

11.D Jordan Normal Form

We consider triangonalisable operators f on finite dimensional K -vector spaces V . We shall improve the description of such operators given in 11.C.6.

Suppose that $\chi_f = (X - \lambda_1)^{\alpha_1} \cdots (X - \lambda_r)^{\alpha_r}$ is the characteristic polynomial of $f: V \rightarrow V$ with pairwise distinct zeros $\lambda_1, \dots, \lambda_r \in K$ of multiplicities $\alpha_1, \dots, \alpha_r$. Then the minimal polynomial of f is of the form $\mu_f = (X - \lambda_1)^{\beta_1} \cdots (X - \lambda_r)^{\beta_r}$, with $0 \leq \beta_i \leq \alpha_i$ for $i = 1, \dots, r$. The primary-components $V_i = \text{Ker}(f - \lambda_i \text{id}_V)^{\beta_i}$, $i = 1, \dots, r$, in general can be further decomposed into f -invariant subspaces, on these subspaces f operates in particular in a simple way. For this we may assume that V itself is such a primary component, see 11.C.6. Then $\mu_f = (X - \lambda)^\beta$. We consider the chain of so-called higher eigen-spaces

$$V_f^{(i)} := V^{(i)} := \text{Ker}(f - \lambda \text{id})^i, \quad i = 1, \dots, \beta.$$

Then $0 = V^{(0)} \subsetneq V^{(1)} \subsetneq \cdots \subsetneq V^{(\beta)} = V$

all these inclusions are strict. For the proof we need the following lemma:

11.D.1 Lemma Let $g: V \rightarrow V$ be an operator on the K -vector space V . For every $i \in \mathbb{N}$, g induces an injective homomorphism

$$\text{Ker } g^{i+2} / \text{Ker } g^{i+1} \xrightarrow{\bar{g}} \text{Ker } g^{i+1} / \text{Ker } g^i.$$

In particular, $\text{Ker } g^i = \text{Ker } g^{i_0}$ for all $i \geq i_0$, if $\text{Ker } g^{i_0+1} = \text{Ker } g^{i_0}$.

Proof Clearly for every $i \in \mathbb{N}$, g maps the subspace $\text{Ker } g^{i+1}$ in $\text{Ker } g^i$. Therefore there exists the given homomorphism \bar{g} . For the proof of its injectivity, let $x \in \text{Ker } g^{i+2}$ with $\bar{g}(\bar{x}) = \overline{g(x)} = 0$, i.e. $g(x) \in \text{Ker } g^i$. Then $0 = g^i(g(x)) = g^{i+1}(x)$, i.e. $x \in \text{Ker } g^{i+1}$ and so $\bar{x} = 0$ in $\text{Ker } g^{i+2} / \text{Ker } g^{i+1}$.

We now apply 11.D.1 to $g := f - \lambda \text{id}$. Since $g^{\beta-1} \neq 0$, $\text{Ker } g^{\beta-1} = V^{(\beta-1)} \subsetneq V = \text{Ker } g^{\beta}$. This proves that all inclusions $V^{(i)} \subsetneq V^{(i+1)}$ are strict for $i = 0, \dots, \beta-1$. Further, we have the following chain of injective homomorphisms:

$$0 = V^{(\beta+1)} / V^{(\beta)} \xrightarrow{\bar{g}} V^{(\beta)} / V^{(\beta-1)} \xrightarrow{\bar{g}} V^{(\beta-1)} / V^{(\beta-2)} \xrightarrow{\bar{g}} \dots \xrightarrow{\bar{g}} V^{(2)} / V^{(1)} \xrightarrow{\bar{g}} V^{(1)} / V^{(0)} = V^{(1)}.$$

Now, for $j = 1, \dots, \beta$, suppose that $v_1^{(j)}, \dots, v_{n_j}^{(j)}$, $n_j := \dim_{\mathbb{K}} V^{(j)} / V^{(j-1)} - \dim_{\mathbb{K}} V^{(j+1)} / V^{(j)}$ are vectors in $V^{(j)}$ such that their residue-classes in $V^{(j)} / V^{(j-1)}$ form a basis of a complement of $\bar{g}(V^{(j+1)} / V^{(j)})$ in $V^{(j)} / V^{(j-1)}$. Then

$$v_1^{(1)}, \dots, v_{n_1}^{(1)}, v_1^{(2)}, g v_1^{(2)}, \dots, v_{n_2}^{(2)}, g v_{n_2}^{(2)},$$

$$\dots$$

$$v_1^{(\beta)}, g v_1^{(\beta)}, \dots, g^{\beta-1} v_1^{(\beta)}, \dots, v_{n_\beta}^{(\beta)}, g v_{n_\beta}^{(\beta)}, \dots, g^{\beta-1} v_{n_\beta}^{(\beta)}$$

is clearly a basis of $V = V^{(\beta)}$. Further, since $g(x) = (f - \lambda \text{id})(x) = f(x) - \lambda x$, i.e.

