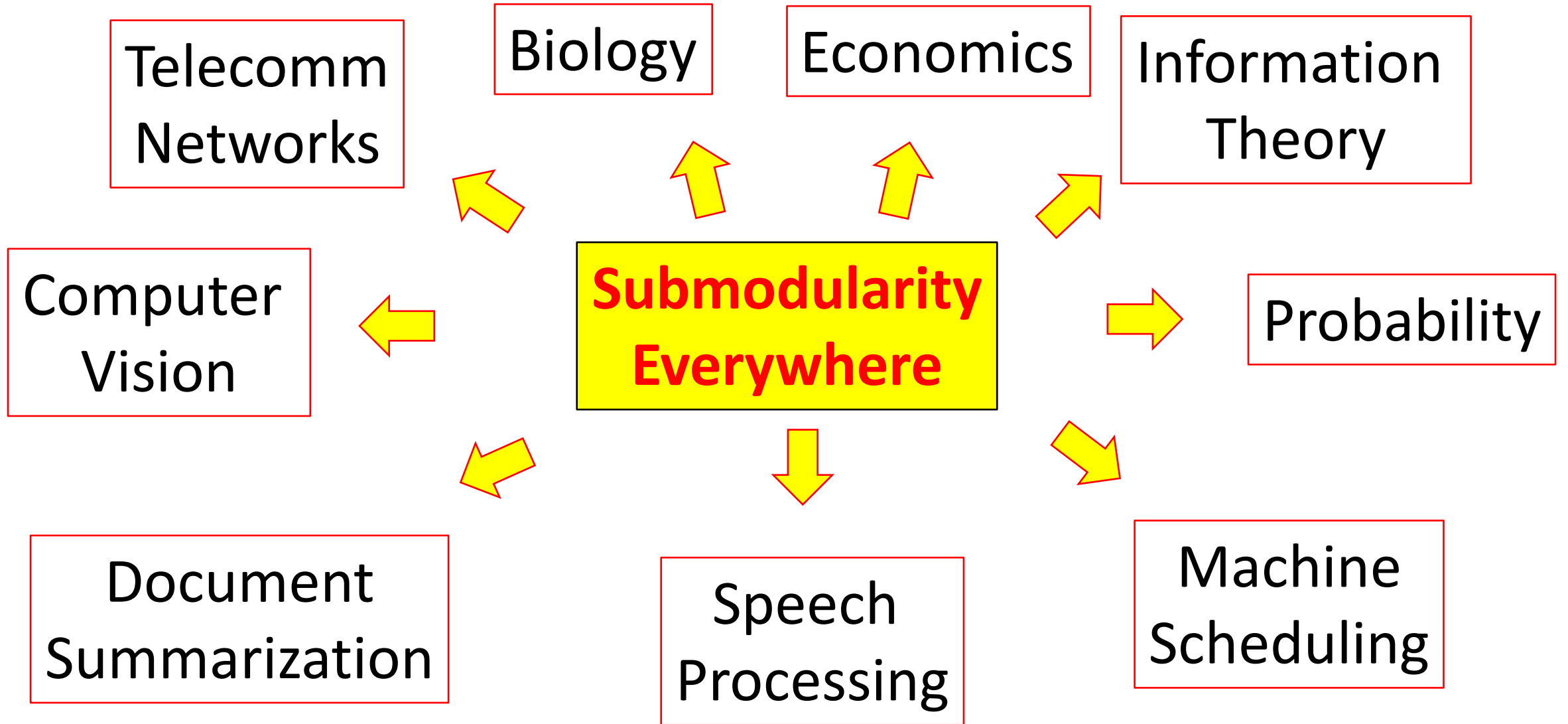
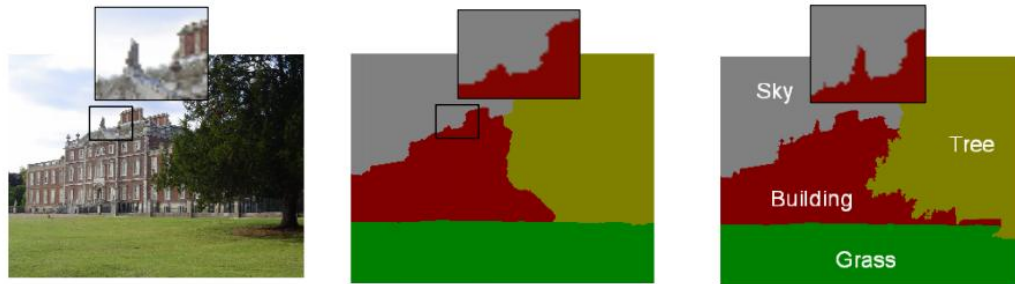


