Some New Results on the Geometry of Random Fields

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- What if the needles were welded together? Will the mean of the total number of intersections change? No!

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A little different setup: Graff(2, 1) – the space of lines.

Theorem (Sylvester (1890))

Consider a piecewise smooth curve C of length L. Then,

$$\int_{Graff(2,1)} \#(C \cap \ell) \, d\lambda_{2,1}(\ell) \quad \propto \quad L$$

where $\lambda_{2,1}$ is the rigid motions invariant measure on Graff(2,1). Also, notice that if $C = \partial K$ for some compact $K \subset \mathbb{R}^2$ then writing D for the set of all straight lines that meet K

$$\int_{Graff(2,1)} \#(C \cap \ell) \, d\lambda_{2,1}(\ell) = 2\lambda_{2,1}(D)$$

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What about generalizations of this to higher dimensions? Crofton's formula

The setup: some geometric functionals

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- Hadwiger (1957): There exist (n + 1) geometric functionals which form a basis for all rigid motion invariant, additive, monotone set functionals. These geometric functionals are called Lipschitz-Killing curvatures (LKCs) / Minkowski functionals.
- How does one characterize LKCs? \longrightarrow A tube formula

Let A be a smooth subset of ℝⁿ, with λ_n as the n-dimensional Euclidean measure.

Let

$$\mathsf{Tube}(A,\rho) = \{x \in \mathbb{R}^n : \mathsf{dist}(x,A) \le \rho\}$$

Then Weyl's tube formula is given by:

$$\lambda_n(\mathsf{Tube}(A,\rho)) = \sum_{i=0}^{\dim(A)} \omega_{n-i} \rho^{n-i} \mathcal{L}_i(A),$$

 $(\mathcal{L}_i(\mathcal{A}))_{i=1}^{\dim(\mathcal{A})} = \text{Lipschitz-Killing curvatures}$, and ω_{n-i} is the volume of a unit ball in \mathbb{R}^{n-i} .

Lipschitz–Killing curvatures (LKCs): examples

A box B with dimensions (a, b, c): L₀(B) = 1,
 L₁(B) = (a + b + c), L₂(B) = (ab + bc + ac), L₃(B) = abc.

• A ball $B_n(r)$ of radius r in \mathbb{R}^n :

$$\mathcal{L}_j(B_n(r)) = r^j \begin{pmatrix} n \\ j \end{pmatrix} \frac{\omega_n}{\omega_{n-j}}$$

• A sphere $S^{n-1}(r)$ of radius r in \mathbb{R}^n :

$$\mathcal{L}_j(S^{n-1}(r)) = 2r^j \begin{pmatrix} n \\ j \end{pmatrix} \frac{\omega_n}{\omega_{n-j}}$$

for even values of (n - j - 1), and 0 otherwise.

• For a unit codimensional manifold, every alternate \mathcal{L}_i vanishes.

LKCs: properties

- For an *m*-dimensional subset A ⊂ ℝⁿ, L₀(A) is its Euler–Poincaré characteristic, and L_m(A) is its *m*-dimensional volume.
- \mathcal{L}_i , of say a set A, is an intrinsic, integral geometric characteristics of the set.
- LKCs for a smooth Riemannian manifold M can be defined as

$$\mathcal{L}_k(M) = \int_M \operatorname{Tr}\left(R^{\frac{n-k}{2}}\right) \operatorname{Vol}_g$$

whenever $\frac{n-k}{2}$ is an integer, and it is zero otherwise.

• Scaling: $\mathcal{L}_k(\lambda A) = \lambda^k \mathcal{L}_k(A)$.

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- This measure can be factored as ν_k^n on Gr(n, k) and Lebesgue measure on \mathbb{R}^n , and can be normalized so that $\nu_k^n(Gr(n, k)) = \begin{bmatrix} n \\ k \end{bmatrix} = \begin{pmatrix} n \\ k \end{pmatrix} \frac{\omega_n}{\omega_k \omega_{n-k}}.$

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- Let $M \subset \mathbb{R}^n$, *nice* and compact, then we have

$$\int_{\mathsf{Graff}(n,n-k)} \mathcal{L}_j(M \cap V) \, d\lambda_{n-k}^n(V) = \begin{bmatrix} k+j \\ j \end{bmatrix} \mathcal{L}_{k+j}(M).$$

A Kinematic Formula

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A kinematic formula

- Consider two piecewise smooth curves C_1 and C_2 in \mathbb{R}^2 .
- Let G_2 group of rigid motions, which is equivalent to $\mathbb{R}^2 \times O(2)$, and is equipped with the obvious product measure ν .
- Let φ(C₁∩gC₂) be the Euler-Poincaré characteristic, which, in this simple case is equivalent to the number of points of intersection of the curves C₁ and gC₂.

