

9.D Computational Rules for Determinants

The determinant of a $n \times n$ matrix $(a_{ij}) \in M_n(K)$ is also denoted by

$$\begin{vmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \cdots & a_{nn} \end{vmatrix}$$

Therefore by definition:

$$\begin{aligned} \begin{vmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \cdots & a_{nn} \end{vmatrix} &= \sum_{\sigma \in S_n} (\text{Sign } \sigma) a_{1,\sigma_1} \cdots a_{n,\sigma_n} \\ &= \sum_{\sigma \in S_n} (\text{Sign } \sigma) a_{\sigma_1,1} \cdots a_{\sigma_n,n} \end{aligned}$$

For $n = 1, 2, 3$, we note explicitly:

$$|a_{11}| = a_{11}, \quad \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} \\ + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} \\ - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33}$$

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The last formula can be remembered by the following scheme which is also known as Sarrus-Rule:

$$\begin{array}{ccccc} + & + & + & - & - \\ a_{11} & a_{12} & a_{13} & a_{11} & a_{12} \\ a_{21} & a_{22} & a_{23} & a_{21} & a_{22} \\ a_{31} & a_{32} & a_{33} & a_{31} & a_{32} \end{array}$$

We repeat 9.C.7:

9.D.1 Theorem Let $A \in M_I(K)$.

Then: $\text{Det } A = \text{Det } A^t$.

The determinant function

$$\text{Det}: M_I(K) \longrightarrow K$$

is an alternating multilinear function of the columns of the matrix.

Because of 9.D.1 it is also of the rows of the matrix. In particular, one can completely determine the behaviour of the determinant of a matrix by applying elementary operations.

$$\alpha' = \alpha(R_i \mapsto R_i + aR_j \mid i, j \in I, a \in K)$$

For a square matrix $\alpha \in M_n(K)$:

(1) Let α' be the matrix obtained from the matrix α by adding a-th multiple of ~~a~~ ^{one} ~~column~~ ^(resp. row) to another column. Then $\text{Det } \alpha' = \text{Det } \alpha$.

(2) Let α' be the matrix obtained from the matrix α by multiplying a column by a non-zero scalar $a \in K$.

$$\text{Then } \text{Det } \alpha' = \text{Det } \alpha \cdot a$$

(3) Let α_σ be the matrix obtained from the matrix α by permuting the columns of α according to the permutation $\sigma \in S(I)$. Then

$$\text{Det } \alpha_\sigma = (\text{Sign } \sigma) \text{Det } \alpha$$

Proof (1) Let $x_j, j \in I$ be columns of α and $\alpha' = (x_1, \dots, x_j, \dots, x_i + ax_j, \dots, x_n)$

$$\begin{aligned} \text{Then } \text{Det } \alpha' &= \Delta_e(x_1, \dots, x_j, \dots, x_i + ax_j, \dots, x_n) \\ &= \Delta_e(x_1, \dots, x_j, \dots, x_i, \dots, x_n) + a \underbrace{\Delta_e(\dots, x_j, \dots, x_j, \dots)}_{=0} \\ &= \text{Det } \alpha. \end{aligned}$$

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All other rules follow similarly by using properties of alternating multilinear maps.

A $n \times n$ arbitrary matrix $A \in M_n(\mathbb{K})$ can be transformed to an upper (resp. lower) triangular matrix by using elementary operations see for example 8. B.4. Since ^{under} each of elementary operations change in the determinant exactly described, for the explicit calculation of the determinant, it is important to know the determinant of triangular matrices. This is very simple to calculate:

9.D.2 Theorem Let $A = (a_{ij}) \in$

$M_n(K)$ be an upper triangular matrix,

i.e. $a_{ij} = 0$ for $n \geq i > j \geq 1$. Then:

$$\text{Det } A = \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ 0 & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a_{nn} \end{vmatrix}$$

$$= a_{11} a_{22} \dots a_{nn}$$

Proof ~~It is~~ $\text{Det } A = \sum_{\sigma \in S_n} (\text{Sign } \sigma) a_{1, \sigma(1)} \dots a_{n, \sigma(n)}$

For every $\sigma \in S_n$, $\sigma \neq \text{id}$, there exists $i_0 \in \{1, \dots, n\}$ with $i_0 > \sigma(i_0)$ and so the corresponding summand is zero.

It remains $\text{Det } A = a_{11} \dots a_{nn}$.

An analogous to 9.D.2 assertion, naturally also holds for lower triangular matrix.