Image Segmentation



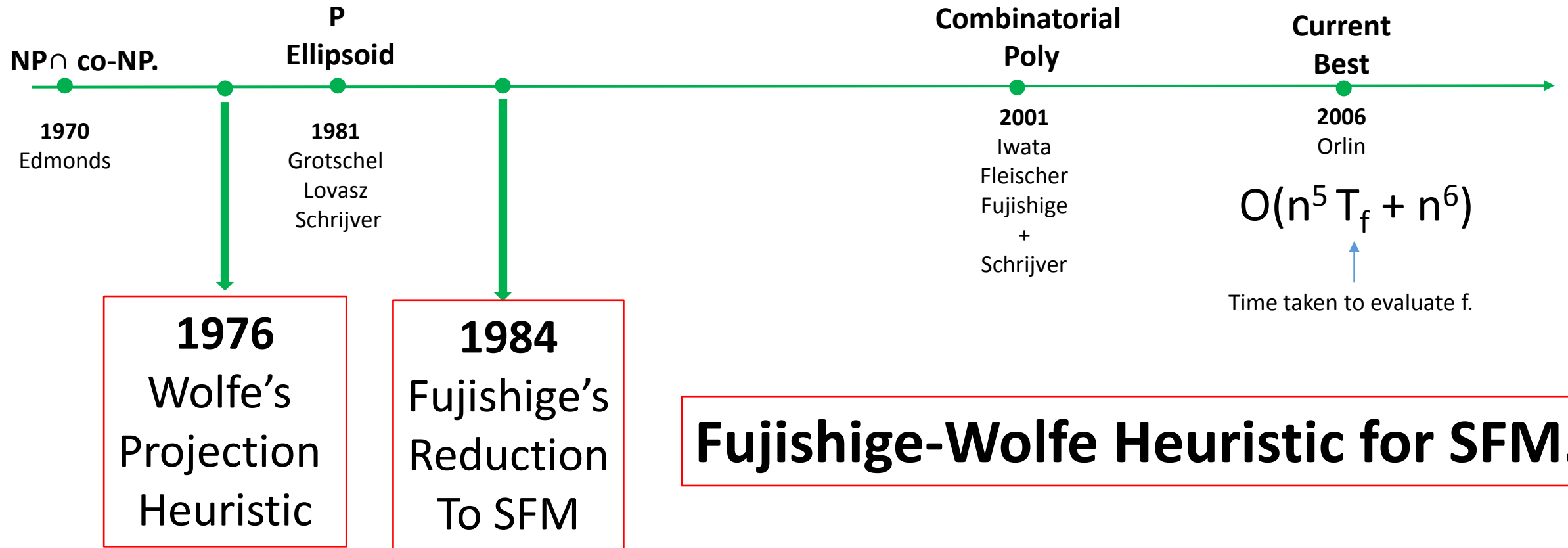
Labelling "Energy" function Observed Image

$X = \arg \min E(X | D)$

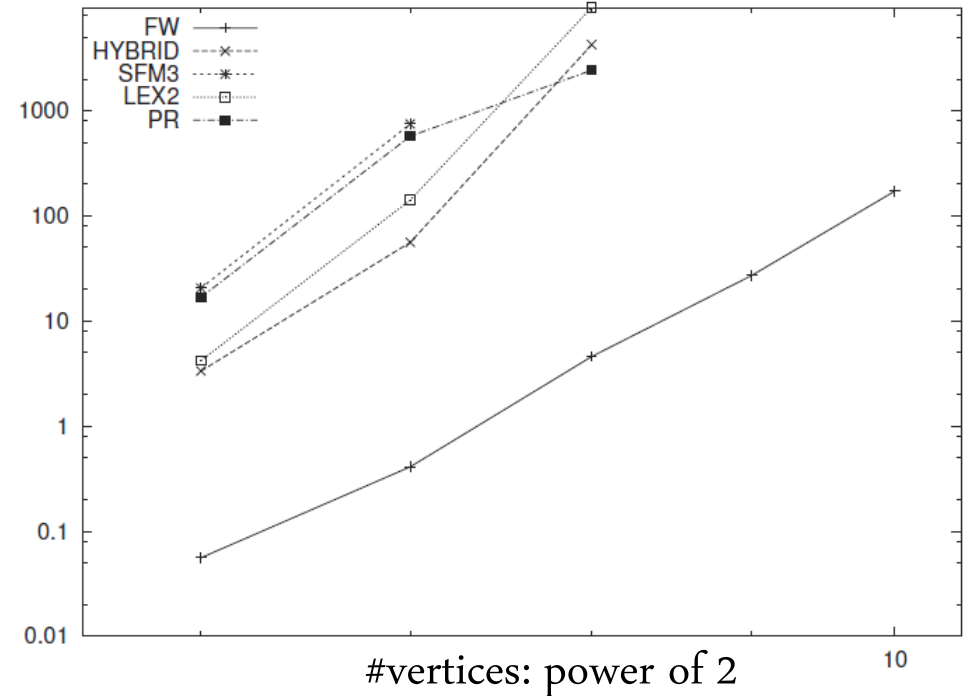
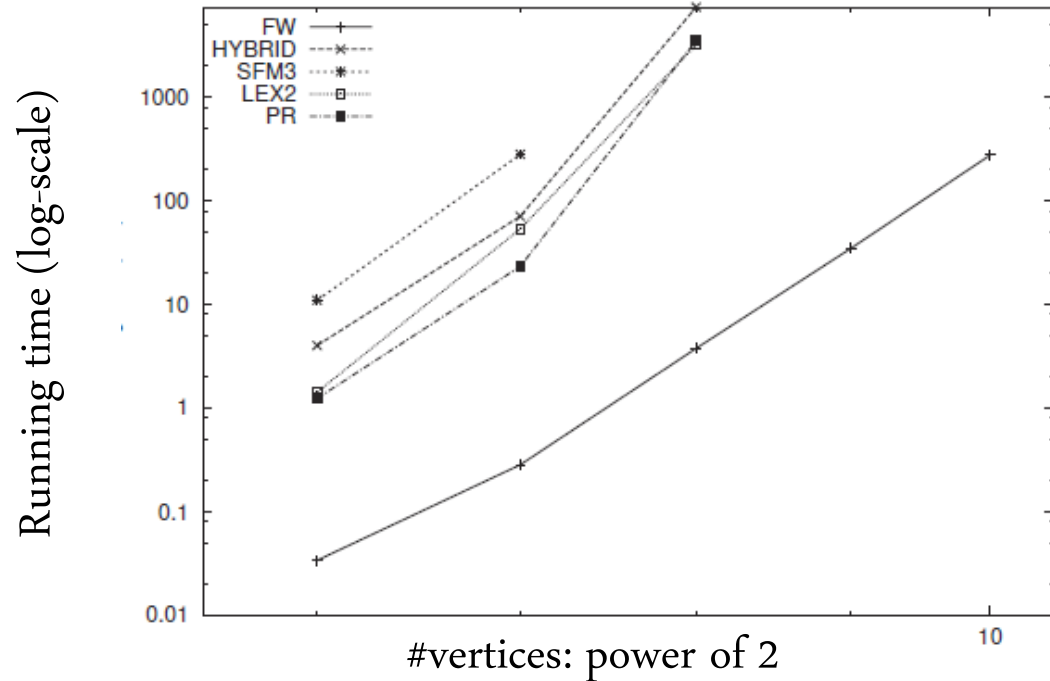
Energy minimization done via reduction to submodular function minimization.

