

On the existence of paths between points in high level excursion sets of Gaussian random fields

Robert Adler, Elina Moldavskaya and Gennady Samorodnitsky

January 2013

▲ロト ▲帰 ト ▲ ヨ ト ▲ ヨ ト ・ ヨ ・ の Q ()



Let $\mathbf{X} = (X(\mathbf{t}), \mathbf{t} \in \mathbb{R}^d)$ be a real-valued sample continuous Gaussian random field.

Given a level u, the excursion set of **X** above the level u is the random set

$$A_u = \left\{ \mathbf{t} \in \mathbb{R}^d : X(\mathbf{t}) > u \right\}.$$

Much is know about the structure of the excursion set when the field is smooth, and u is large (Adler and Taylor (2007), Azaïs and Wschebor (2009)).



Consider a large level u.

Question: given that two points in \mathbb{R}^d belong to the excursion set, what is the probability that they belong to the same path connected component of the excursion set?

Let $\mathbf{a}, \mathbf{b} \in \mathbb{R}^d$, $\mathbf{a} \neq \mathbf{b}$. A path in \mathbb{R}^d connecting \mathbf{a} and \mathbf{b} is a continuous map $\xi : [0, 1] \to \mathbb{R}^d$ with $\xi(0) = \mathbf{a}, \xi(1) = \mathbf{b}$.

Denote the collection of all such paths by $\mathcal{P}(\mathbf{a}, \mathbf{b})$. Estimate

$$P\left(\exists \xi \in \mathcal{P}(\mathbf{a}, \mathbf{b}) : X(\xi(v)) > u, \ 0 \le v \le 1 \ \middle| \ X(\mathbf{a}) > u, \ X(\mathbf{b}) > u\right)$$



The non-trivial part of the problem: estimate the probability

$$\Psi_{\mathbf{a},\mathbf{b}}(u) := P\left(\exists \ \xi \in \mathcal{P}(\mathbf{a},\mathbf{b}) : \ X(\xi(v)) > u, \ 0 \le v \le 1\right).$$

If the random field is stationary, we may assume that $\bm{b}=\bm{0},$ and use the notation $\Psi_{\bm{a}}.$

If the domain of a random field is restricted to $T \subset \mathbb{R}^d$, and **a**, **b** are in *T*, we consider

 $\Psi_{\mathbf{a},\mathbf{b}}(u) = P\left(\exists \xi \in \mathcal{P}(\mathbf{a},\mathbf{b}): \, \xi(v) \in \mathcal{T} \text{ and } X(\xi(v)) > u, \, \, 0 \leq v \leq 1\right).$

(日) (日) (日) (日) (日) (日) (日) (日)

Introduction	Large deviations	Fixed path	1 dim	Long int

Large deviations setup

Let A be the open set

$$\begin{split} A &\equiv A_{\mathbf{a},\mathbf{b}} := \Big\{ \omega \in C_0(\mathbb{R}^d) : \ \exists \, \xi \in \mathcal{P}(\mathbf{a},\mathbf{b}), \ \omega(\xi(v)) > 1, \ 0 \le v \le 1 \Big\}, \\ C_0(\mathbb{R}^d) &= \Big\{ \omega = (\omega(\mathbf{t}), \ \mathbf{t} \in \mathbb{R}^d) \in C(\mathbb{R}^d) : \ \lim_{\|\mathbf{t}\| \to \infty} \omega(\mathbf{t}) / \|\mathbf{t}\| = 0 \Big\}. \end{split}$$
We can write for $u > 0$

$$\Psi_{\mathbf{a},\mathbf{b}}(u) = P(u^{-1}\mathbf{X} \in A),$$

and use the large deviations results for Gaussian measures of Deutschel and Stroock (1989).

The reproducing kernel Hilbert space (RKHS) \mathcal{H} of the random field **X**, is a subspace of $C(\mathbb{R}^d)$.