9.D.3 Example

$R_3 \mapsto R_3 + R_2$

$C_3 \mapsto C_3 - 2C_1$
 $\begin{vmatrix} 1 & 0 & 2 \\ 2 & -1 & 3 \\ 4 & 1 & 8 \end{vmatrix} = \begin{vmatrix} 1 & 0 & 2 \\ 0 & -1 & -1 \\ 0 & 1 & 0 \end{vmatrix}$

$= \begin{vmatrix} 1 & 0 & 2 \\ 0 & -1 & -1 \\ 0 & 0 & -1 \end{vmatrix} = 1 \cdot (-1) \cdot (-1) = 1.$

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A generalisation of 9.D.2 is the following theorem:

9.D.4 Theorem Let $\alpha \in M_r(K)$, $\beta \in M_{r,s}(K)$ and $\tau \in M_s(K)$ be matrices over the field K . Then the square $(r+s) \times (r+s)$ -block matrix

$$\begin{pmatrix} \alpha & \beta \\ 0 & \tau \end{pmatrix} \in M_{r+s}(K)$$

has the determinant $\text{Det } \alpha \cdot \text{Det } \tau$.

Proof By elementary operations we can transform the matrix α resp. τ into upper triangular matrices:

$$\alpha' = \begin{pmatrix} a'_{11} & a'_{12} & \dots & a'_{1r} \\ 0 & a'_{22} & \dots & a'_{2r} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & a'_{rr} \end{pmatrix} \text{ resp. } \tau' = \begin{pmatrix} c'_{11} & c'_{12} & \dots & c'_{1s} \\ 0 & c'_{22} & \dots & c'_{2s} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & c'_{ss} \end{pmatrix}$$

Then $\text{Det } \alpha = a \text{ Det } \alpha' = a a'_{11} \dots a'_{rr}$
and $\text{Det } \tau = c \text{ Det } \tau' = c c'_{11} \dots c'_{ss}$,
where the factors a (resp. c) are the modifications (changes) in the determinants described by the operations.

Now, we conduct the analogous operations on the matrix:

$\begin{pmatrix} \alpha & \beta \\ 0 & \tau \end{pmatrix}$ and obtain an upper triangular matrix $\begin{pmatrix} \alpha' & \beta' \\ 0 & \tau' \end{pmatrix}$. It follows

$$\text{Det} \begin{pmatrix} \alpha & \beta \\ 0 & \tau \end{pmatrix} = ac \text{Det} \begin{pmatrix} \alpha' & \beta' \\ 0 & \tau' \end{pmatrix} =$$

$$ac a'_{11} \cdots a'_{rr} c'_{11} \cdots c'_{ss} = \text{Det } \alpha \cdot \text{Det } \tau.$$

Finally, we prove the fundamental product-formula:

9.D.5 Product Formula For square matrices $\alpha, \beta \in M_I(K)$

$$\text{Det}(\alpha\beta) = (\text{Det } \alpha)(\text{Det } \beta)$$

Proof Let $x_j, j \in I$, be the columns of β , then $\alpha x_j, j \in I$, are the columns of $\alpha\beta$. The map

$$f: (K^I)^I \rightarrow K, \beta \mapsto \text{Det}(\alpha\beta) = \Delta_e \left(\left(\alpha x_j \right)_{j \in I} \right)$$

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is an alternating multilinear map
i.e. a determinant function on K^I .

From 9.C.4 it follows that

$$\begin{aligned} \text{Det}(\alpha \mathcal{L}) &= f(\mathcal{L}) = f\left(\left(x_j\right)_{j \in I}\right) = \\ & \Delta_{\underline{e}}\left(\left(x_j\right)_{j \in I}\right) \cdot f\left(\left(e_j\right)_{j \in I}\right) \\ &= \Delta_{\underline{e}}\left(\left(x_j\right)_{j \in I}\right) \cdot f\left(\underline{e}_I\right) \\ &= (\text{Det } \mathcal{L}) \cdot (\text{Det } \alpha) \quad \square \end{aligned}$$

If $\alpha \in M_I(K)$ is invertible, i.e.

if $\alpha \in GL_I(K)$, then $\alpha \cdot \alpha^{-1} = \underline{e}_I$

and hence $1 = \text{Det } \underline{e}_I = \text{Det}(\alpha \alpha^{-1})$

$= (\text{Det } \alpha) (\text{Det } \alpha^{-1})$. Once again (as
from 9.C.10 and also from 9.D.2)

it follows that the determinant
of an invertible matrix is non-zero.