Theorem (Kinematic formula for curves (1912))

$$\int_{G_2} \phi(C_1 \cap gC_2) \, d\nu(g) = 4\mathcal{L}_1(C_1)\mathcal{L}_1(C_2)$$

Euclidean Kinematic Fundamental Formula (KFF)

- G_n : isometry group on \mathbb{R}^n ; isomorphic to $\mathbb{R}^n \times O(n)$.
- ν_n : a normalized measure on G_n , such that $\nu_n(g_n \in G_n : g_n x \in A) = \mathcal{H}_n(A)$, for any $x \in \mathbb{R}^n$ and $A \in \mathcal{B}(\mathbb{R}^n)$.
- Then for smooth M_1 and M_2 , we have

$$\int_{G_n} \mathcal{L}_i(M_1 \cap g_n M_2) \, d\nu_n(g_n) \\ = \sum_{j=0}^{n-i} \frac{s_{i+1}s_{n+1}}{s_{i+j+1}s_{n-j+1}} \mathcal{L}_{i+j}(M_1) \mathcal{L}_{n-j}(M_2)$$

Gaussian Kinematic Fundamental Formula

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Gaussian geometric characteristics via a Gaussian tube formula

Gaussian Minkowski functionals (GMFs): $\mathcal{M}_{i}^{\gamma_{n}}$

• Let A be *smooth* subset of \mathbb{R}^n , with $\gamma_n(dx) = (2\pi)^{-n/2} e^{-||x||^2/2} dx$, then the GMFs can be defined as

$$\gamma_n(\mathsf{Tube}(A, \rho)) = \sum_{j=0}^{\infty} \frac{\rho^j}{j!} \mathcal{M}_j^{\gamma_n}(A),$$

where Tube(A, ρ) is a tube of radius ρ around A.

• One can also define the GMFs as integral of some Hermite polynomials with respect to the measures induced by \mathcal{L}_i 's, called the generalized curvature measures.

A Gaussian Kinematic Formula (GKF)

- Let *M* be an *m*-dimensional smooth manifold.
- Let y_1, \ldots, y_k be i.i.d. Gaussian random fields on M.
- Let $F : \mathbb{R}^k \to \mathbb{R}$ be twice differentiable, and define $f = F(y_1, y_2, \dots, y_k)$. Then [Taylor (2006)]

$$\mathbb{E}\left(\mathcal{L}_0\left(M\cap f^{-1}[u,\infty)\right)\right) = \sum_{j=0}^n c_j \,\mathcal{L}_j^{\gamma}(M) \,\mathcal{M}_j^{\gamma_k}\left(F^{-1}[u,\infty)\right)$$

where $\mathcal{L}_{j}^{y}(\cdot)$ are the LKCs defined w.r.t. the induced metric given by

$$g^{y}(X,Y) = \mathbb{E}\left(Xy_{1} \cdot Yy_{1}\right)$$

The metric induced by any y_i is the same due to i.i.d. nature of y_i 's

A sneak peek into the proof of GKF

Define

$$\mu_k = \#\{x \in M : f(x) \ge u, \ \nabla f(x) = 0, \ \operatorname{index}\left(\nabla^2 f(x)\right) = k\}$$

Then,

$$\mathbb{E}\left(\mathcal{L}_0\left(M\cap f^{-1}[u,\infty)\right)\right)=\mathbb{E}\left(\sum_{k=0}^m(-1)^k\mu_k\right)$$

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$$= \int_{M}\mathbb{E}\left\{\operatorname{Tr}\left(-\nabla^{2}f(x)\right)^{m}\mathbf{1}_{\left(f(x)\geq u\right)}\middle|\,\nabla f(x)=0\right\}p_{\nabla f(x)}(0)\,dx$$
$$= \int_{M}\mathbb{E}\left[\mathbf{1}_{\left(f(x)\geq u\right)}\mathbb{E}\left\{\operatorname{Tr}\left(-\nabla^{2}f(x)\right)^{m}\middle|\,f(x),\nabla f(x)=0\right\}\right]$$
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- In general, if W is a (1,1) Gaussian form with mean and covariance are μ and C respectively, then

$$\mathbb{E}[W^k] = \sum_{j=0}^{\lfloor \frac{k}{2} \rfloor} \frac{k!}{(k-2j)!j!2^j} \mu^{k-2j} C^j.$$

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- The conditional covariance $= -(I^2 + 2R) ||\nabla F||^2$, where R is the Riemannian curvature tensor with respect to the induced metric.
- Then need to go from conditioning on (y, ∇y) to conditioning on (f, ∇f), which involves another Gaussian computation (majorly technical).