Submodular Function Minimization

Find set S which minimizes $f(S)$



Theory vs Practice



Cut functions from DIMACS Challenge

Is it good in theory?

Theoretical guarantee so far

$$2^{O(n^2)}$$

Today

Fujishige-Wolfe is (pseudo)**polynomial**.

$$O(n^7 F^2), F = \max_i |f(\{i\})|$$

Fujishige-Wolfe Heuristic

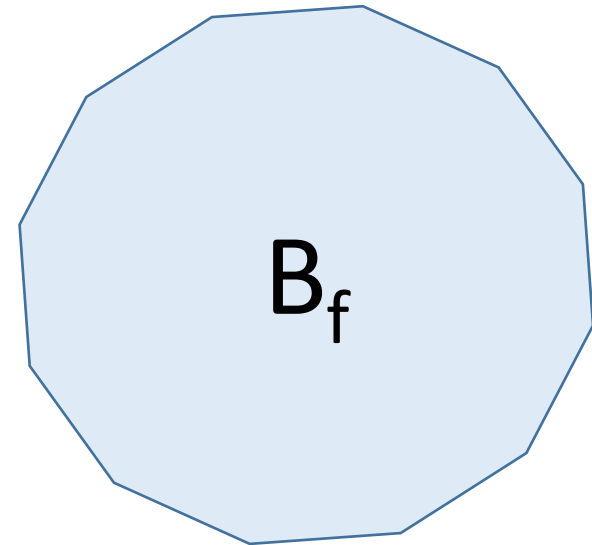
- **Fujishige Reduction.** Submodular minimization reduced to finding nearest-to-**origin** point (i.e., a **projection**) of the **base** polytope.
- **Wolfe's Algorithm.** Finds the nearest-to-origin point of **any** polytope. Reduces to **linear optimization** over that polytope.

Our Results

- **First convergence analysis** of Wolfe's algorithm for projection on **any** polytope. *How quickly can we get within ε of optimum?* (THIS TALK)
- **Robust generalization of Fujishige Reduction.** When small enough, ε -close points can give exact submodular function minimization.

Base Polytope

Submodular
function f

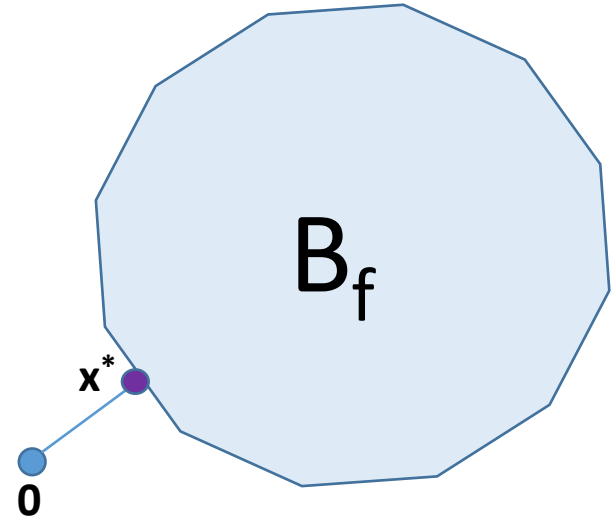


$$(x_1, \dots, x_n) : \begin{aligned} \sum_{i \in S} x_i &\leq f(S) \quad \forall S \subseteq U \\ \sum_{i \in U} x_i &= f(U) \end{aligned}$$

Linear Optimization in almost **linear** time!