Moreover, $\text{Det } \alpha^{-1} = (\text{Det } \alpha)^{-1}$

The determinant map

$$\text{Det}: GL_I(K) \longrightarrow K^*$$

is a group homomorphism (by 9.D.5),

from the general linear group $GL_{\mathbb{I}}(K)$ into the multiplicative group (K^{\times}, \cdot) of K , and if $\mathbb{I} \neq \emptyset$, then it is surjective. Its kernel Ker Det is the subgroup

$$SL_{\mathbb{I}}(K) := \{ \alpha \in GL_{\mathbb{I}}(K) \mid \text{Det } \alpha = 1 \}$$

of the matrices $\alpha \in GL_{\mathbb{I}}(K)$ whose determinant is 1. It is called the special linear group (corresponding to the index set \mathbb{I}). In particular, ($\mathbb{I} = \mathbb{N}_n^*$) we denote it by

$$SL_n(K)$$

for $n \in \mathbb{N}$, the group of the square $n \times n$ -matrices over K whose determinant is 1. By the isomorphism theorem 6.A.11, for $n \geq 1$, we have

$$GL_n(K) / SL_n(K) \cong K^{\times}$$

9.D.6 Example By 8.C.8 every matrix $\alpha \in GL_n(K)$ is a product of diagonal matrix $\text{Diag}(d, 1, \dots, 1)$ and

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elementary matrices $B_{ij}(a) = E_n + a E_{ij}$, $i \neq j$, $a \in K$. Since the elementary matrices have determinant 1, by the product theorem 9.D.5 the determinant of α is equal to the determinant of the diagonal matrix, i.e. equal to the coefficient d . If $\alpha \in SL_n(K)$, then necessarily $d = 1$ and α is the product of elementary matrices, in other words:

9.D.7 Theorem Let K be a field. Then the special linear group $SL_n(K)$, $n \in \mathbb{N}$, is generated by the elementary matrices $B_{ij}(a)$, $i \neq j$, $a \in K$.

Theorem 9.D.7 has the following important group theoretic ~~Corollary~~ Consequence:

9.D.8 Theorem Let K be a field and $n \in \mathbb{N}$, $n \geq 2$. Then the special

linear group $SL_n(K)$ is the commutator group of the general linear group $GL_n(K)$. In the case $|K|=2$, we assume $n=2$.

Proof Since the residue class group $GL_n(K)/SL_n(K) \cong K^*$ is commutative, the commutator group $N := [GL_n(K), GL_n(K)]$ of $GL_n(K)$ is contained in $SL_n(K)$.

By 9.D.7 it is enough to prove that the residue class of every elementary matrix $B_{ij}(a)$, $i \neq j$, $a \in K$, $a \neq 0$, is in $GL_n(K)/N$ is trivial.

Since

$$\begin{aligned} B_{ij}(a) &= \sigma B_{ij}(1) \sigma^{-1} \\ &= \sigma B_{ij}(1) \sigma^{-1} B_{ij}^{-1}(1) B_{ij}(1) \sigma^{-1} \end{aligned}$$

where $\sigma = \text{Diag}(1, \dots, 1, a, 1, \dots, 1)$ is the diagonal matrix with a at the i -th position on the diagonal, all $B_{ij}(a)$ have the same residue class as that of $B_{ij}(1)$

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Now, if $|K| > 2$ and if $a \notin \{0, 1\}$,
then $B_{ij}(1) = B_{ij}(1-a) B_{ij}(a)$.

It follows that the residue class
of $B_{ij}(1)$ is equal to its square
and hence it is trivial.

Now, assume that $n \geq 3$. Then
there exists $r \in \{1, \dots, m\} \setminus \{i, j\}$,
for every pair i, j ,

$r \in \{1, \dots, m\} \setminus \{i, j\}$. From the
equations

$$B_{ij}(a) = B_{rj}(a) \cdot B_{is}(-1) B_{rj}(a)^{-1} B_{ir}(-1)^{-1}$$

(which can be checked easily), it follows
that every elementary matrix $B_{ij}(a)$

is itself a commutator of elementary
matrices. Therefore, $SL_n(K)$, for $n \geq 3$,

is its own commutator subgroup,

i.e. $SL_n(K)$, $n \geq 3$, is a perfect group.