Consider the space of finite linear combinations $\sum_{j=1}^{k} a_j X(\mathbf{t}_j)$ $a_j \in \mathbb{R}, \mathbf{t}_j \in \mathbb{R}^d$ for j = 1, ..., k, k = 1, 2, ...

Its closure \mathcal{L} in the mean square norm is identified with \mathcal{H} via the injection $\mathcal{L} \to C(\mathbb{R}^d)$ given by

$$H \to w_H = \left(E(X(\mathbf{t})H), \ \mathbf{t} \in \mathbb{R}^d \right)$$

and the resulting norm

$$\|w_H\|_{\mathcal{H}}^2 = E(H^2).$$

Introduction	Large deviations	Fixed path	1 dim	Long int

Let **X** be stationary with spectral measure $F_{\mathbf{X}}$.

The RKHS \mathcal{H} can be identified with the subspace of $L^2(F_{\mathbf{X}})$ of functions with even real parts and odd imaginary parts, via the injection $L^2(F_{\mathbf{X}}) \to C_0(\mathbb{R}^d)$ given by

$$h o S(h) = \left(\int_{\mathbb{R}^d} e^{i(\mathbf{t},\mathbf{x})} \, ar{h}(\mathbf{x}) \, F_{\mathbf{X}}(d\mathbf{x}), \; \mathbf{t} \in \mathbb{R}^d
ight) \, ,$$

with the resulting norm

$$\|S(h)\|_{\mathcal{H}}^2 = \|h\|_{L^2(F_{\mathbf{X}})}^2 = \int_{\mathbb{R}^d} \|h(x)\|^2 F_{\mathbf{X}}(d\mathbf{x}).$$

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Theorem 1 Let $X = (X(t), t \in \mathbb{R}^d)$ be a continuous stationary Gaussian random field, with covariance function satisfying

 $\limsup_{\|\mathbf{t}\|\to\infty} R_{\mathbf{X}}(\mathbf{t}) \leq 0.$

Then

$$\lim_{u\to\infty}\frac{1}{u^2}\log\Psi_{\mathbf{a}}(u)=-\frac{1}{2}\mathfrak{C}_{\mathbf{X}}(\mathbf{a}),$$

where

$$\begin{split} \mathfrak{C}_{\mathbf{X}}(\mathbf{a}) &:= \inf \left\{ \int_{\mathbb{R}^d} \|h(\mathbf{x})\|^2 \, F_{\mathbf{X}}(d\mathbf{x}) : \text{ for some } \xi \in \mathfrak{P}(\mathbf{0}, \mathbf{a}) \\ & \int_{\mathbb{R}^d} e^{i(\xi(v), \mathbf{x})} \, \bar{h}(\mathbf{x}) \, F_{\mathbf{X}}(d\mathbf{x}) > 1, \, 0 \leq v \leq 1 \right\}. \end{split}$$



The constraints in the optimization problem in Theorem 1 are not convex. However, for a fixed path, the constraints are convex, and one can use the convex Lagrange duality.

Theorem 2 For a continuous stationary Gaussian random field X,

$$\mathcal{C}_{\mathbf{X}}(\mathbf{a}) = \left[\sup_{\xi \in \mathcal{P}(\mathbf{0},\mathbf{a})} \min_{\mu \in M_1^+([0,1])} \int_0^1 \int_0^1 R_{\mathbf{X}}(\xi(u) - \xi(v)) \mu(du) \mu(dv)\right]^{-1}$$

Here $M_1^+([0,1])$ is the space of all probability measures on [0,1].

An optimal path is a path of maximal R_X capacity.



Assume a path $\xi \in \mathcal{P}(\mathbf{0}, \mathbf{a})$ is fixed. Then the minimization problem

$$\min_{\mu \in M_1^+([0,1])} \int_0^1 \int_0^1 R_{\mathbf{X}}(\xi(u),\xi(v)) \,\mu(du) \,\mu(dv)$$

is the problem of finding a probability measures μ of *minimal* energy, or capacitory measures.