Fujishige's Theorem

$$(x_1, \dots, x_n) : \begin{aligned} \sum_{i \in S} x_i &\leq f(S) \quad \forall S \subseteq U \\ \sum_{i \in U} x_i &= f(U) \end{aligned}$$

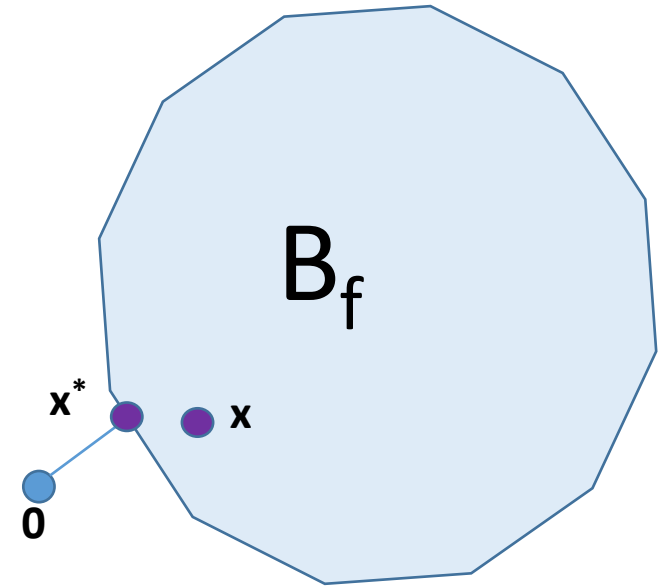


If x^* is the closest-to-origin point of B_f , then $A = \{j : x_j^* \leq 0\}$ is a minimizer of f .

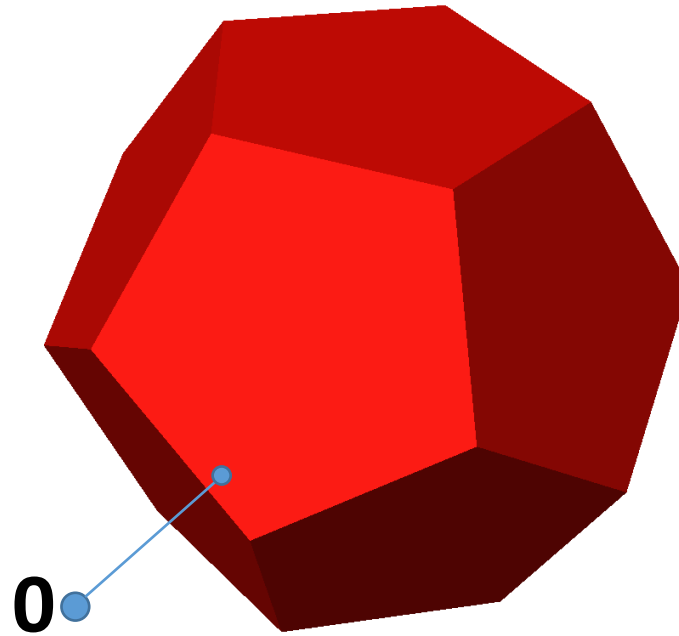
A Robust Version

Let x satisfy $\|x - x^*\| \leq \varepsilon$.

Can read out a set B from x
such that: $f(B) \leq f(A) + 2n\varepsilon$



If f is **integral**, $\varepsilon < 1/2n$ implies **exact SFM**.



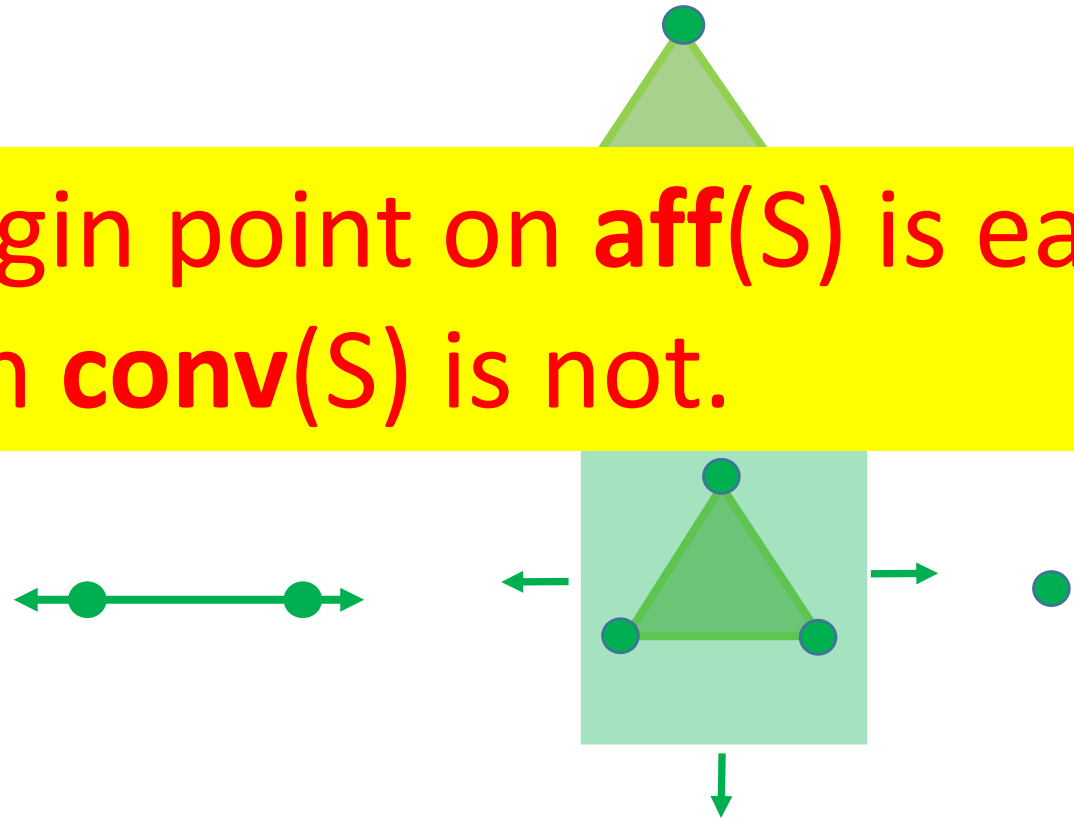
Wolfe's Algorithm: Projection onto a polytope