9.D.9 Corollary Let K be a field and $n \in \mathbb{N}$, $n \geq 2$; if $n=2$, then assume that $|K| > 2$. Then ~~for every~~ group homomorphism

$$\varphi: GL_n(K) \longrightarrow H$$

from $GL_n(K)$ in an abelian group H there exists a unique group homomorphism

$$\psi: K^\times \longrightarrow H$$

such that $\varphi(\alpha) = \psi(\text{Det } \alpha)$

for all $\alpha \in GL_n(K)$. It is

$$\psi(a) = \varphi(\text{Diag}(a, 1, \dots, 1)), a \in K^\times.$$

Proof By 9.D.8 φ is trivial on $SL_n(K)$ and hence the assertion follows from the Theorem 6.A.10 on induced homomorphisms. ■

In 9.D.8 and 9.D.9 the exceptional case $K = \mathbb{Z}_2$ and $n=2$, $GL_2(K) = SL_2(K) = GL_2(\mathbb{Z}_2) \cong S_3$ permut-

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tion group) and its commutator group $[\mathbb{S}_3 : \mathbb{S}_3] = \mathbb{A}_3$ has index 2.

Let K be a field, $n \in \mathbb{N}^*$ and $\varphi: GL_n(K) \rightarrow K^\times$ be a group homomorphism, i.e. a character of $GL_n(K)$ with values in K . Then it follows from 9.D.9 together with 5.A.17 that:

(1) If φ is a rational function, then there exists $m \in \mathbb{Z}$ with

$\varphi(\alpha) = (\text{Det } \alpha)^m$ for all $\alpha \in GL_n(K)$. In particular, if φ is a polynomial function, then $m \in \mathbb{N}$.

(2) If $K = \mathbb{R}$ and if φ is continuous, then there exists a real number $\beta \in \mathbb{R}$ with $\varphi(\alpha) = |\text{Det } \alpha|^\beta$ for all $\alpha \in GL_n(\mathbb{R})$ or with $\varphi(\alpha) = |\text{Det } \alpha|^\beta \text{Sign}(\text{Det } \alpha)$ for all $\alpha \in GL_n(\mathbb{R})$.

(3) If $K = \mathbb{C}$ and if φ is continuous,

then there exists a complex-number
 $\alpha \in \mathbb{C}$ and an integer $m \in \mathbb{Z}$ with $GL_n(\mathbb{C})$
 $\varphi(\alpha z) = |\text{Det } \alpha z| \cdot (\text{Det } \alpha z)^m$ for all $z \in GL_n(\mathbb{C})$

In the cases (2) and (3), consider $GL_n(\mathbb{K}) \subseteq \mathbb{K}^{n^2}$
 with the canonical topology induced
 from the usual topology of \mathbb{K}^{n^2} .

Further, in the case (1) the exception
 mentioned in 9.D.9 is not significant,
 since for the field \mathbb{Z}_2 with 2 elements,
 the group \mathbb{Z}_2^* is trivial.

9.D.10 Example (Special Projective
Linear Group) The center of the
 group $GL_n(K)$, K field, $n \geq 1$, is

$$\begin{aligned} Z(GL_n(K)) &= \{ a E_n \mid a \in K^* \} \\ &= K^* E_n \cong K^*. \end{aligned}$$

The residue class group

$$GL_n(K) / Z(GL_n(K))$$

is isomorphic to the group $PGL_n(K)$

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of projective collineations of the $(n-1)$ -dimensional projective space $\mathbb{P}^{n-1}(K)$, see Subsection 7.B which is called the projective linear group over K .

The center of the group $SL_n(K)$, $n \geq 1$, is the group $\sqrt[n]{E_n^{(K)}} := \{a \in K^\times \mid a^n = 1\}$ is the group of the n -th roots of unity in K .

$$* \quad Z(SL_n(K)) = \{a E_n \mid a \in E_n^{(K)}\}, \text{ where}$$

The corresponding residue-class group

$$PSL_n(K) = SL_n(K) / Z(SL_n(K))$$

is called the special linear group over K . The embedding

$SL_n(K) \rightarrow GL_n(K)$ induces an embedding $PSL_n(K) \rightarrow PGL_n(K)$ via this embedding and hence $PSL_n(K)$ can be identified as subgroup of $PGL_n(K)$. Moreover,

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it is normal in $\text{PGL}_m(K)$. The quotient group

$$\text{PGL}_m(K) / \text{PSL}_m(K) \cong K^x / {}^n K^x,$$

where ${}^n K^x$ is the subgroup

$\{a^n \mid a \in K^x\}$ of the n -th powers in K^x . In particular, $\text{PSL}_m(K) =$

$\text{PGL}_m(K)$ if and only if ${}^n K^x = K^x$, i.e. every element in K is a n -th power (in K).