The set $W_{\xi} \subseteq M_1^+([0,1])$ over which the minimum is achieved is a weakly compact convex subset of $M_1^+([0,1])$.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

(日) (日) (日) (日) (日) (日) (日) (日)

If the feasible set for the primary problem is non-empty then, for every $\varepsilon > {\rm 0},$

$$P\left(\sup_{0\leq v\leq 1}\left|\frac{1}{u}X(\xi(v))-x_{\xi}(v)\right|\geq \varepsilon \left|X(\xi(v))>u,\,0\leq v\leq 1\right)\to 0$$

as $u \to \infty$. Here H_{ξ} is primary optimal, and

$$x_{\xi}(v) = E[X(\xi(v))H_{\xi}], \ 0 \leq v \leq 1.$$

Furthermore, there is a characterization of the optimal $H_{\xi} \in \mathcal{L}$ and the optimal $\mu \in \mathcal{W}_{\xi}$.

Theorem 3 (i) For every $\mu \in \mathcal{W}_{\xi}$ we have

$$H_{\xi} = \mathfrak{C}_{\mathbf{X}}(\mathbf{a}, \mathbf{b}; \xi) \int_0^1 X(\xi(v)) \, \mu(dv)$$

with probability 1.

(ii) A probability measure $\mu \in M_1^+([0,1])$ is a measure of minimal energy if and only if

$$\min_{0 \le v \le 1} \int_0^1 R_{\mathbf{X}}(\xi(u), \xi(v)) \, \mu(du)$$

= $\int_0^1 \int_0^1 R_{\mathbf{X}}(\xi(u_1), \xi(u_2)) \, \mu(du_1) \, \mu(du_2) > 0$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ○臣 - の々ぐ

Introduction	Large deviations	Fixed path	1 dim	Long int

Remarks

• By Theorem 3, the function

$$v\mapsto \int_0^1 R_{\mathbf{X}}ig(\xi(u),\xi(v)ig)\,\mu(du),\,0\leq v\leq 1,$$

is constant on the support of any measure $\mu \in W_{\xi}$. This seems to indicate that the support of any measure of minimal energy may not be 'large'. However, this intuition holds only in some cases.

• If the random field is stationary, and the spectral measure is of the full support, then the image of any measure $\mu \in W_{\xi}$ on the path ξ is unique.

Introduction	Large deviations	Fixed path	1 dim	Long int

One-dimensional case

In this case there is, essentially, a single path between two points.

Let $\mathbf{X} = (X(t), t \in \mathbb{R})$ be a stationary continuous Gaussian process. We are interested in understanding how the probability

$$\Psi_a(u) = P\Big(X(t) > u, \, 0 \le t \le a\Big)$$

changes with a > 0, and what happens with the optimal probability measures μ_a and limiting shapes x_a .

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

For some processes (in particular, those with a finite second spectral moment), on short intervals we get an easy descrption.

Proposition 1 Suppose that for some a > 0

 $R_{\mathbf{X}}(t) + R_{\mathbf{X}}(a-t) \geq R_{\mathbf{X}}(0) + R_{\mathbf{X}}(a) > 0 \ \text{ for all } 0 \leq t \leq a.$

Then a measure in \mathcal{W}_a is given by

$$\mu = \frac{1}{2}\delta_0 + \frac{1}{2}\delta_1.$$

Furthermore,

$$\begin{aligned} \mathcal{C}_{\mathbf{X}}(a) &= \frac{2}{R_{\mathbf{X}}(0) + R_{\mathbf{X}}(a)},\\ x_{a}(t) &= \frac{R_{\mathbf{X}}(t) + R_{\mathbf{X}}(a - t)}{R_{\mathbf{X}}(0) + R_{\mathbf{X}}(a)}, \qquad 0 \leq t \leq a\,. \end{aligned}$$

In any case, the measure $\mu = (\delta_0 + \delta_1)/2$ does NOT remain optimal for longer intervals.