Geometrical preliminaries

Convex Hull: $\text{conv}(S)$

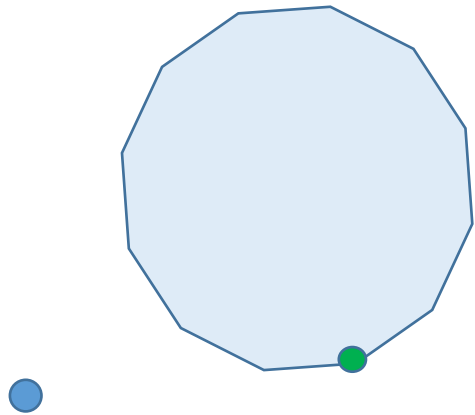
Finding closest-to-origin point on $\text{aff}(S)$ is easy
Finding it on $\text{conv}(S)$ is not.

Affine Hull: $\text{aff}(S)$

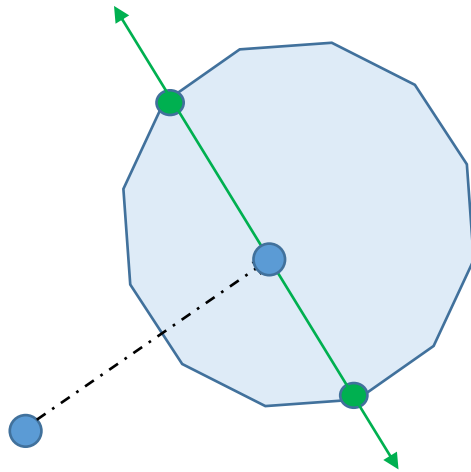


Corrals

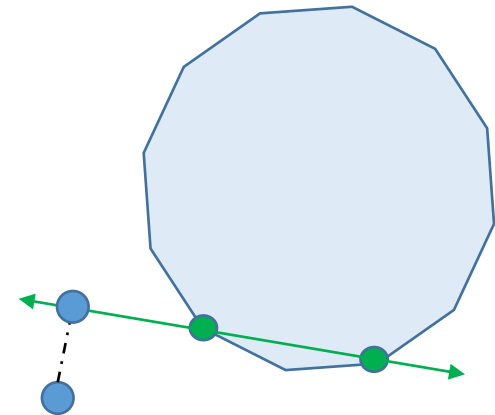
Set S of points s.t. the min-norm point in $\mathbf{aff}(S)$ lies in $\mathbf{conv}(S)$.