We state (without proof) very important theorem:

Theorem Let K be a field and
 $n \in \mathbb{N}$, $n \geq 2$ (if $n=2$,
 then assume $|K| \geq 4$). Then the
special projective linear group
 $\text{PSL}_m(K)$ is simple (and non-abelian)

For a finite field K we note in particular, the order of this finite non-abelian simple group:

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Let \mathbb{K}_q be a finite field with q elements. Then (see Example 10.A.28)

$$|\mathrm{PSL}_n(\mathbb{K}_q)| = \frac{q^{\binom{n}{2}} (q^n - 1)(q^{n-1} - 1) \cdots (q^2 - 1)}{\mathrm{gcd}(q-1, n)}$$

Note that proof of this formula use the fact that \mathbb{K}^\times is cyclic (see 6.A.26) of order $q-1$ and hence the subgroup $E_n(\mathbb{K}_q) = \{a \in \mathbb{K}_q^\times \mid a^n = 1\}$ has the order $\mathrm{gcd}(q-1, n)$.

The groups $\mathrm{PSL}_2(\mathbb{K}_2) = \mathrm{PGL}_2(\mathbb{K}_2) \cong \mathbb{S}_3$
and $\mathrm{PSL}_2(\mathbb{K}_3) \cong \mathbb{A}_4$ are not simple.

(Note that $\mathrm{PGL}_2(\mathbb{K}_3) \cong \mathbb{S}_4$).

The simple groups $\mathrm{PSL}_2(\mathbb{K}_5)$ and $\mathrm{PSL}_2(\mathbb{K}_4) = \mathrm{PGL}_2(\mathbb{K}_4)$ both have order 60 and hence isomorphic to \mathbb{A}_5 , see Example 9.A.15. The smallest non-abelian simple group with more than 60 elements is (upto isomorphism) is the

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group $PSL_2(\mathbb{K}_7) \cong PSL_3(\mathbb{K}_2) = PGL_3(\mathbb{K}_2)$
 $= GL_3(\mathbb{K}_2)$ with 168 elements which
is often denoted by G_{168} .

The group $PGL_2(\mathbb{K}_5)$ is of order
120 and by Example 7.B.4 operates
transitively (even 3-fold transitively)
on the projective line $\mathbb{P}^1(\mathbb{K}_5) = \overline{\mathbb{K}_5}$
 $= \{0, 1, 2, 3, 4, \infty\}$. It is an interesting
subgroup (of index 6) of the (full-)
permutation group $S(\overline{\mathbb{K}_5}) = S_6$.

The canonical operation of $S(\overline{\mathbb{K}_5})$ on
the set $S(\overline{\mathbb{K}_5}) / PGL_2(\mathbb{K}_5)$ of left-
cosets induces a group homomorphism

$$\underline{\Phi}: S(\overline{\mathbb{K}_5}) \xrightarrow{\sim} G(S(\overline{\mathbb{K}_5}) / PGL_2(\mathbb{K}_5))$$

which is trivially injective and hence
bijective. If $\tau \in S(\overline{\mathbb{K}_5})$ is a transposi-
tion, then $\underline{\Phi}(\tau): \sigma PGL_2(\mathbb{K}_5) \mapsto \tau \sigma PGL_2(\mathbb{K}_5)$

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has clearly no fixed point (see again Example 7.B.4) and is in particular, cannot be a transposition.

If $\psi: \overline{\mathbb{K}_5} \rightarrow \mathbb{S}(\overline{\mathbb{K}_5}) / \text{PGL}_2(\overline{\mathbb{K}_5})$ is an arbitrary bijection, then the group automorphism

$$\mathbb{S}(\overline{\mathbb{K}_5}) \rightarrow \mathbb{S}(\overline{\mathbb{K}_5}), \sigma \mapsto \psi^{-1} \psi(\sigma) \psi$$

of $\mathbb{S}(\overline{\mathbb{K}_5})$ is not an inner automorphism of $\mathbb{S}(\overline{\mathbb{K}_5})$, since for a transposition τ as above, the image $\psi^{-1} \psi(\tau) \psi$ is not a transposition.

On the other hand, for $n \neq 6$, all automorphisms of \mathbb{S}_n are inner automorphisms.