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- In this case, the *majorly technical* step is not needed.
- Then notice that we are left with integrals of trace of polynomials of *R*, which can readily be identified with LKCs, and the rest matches with the GMFs in each term of the polynomial.

Testing the Limits of Gaussian Kinematic Fundamental Formula

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- We take a simple case of m = k = 2. In particular, we take $M = S^2$, with g as the usual spherical metric.
- We assume y₁ and y₂ are isotropic independent Gaussian fields, but they are not identically distributed.
- We still have:

$$\mathbb{E}\left(\mathcal{L}_{0}\left(M \cap f^{-1}[u,\infty)\right)\right)$$

=
$$\int_{\mathbb{S}^{2}} \mathbb{E}\left[1_{(f(x)\geq u)}\mathbb{E}\left\{\left.\operatorname{Tr}\left(-\nabla^{2}f(x)\right)^{2}\right|f(x),\nabla f(x)=0\right\}\right]$$

$$\times p_{\nabla f(x)}(0) \ dx$$

 $\{ \nabla^2 f \, | \, y, \nabla y \}$ is still a Gaussian (1,1) form, with mean

$$y^* \nabla^2 F(y) - \left(\sum_{k=1}^2 \lambda_{2,k} y_k \frac{\partial F(y)}{\partial y_k}\right) I_2,$$

and covariance

$$-\sum_{k=1}^{2}\lambda_{2,k}^{2}\left(\frac{\partial F(y)}{\partial y_{k}}\right)^{2}I_{2}^{2}-2\sum_{k=1}^{2}\lambda_{2,k}\left(\frac{\partial F(y)}{\partial y_{k}}\right)^{2}R$$

where R is the Riemannian curvature tensor w.r.t. the spherical metric.

A partial result

$$\mathbb{E}\left(\mathcal{L}_{0}(M \cap f^{-1}[u,\infty))\right)$$

$$= \left(\sum_{\nu=1}^{k} \frac{1}{\lambda_{2,\nu}} \mathbb{E}\left[1_{(f>u)}\left(\frac{\partial F(y)}{\partial y_{\nu}}\right)^{2}\right]\right) p_{\nabla f}(0) 4\pi \mathcal{L}_{0}(M)$$

$$+ \frac{1}{2}\sum_{i,j=1}^{2} \mathbb{E}\left[1_{(f>0)}\left(\mu^{2}(y,\nabla y)(E_{i},E_{j},E_{i},E_{j})\right) - S_{\nabla F}^{T}(E_{i},E_{i})\Sigma_{M,(y,\nabla y)}\Sigma_{(y,\nabla y)}^{-1}\Sigma_{(y,\nabla y),M}S_{\nabla F}(E_{j},E_{j})$$

$$+ S_{\nabla F}^{T}(E_{i},E_{j})\Sigma_{M,(y,\nabla y)}\Sigma_{(y,\nabla y)}^{-1}\Sigma_{(y,\nabla y),M}S_{\nabla F}(E_{j},E_{i})\right)\right] p_{\nabla f}(0)\mathcal{L}_{2}(M)$$

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$$+ \frac{1}{2} \sum_{i,j=1}^{2} \mathbb{E} \left[\mathbb{1}_{(f>0)} \left(\mu^{2}(y, \nabla y)(E_{i}, E_{j}, E_{i}, E_{j}) \right) - S_{\nabla F}^{T}(E_{i}, E_{i}) \Sigma_{M,(y,\nabla y)} \Sigma_{(y,\nabla y)}^{-1} \Sigma_{(y,\nabla y),M} S_{\nabla F}(E_{j}, E_{j}) \right)$$

$$+ S_{\nabla F}^{T}(E_{i}, E_{j}) \Sigma_{M,(y,\nabla y)} \Sigma_{(y,\nabla y)}^{-1} \Sigma_{(y,\nabla y),M} S_{\nabla F}(E_{j}, E_{i}) \right) p_{\nabla f}(0) \mathcal{L}_{2}(M)$$

Good news: we still have a breakup of the two spaces (by possibly a bit of cheating)

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$$+ \frac{1}{2} \sum_{i,j=1}^{2} \mathbb{E} \left[\mathbb{1}_{(f>0)} \left(\mu^{2}(y,\nabla y)(E_{i},E_{j},E_{i},E_{j}) - S_{\nabla F}^{T}(E_{i},E_{i}) \Sigma_{M,(y,\nabla y)} \Sigma_{(y,\nabla y)}^{-1} \Sigma_{(y,\nabla y),M} S_{\nabla F}(E_{j},E_{j}) \right)$$

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Good news: we still have a breakup of the two spaces (by possibly a bit of cheating) Bad news: we are yet to figure out meaning of the coefficients of the LKCs.

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Thank you!

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