Trivial Corral



Corral

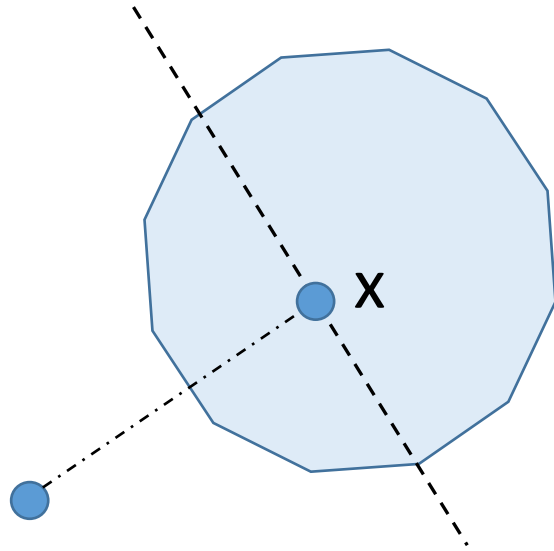


Not a Corral

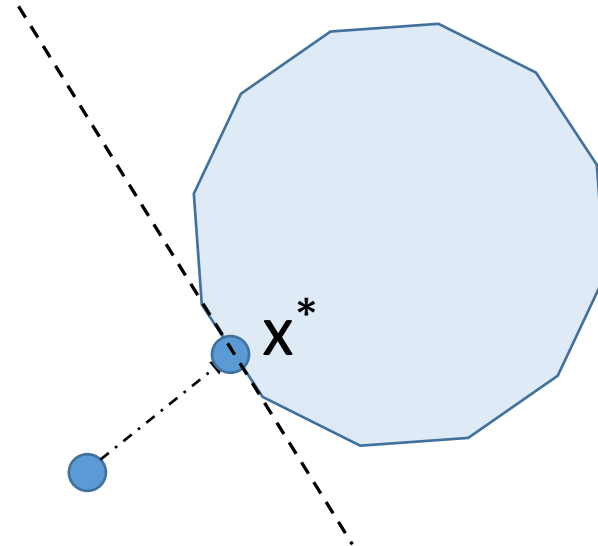
Wolfe's algorithm in a nutshell

- Moves from corral to corral till optimality.
- In the process it goes via “non-corrals”.

Checking Optimality



Not Optimal



Optimal

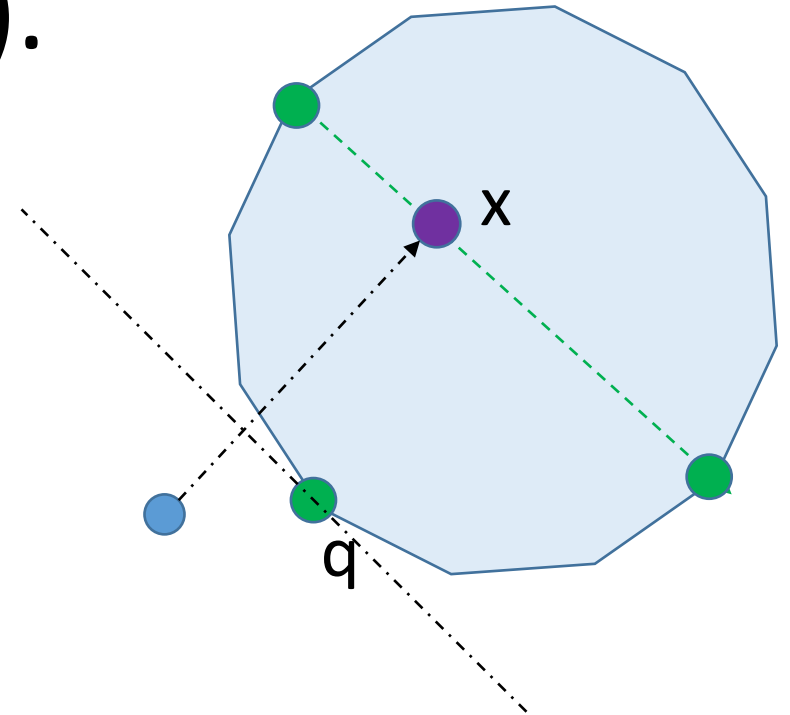
x is optimal iff $\|x\|^2 \leq x \cdot q$ for all $q \in P$

Wolfe's Algorithm: Details

- **State: (x, S) .** $S \subseteq$ vertices, x in **conv**(S)
- Start: S *arbitrary* vertex $\{q\}$, $x = q$.
- Till x is optimal, run **major** or **minor** cycle to update x and S .

If S is a corral: Major Cycle

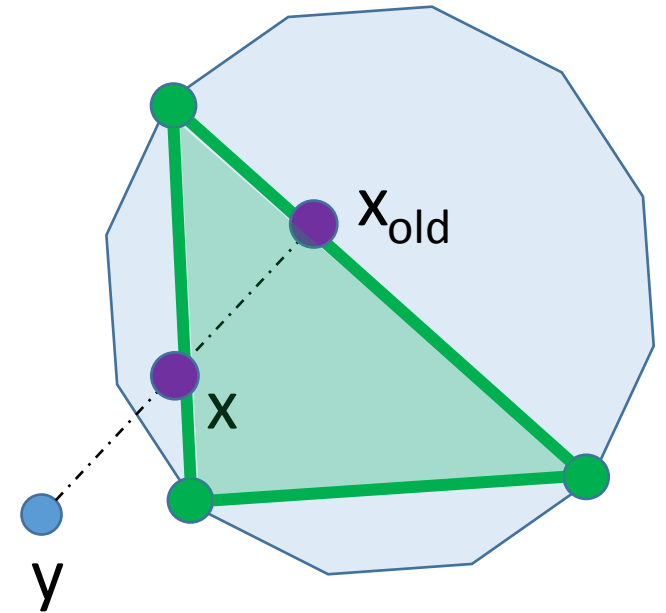
- $x = \text{min norm point in } \mathbf{aff}(S).$
- $q = \arg \min_{p \in P} (p \cdot x)$
- $S = S + q.$



Major cycle increments $|S|$.

If S is **not** a corral: Minor Cycle

- $y = \text{min-norm point in } \mathbf{aff}(S)$
- $x = \text{pt on } [y, x_{\text{old}}] \cap \mathbf{conv}(S)$
closest to y
- **Remove** *irrelevant* points from S .



Minor cycle decrements $|S|$.