The group $\text{Inn } \mathbb{S}_6 \cong \mathbb{S}_6 / Z(\mathbb{S}_6) = \mathbb{S}_6$, see Example 9.A.12) of inner automorphisms of \mathbb{S}_6 has the index 2 in the group $\text{Aut } \mathbb{S}_6$ of all automorphisms of \mathbb{S}_6 . Therefore $|\text{Aut } \mathbb{S}_6| = 1440$.

Moreover, $\text{PGL}_2(K_5) \cong S_5$. For a proof consider the dihedral group D_4 which is isomorphic to the subgroup $D \subseteq G := \text{PGL}_2(K_5)$ of the transformations $z \mapsto az$ and $z \mapsto b\bar{z}^{-1}$, $a, b \in K_5^\times$, and within the subgroup $V := \{ \pm z, \pm \bar{z} \}$ which is isomorphic to the Klein's 4-group $D_2 = \mathbb{Z}_2 \times \mathbb{Z}_2$ (for the description of elements of G , see Example 7.B.4). Moreover, V is a subgroup of $\text{PSL}_2(K_5) \cong A_5$ (Note that D contains another subgroup $\tilde{V} := \{ \pm z, \pm 2\bar{z} \}$ which is isomorphic to D_2 , but not contained in $\text{PSL}_2(K_5)$.)

The normaliser $N_G(V)$ of V in G is contained in D and is isomorphic to N_4 (a subgroup of $\text{PSL}_2(K_5)$ which is) (since N_4 is normal in N_4), its order is therefore a multiple of 24. But, since

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V is not normal in G , $|N_G(V)| = 24$

and the natural transitive not necessarily faithful operation of G on

$G/N_G(V)$ induces an isomorphism

$$G \cong \mathcal{S}(G/N_G(V)) \cong \mathcal{S}_5.$$

(moreover, $N_G(\tilde{V}) = D$)

The inverse matrix of an invertible matrix can be explicitly given by with the help of determinants. For preparation we introduce of notation =

Let $M = (a_{ij}) \in M_n(K)$ be a $n \times n$ matrix. The determinants of the $(n-1) \times (n-1)$ -matrix

$$M(1, \dots, i-1, i+1, \dots, n \mid 1, \dots, j-1, j+1, \dots, n)$$

obtained from M by deleting i -th row and j -th column is denoted by

A_{ij} . By 9.A.4 (with $r=1$ and $s=n-1$)

$$A_{ij} = \begin{vmatrix} 1 & a_{i1} & \dots & a_{i,j-1} & a_{i,j+1} & a_{in} \\ 0 & a_{11} & & a_{1,j-1} & a_{1,j+1} & a_{1n} \\ \vdots & \vdots & & \vdots & \vdots & \vdots \\ 0 & a_{i-1,1} & & a_{i-1,j-1} & a_{i-1,j+1} & a_{i-1,n} \\ 0 & a_{i+1,1} & & a_{i+1,j-1} & a_{i+1,j+1} & a_{i+1,n} \\ \vdots & \vdots & & \vdots & \vdots & \vdots \\ 0 & a_{n1} & & a_{n,j-1} & a_{n,j+1} & a_{nn} \end{vmatrix}$$

By $(i-1)$ -interchanges of rows and $(j-1)$ interchanges of columns, we get =

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$$A_{ij} = (-1)^{i+j} \begin{vmatrix} a_{11} & \dots & a_{1,j-1} & 0 & a_{1,j+1} & \dots & a_{1n} \\ \vdots & & \vdots & \vdots & \vdots & & \vdots \\ a_{i1} & \dots & a_{i,j-1} & 1 & a_{i,j+1} & \dots & a_{in} \\ \vdots & & \vdots & \vdots & \vdots & & \vdots \\ a_{n1} & \dots & a_{n,j-1} & 0 & a_{n,j+1} & \dots & a_{nn} \end{vmatrix}$$

$$= (-1)^{i+j} \Delta_{\underline{e}} (x_1, \dots, x_{j-1}, e_i, x_{j+1}, \dots, x_n)$$

where x_1, \dots, x_n are the columns of \mathcal{M} and $\underline{e} = (e_1, \dots, e_n)$ is the standard basis of K^n .