 $\label{eq:consider} \begin{array}{l} \textbf{Example 1} & \textbf{Consider the centered stationary Gaussian process} \\ \text{with the Gaussian covariance function} \end{array}$

$$R(t)=e^{-t^2/2},\ t\in\mathbb{R}.$$

Since the spectral measure has a Gaussian spectral density which is of full support in \mathbb{R} , for every a > 0 there is a unique (symmetric) measure of minimal energy. Furthermore, the second spectral moment is finite, so that, for a > 0 sufficiently small this process satisfies the conditions of Proposition 1.



The measure $\mu = (\delta_0 + \delta_1)/2$ remains optimal for $a \le a_1 \approx 2.2079$.



In the next regime the optimal measure acquires a point in the middle of the interval. This continues for $a_1 < a \le a_2 \approx 3.9283$.





a=3.93



_t

A 10

ヨト ヨ

・ロト ・ 理 ト ・ ヨ ト ・ ヨ ト ・ ヨ

In the next regime the middle point of the optimal measure splits in two and starts moving away from the middle. This continues for $a_2 < a \le a_3 \approx 5.4508$.





Example 2 Consider an Ornstein-Uhlenbeck process, i.e. a centered stationary Gaussian process with the covariance function

$$R(t)=e^{-|t|},\ t\in\mathbb{R}$$
 .

For this process the spectral measure has a Cauchy spectral density, which has a full support in \mathbb{R} . Therefore, for every a > 0 there is a unique (symmetric) measure of minimal energy.

In this case even the first spectral moment is infinite. Proposition 1 does not apply here.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Introduction	Large deviations	Fixed path	1 dim	Long int

The optimal probability measure is

$$\mu = \frac{1}{a+2}\delta_0 + \frac{1}{a+2}\delta_1 + \frac{a}{a+2}\lambda,$$

where λ is Lebesgue measure on (0, 1).

There are no phase transitions. We have

$$C_{\mathbf{X}}(a) = (a+2)/2$$
 for all $a > 0$

and the limiting shape x_a is identically equal to 1 on [0, a].

Long intervals

As the length *a* of the interval increases, a difference between short and long memory processes arises. In the short memory case, the uniform measure is asymptotically optimal.

Theorem 4 Assume that R_X is positive, and satisfies

$$\int_0^\infty R(t)\,dt<\infty\,.$$

Then, with λ denoting the uniform probability measure on [0, 1],

$$\lim_{a \to \infty} \frac{1}{a} C_{\mathbf{X}}(a) = \left(\lim_{a \to \infty} a \int_0^1 \int_0^1 R_{\mathbf{X}}(a(u-v)) \lambda(du) \lambda(dv) \right)^{-1}$$
$$= \frac{1}{2 \int_0^\infty R(t) dt}.$$

In the long memory case the uniform measure is no longer asymptotically optimal. We will assume that the covariance function of the process is regularly varying at infinity:

$$R_{\mathbf{X}}(t) = rac{L(t)}{|t|^eta}, \qquad 0 < eta < 1,$$

where L is slowly varying at infinity.

Consider the minimization problem with respect to Riesz kernel,

$$\min_{\mu \in \mathcal{M}_1^+([0,1])} \int_0^1 \int_0^1 \frac{\mu(du)\mu(dv)}{|u-v|^\beta} \qquad 0 < \beta < 1.$$

An optimal measure μ_β exists, but it is different from the uniform measure.



Theorem 5 Assume that $R_{\mathbf{X}}$ is positive and regularly varying. Then for any $\mu_{\beta} \in W_{\beta}$, the set of optimal measures for the Riesz kernel,

$$\lim_{a\to\infty} R_{\mathbf{X}}(a) \mathcal{C}_{\mathbf{X}}(\mathbf{a}) = \left(\int_0^1 \int_0^1 \frac{\mu_\beta(du)\mu_\beta(dv)}{|u-v|^\beta}\right)^{-1}$$

.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

In particular, $C_{\mathbf{X}}(\mathbf{a})$ is regularly varying with exponent β .