Summarizing Wolfe's Algorithm

- State: (x, S) . x lies in **conv**(S).
- Each iteration is either a **major** or a **minor** cycle.
- Linear Programming and Matrix Inversion.
- **Major** cycles increment and **minor** cycles decrement $|S|$.
- In $< n$ minor cycles, we get a major cycle, and vice versa.
- Norm strictly decreases. Corrals can't repeat.
Finite termination.

Our Theorem

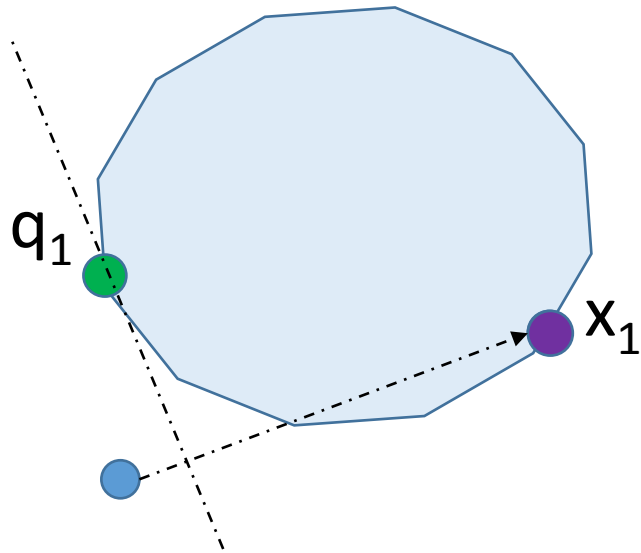
For any polytope P , for any $\varepsilon > 0$, in $O(nD^2/\varepsilon^2)$ iterations Wolfe's algorithm returns a point x such that $\|x - x^*\| \leq \varepsilon$ where D is the diameter of P .

For SFM, the base polytope has diameter $D^2 < nF^2$.

Outline of the Proof

- **Significant** norm decrease when far from optimum.
- Will argue this for two **major** cycles with **at most** one **minor** cycle in between.

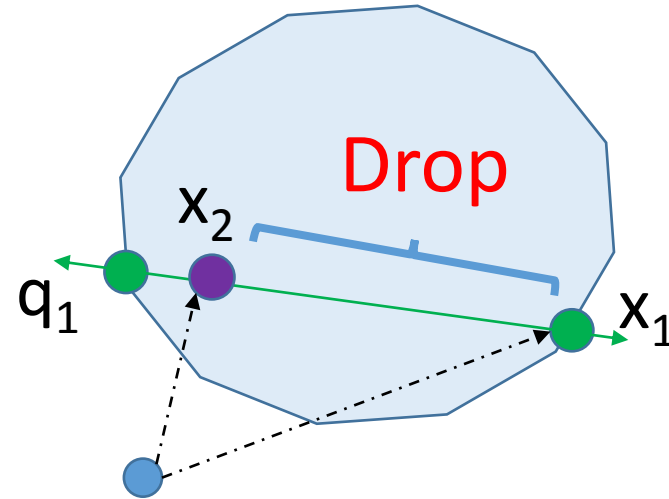
Two Major Cycles in a Row



$$q_1 = \arg \min_{p \in P} p \cdot x_1$$

If x_1 is “far away”, then

$\|x_1\|^2 - x_1 \cdot q_1$ is “large”