9.D.11 Expansion Theorem for Determinants

Let $\mathcal{M} = (a_{ij}) \in M_n(K)$. Then for all $i, j \in \{1, 2, \dots, n\}$ we have:

$$\begin{aligned} \text{Det } \mathcal{M} &= \sum_{k=1}^n (-1)^{k+j} a_{kj} A_{kj} \\ &= \sum_{k=1}^n (-1)^{i+k} a_{ik} A_{ik} \end{aligned}$$

The first equality is known as the

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expansion of $\text{Det } \alpha$ by the j -th column
 and the second equality is known as the
expansion of $\text{Det } \alpha$ by the i -th row.

Proof of 9.D.11 It is enough to
 prove the first equality. The second
 equality follows by applying the first
 equality to the transpose matrix α^t .
 Using the above notation, we have:

$$\begin{aligned}
 \text{Det } \alpha &= \Delta_{\underline{e}}(x_1, \dots, x_j, \dots, x_n) \\
 &= \Delta_{\underline{e}}\left(x_1, \dots, \sum_{k=1}^n a_{kj} e_k, \dots, x_n\right) \\
 &= \sum_{k=1}^n a_{kj} \Delta_{\underline{e}}(x_1, \dots, x_{j-1}, e_k, x_{j+1}, \dots, x_n) \\
 &= \sum_{k=1}^n (-1)^{k+j} a_{kj} A_{kj} \quad \square
 \end{aligned}$$

Further, for $\alpha = (a_{ij}) \in M_n(K)$,
 the matrix

$$\text{Adj } \alpha := (\tilde{a}_{ij}) \text{ with } \tilde{a}_{ij} := (-1)^{i+j} A_{ji}$$

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is called the adjoint matrix of A or adjoint to A .

Note that in the formation of the adjoint matrix the interchange in the indices i and j :

The (i, j) -th entry of $\text{Adj } A$ is obtained by deleting j -th row and i -th column of A . The sign $(-1)^{i+j}$ is obtained from the checker:

$$\begin{pmatrix} + & - & + & \dots \\ - & + & - & \dots \\ + & - & + & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}$$

The element $(-1)^{i+j} A_{ij} = \tilde{a}_{ji}$ is also called the (i, j) -th cofactor of A

9.D.12 Example

$$\text{Adj} \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = \begin{pmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{pmatrix}. \text{ Further,}$$

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$$\text{Adj} \begin{pmatrix} 1 & 0 & 2 \\ 2 & -1 & 3 \\ 4 & 1 & 8 \end{pmatrix} = \begin{bmatrix} \begin{vmatrix} -1 & 3 \\ 1 & 8 \end{vmatrix} & - \begin{vmatrix} 0 & 2 \\ 1 & 8 \end{vmatrix} & \begin{vmatrix} 0 & 2 \\ -1 & 3 \end{vmatrix} \\ - \begin{vmatrix} 2 & 3 \\ 4 & 8 \end{vmatrix} & \begin{vmatrix} 1 & 2 \\ 4 & 8 \end{vmatrix} & - \begin{vmatrix} 1 & 2 \\ 2 & 3 \end{vmatrix} \\ \begin{vmatrix} 2 & -1 \\ 4 & 1 \end{vmatrix} & - \begin{vmatrix} 1 & 0 \\ 4 & 1 \end{vmatrix} & \begin{vmatrix} 1 & 0 \\ 2 & -1 \end{vmatrix} \end{bmatrix}$$

$$= \begin{pmatrix} -11 & 2 & 2 \\ -4 & 0 & 1 \\ 6 & -1 & -1 \end{pmatrix}$$

From the Expansion Theorem 9.D.11,
it follows directly:

9.D.13 Theorem Let $\alpha \in M_n(K)$.

Then:

$$\begin{aligned} (\text{Adj } \alpha) \cdot \alpha &= \alpha \cdot (\text{Adj } \alpha) \\ &= (\text{Det } \alpha) E_n \end{aligned}$$

If α is invertible, then

$$\alpha^{-1} = \frac{1}{\text{Det } \alpha} \cdot \text{Adj } \alpha.$$

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Proof Let $\alpha = (a_{ij})$ and

$$\text{Adj } \alpha = (\tilde{a}_{ij}) \text{ with } \tilde{a}_{ij} = (-1)^{i+j} A_{ji}.$$

Then $(\text{Adj } \alpha) \cdot \alpha = (b_{ij})$ with

$$b_{ij} = \sum_{k=1}^n \tilde{a}_{ik} \cdot a_{kj} = \sum_{k=1}^n (-1)^{k+i} a_{kj} A_{ki}$$

$$= \delta_{ij} \cdot \text{Det } \alpha$$

$$\left(\text{Note by 9.D.11: } \text{Det } \alpha = \sum_{k=1}^n (-1)^{k+i} a_{kj} A_{kj} \right)$$

In the case $i=j$ the last equality is the Expansion of the $\text{Det } \alpha$ by the j -th Column by 9.D.11. For $i \neq j$,

again by 9.D.11:

$$\sum_{k=1}^n (-1)^{k+i} a_{kj} A_{ki}$$

is the determinant of the matrix obtained from α by replacing i -th column by the j -th column and hence this matrix has two equal columns; thus its determinant is 0.