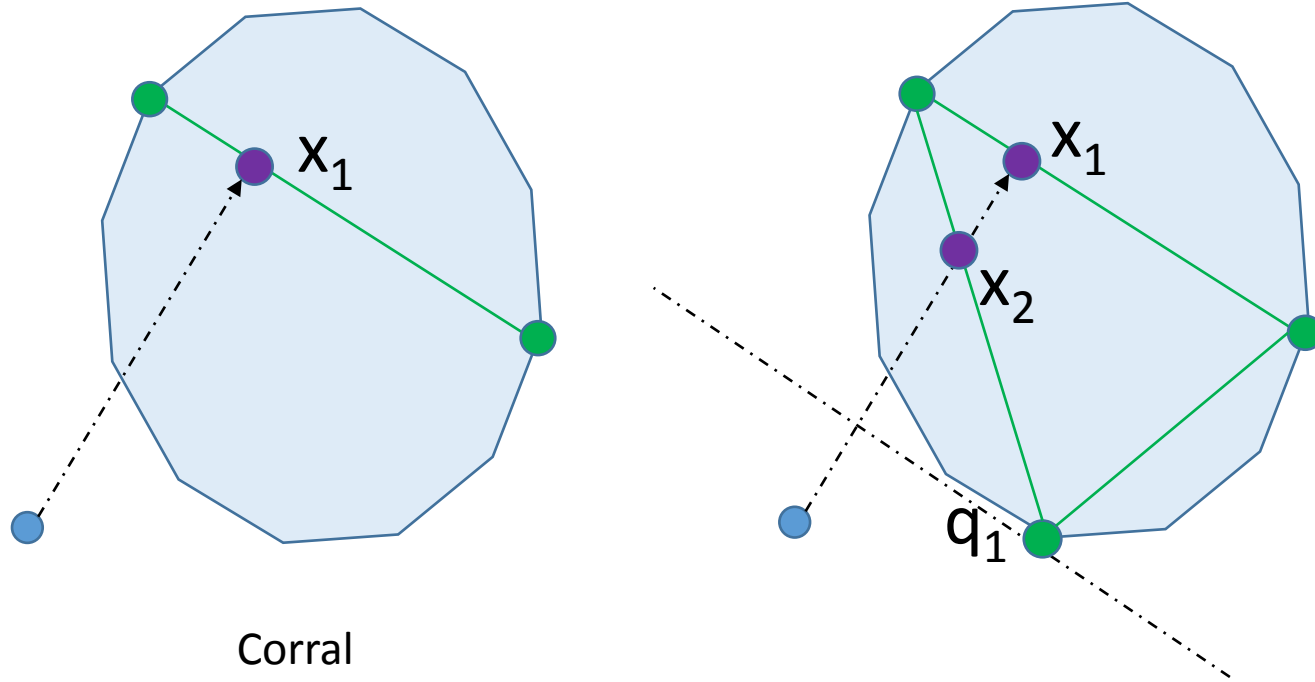


$$\text{Drop} = x_1 \cdot \frac{(x_1 - q_1)}{D}$$

$$= \frac{\|x_1\|^2 - x_1 \cdot q_1}{D}$$



Major-minor-Major

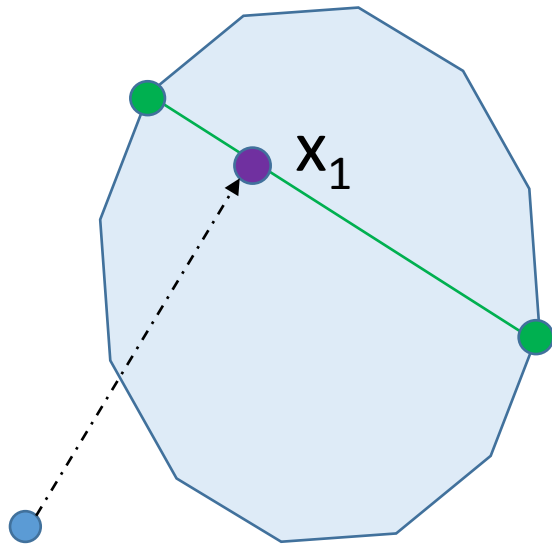


Corral

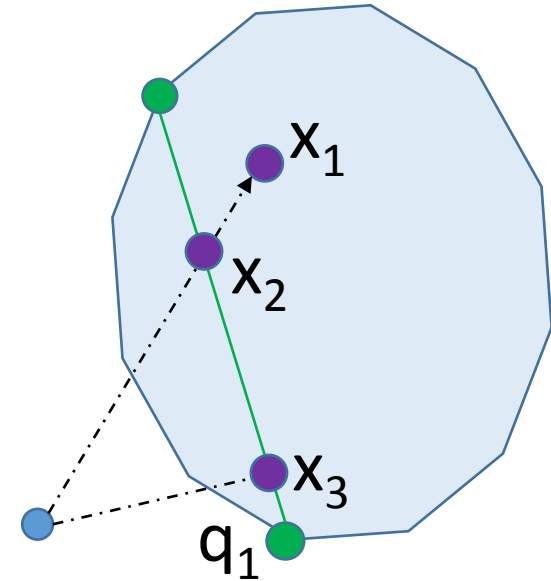
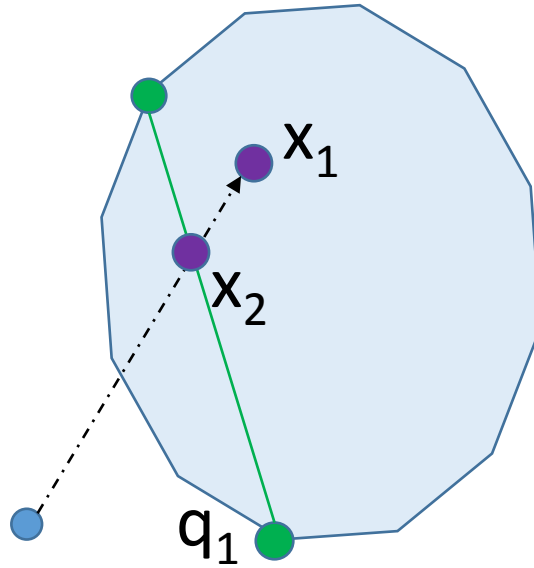
$$q_1 = \arg \min_{p \in P} p \cdot x_1$$

$\text{aff}(S + q_1)$ is the whole 2D plane. Origin is itself closest-to-origin

Major-minor-Major



Corral



Corral

Either x_2 “far away” from x_1 implying $||x_1||^2 - ||x_2||^2$ is large.

Or, x_2 “behaves like” x_1 , and $||x_2||^2 - ||x_3||^2$ is large.

Outline of the Proof

- **Significant** norm decrease when far from optimum.
- Will argue this for two **major** cycles with **at most** one **minor** cycle in between.
- Simple combinatorial fact: in $3n$ iterations there must be one such “good pair”.

Take away points.

- Analysis of Wolfe's algorithm, a practical algorithm.
- Can one remove dependence on F ?
- Can one **change** the Fujishige-Wolfe algorithm to get a better one, both in theory and in practice?

Thank you.