The equation $AC \cdot \text{Adj} C = (\text{Det} C)E_n$ is proved analogously ~~with~~ ^{by using} the expansion theorem for rows.

It also follows formally from the first equality for the transpose tAC of AC and the equality

$$\text{Adj} {}^tAC = {}^t(\text{Adj} AC)$$

(by taking transpose).

The last assertion in 9.D.13 follows from the fact that the determinant of an invertible matrix is $\neq 0$ (see Cor. to 9.D.5).

9.D.14 Corollary (Cramer's Rule)

Let

$$a_{11}x_1 + \dots + a_{1n}x_n = b_1$$

$$a_{m1}x_1 + \dots + a_{mn}x_n = b_n$$

be a system of m linear equations in n unknowns with coefficients in the field K . Suppose that the coefficient

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matrix $\alpha = (a_{ij}) \in GL_n(K)$. Then

$$\underline{x}_j = \begin{pmatrix} a_{11} & \dots & a_{1,j-1} & b_1 & a_{1,j+1} & \dots & a_{1n} \\ \vdots & & \vdots & & \vdots & & \vdots \\ a_{n1} & \dots & a_{n,j-1} & b_n & a_{n,j+1} & \dots & a_{nn} \end{pmatrix}$$

Det α

$j=1, \dots, n$

is the unique solution of the given system.

Proof Let $\underline{b} = (b_i) \in K^n$. The system $\alpha \cdot \underline{x} = \underline{b}$ for $\underline{x} \in K^n = (x_i)_{i \in I}$

is equivalent with the system

$$\underline{x} = \alpha^{-1} \underline{b} = \frac{1}{\text{Det } \alpha} (\text{Adj } \alpha) \underline{b}$$

Equating the j -th component:

$$x_j = \frac{1}{\text{Det } \alpha} \sum_{k=1}^n (-1)^{j+k} A_{kj} b_k.$$

Now the result follows from the Expansion Theorem 9.D.11 ■

9.D.15 Example. The determinant of the coefficient matrix of the system of linear equations:

$$\begin{aligned}x_1 + 2x_3 &= 1 \\2x_1 - x_2 + 3x_3 &= 0 \\4x_1 + x_2 + 8x_3 &= -1\end{aligned}$$

is by Example 9.D.3 is equal to 1

Therefore by the Cramer's Rule 9.D.14 the system has the unique solution:

$$x_1 = \begin{vmatrix} 1 & 0 & 2 \\ 0 & -1 & 3 \\ -1 & 1 & 8 \end{vmatrix} = -13$$

$$x_2 = \begin{vmatrix} 1 & 0 & 2 \\ 2 & 0 & 3 \\ 4 & -1 & 8 \end{vmatrix} = -5$$

$$x_3 = \begin{vmatrix} 1 & 0 & 1 \\ 2 & -1 & 0 \\ 4 & 1 & -1 \end{vmatrix} = 7$$

The inverse of the coefficient matrix is by 9.D.13 and the Computational Rule in Example 9.D.12 is:

$$\begin{pmatrix} 1 & 0 & 2 \\ 2 & -1 & 3 \\ 4 & 1 & 8 \end{pmatrix}^{-1} = \begin{pmatrix} -11 & 2 & 2 \\ 4 & 0 & 1 \\ 6 & -1 & -1 \end{pmatrix}, \text{ see also Example 8.B.7.}$$

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With these calculations, note that the unique solution of the system in the form =

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -11 & 2 & 2 \\ -4 & 0 & 1 \\ 6 & -1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} -13 \\ -5 \\ 7 \end{pmatrix}$$

We remark also that the Cramer's Rule and the formulae in 9.D.13 in general, have more theoretical interest. For ^{finding} the solutions ~~of~~ concretely of systems of equations (resp. finding inverses of matrices) ^{explicitly} We recommend the Gauss-elimination process (resp. ^{the} methods deduced from ~~Gauss-elimination~~ ^{it}, see also the subsections 8.B and 8.C.