$$f(x) = \lambda x + g(x)$$

and $g^j v_1^{(j)} = \dots = g^j v_{n_j}^{(j)} = 0$ for $j=1, \dots, \beta$,

the matrix of f with respect to this basis is the diagonal-block matrix

$$\text{Diag} \left(\mathcal{D}_1^{(1)}, \dots, \mathcal{D}_{n_1}^{(1)}, \dots, \mathcal{D}_1^{(\beta)}, \dots, \mathcal{D}_{n_\beta}^{(\beta)} \right),$$

where the matrices $\mathcal{D}_i^{(j)}$ are of the form:

$$f^{(j)}(\lambda) = \begin{pmatrix} \lambda & 0 & \dots & 0 & 0 \\ 1 & \lambda & & 0 & 0 \\ \vdots & \vdots & & & \\ 0 & 0 & & \lambda & 0 \\ 0 & 0 & & 1 & \lambda \end{pmatrix} \in M_j(K)$$

Conversely, if the matrix of f with respect to a basis of V is of such a form, then the number of the blocks $f^{(j)}(\lambda)$ of length j in this matrix is equal to

$$n_j = \dim_K V^{(j)} / V^{(j-1)} - \dim_K V^{(j+1)} / V^{(j)}$$

$$= 2 \dim_K V^{(j)} - \dim_K V^{(j-1)} - \dim_K V^{(j+1)},$$

$j \geq 1$ and hence independent of the choice of

the basis and $\hat{\alpha}$ uniquely determined by f . The matrices of the type $J^{(j)}(\lambda)$, $\lambda \in K$, are called Jordan-matrices over K and a matrix in the above block-form with Jordan-matrices in the main-diagonal, where the diagonal elements λ for distinct blocks are also distinct, is said to be in Jordan-Normal form. With this we have proved:

11.D.2 Jordan-Normal-Form For every triangonalisable operator f on a finite dimensional K -vector space V , there exists a basis of V such that the matrix of f with respect to this basis is a matrix in Jordan-normal-form. Moreover, the number $n_j(\lambda)$ of Jordan-blocks $J^{(j)}(\lambda)$ of length j corresponding to the eigen-value λ , appearing are uniquely determined and is equal to

$$2 \dim_K \ker(f - \lambda \text{id})^j - \dim_K \ker(f - \lambda \text{id})^{j-1} - \dim_K \ker(f - \lambda \text{id})^{j+1}.$$

For matrices the formulation is: Every triangonalisable matrix in $M_n(K)$ is similar to a matrix in Jordan-normal form. Moreover, this is uniquely determined upto an order of the Jordan-blocks.

11.D.3 Example We consider the operator $f: \mathbb{R}^5 \rightarrow \mathbb{R}^5$ with the matrix with respect to the standard basis

$$\mathcal{M} := \begin{pmatrix} 4 & -4 & 9 & 7 & 11 \\ 1 & 0 & 4 & 4 & 6 \\ 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 & 3 \end{pmatrix} \in M_5(\mathbb{R}).$$

$$\text{Then } \chi_f = \chi_{\mathcal{M}} = \text{Det}(X E_5 - \mathcal{M}) = (X-2)^5$$

$$\text{Further, } V^{(1)} := \text{Ker}(f - 2\text{id}) = V_f(2)$$

$$= \mathbb{R}^t(2, 1, 0, 0, 0) \oplus \mathbb{R}^t(-2, 0, 0, -1, 1)$$

$$V^{(2)} = \text{Ker}(f - 2\text{id})^2 =$$

$$= V^{(1)} \oplus \mathbb{R}^t(1, 0, 0, 0, 0) \oplus \mathbb{R}^t(0, 0, -1, 1, 0)$$

$$V^{(3)} = \text{Ker}(f - 2\text{id})^3 = \mathbb{R}^5 = V^{(2)} \oplus \mathbb{R}^t(0, 0, 0, 0, 1)$$

The vector $v_1^{(3)} = (0, 0, 0, 0, 1)$ extends a basis of $V^{(2)}$ to a basis of $V^{(3)} = V$ and therefore form a basis of $V^{(3)}/V^{(2)}$. Moreover, $g(v_1^{(3)}) = {}^t(11, 6, -1, 0, 1) \in V^{(2)}$ with $g := f - 2\text{id}$.

The vector $v_1^{(2)} := {}^t(0, 0, -1, 1, 0)$ together with $g(v_1^{(3)})$ and a basis of $V^{(1)}$ to a basis of $V^{(2)}$. Its residue class in $V^{(2)}/V^{(1)}$, therefore generate a complement of $\bar{g}(V^{(3)}/V^{(2)})$. It follows

that the matrix of f with respect to the basis

$$v_1^{(2)} = {}^t(0, 0, -1, 1, 0), \quad g v_1^{(2)} = {}^t(-2, 0, 0, -1, 1),$$

$$v_1^{(3)} = {}^t(0, 0, 0, 0, 1), \quad g v_1^{(3)} = {}^t(11, 6, -1, 0, 1), \quad g^2 v_1^{(3)} =$$

$${}^t(0, 1, 0, -1, 1) \text{ is the Jordan-form: } \begin{pmatrix} 2 & 0 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 & 0 \\ \hline 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 & 2 \end{pmatrix}.$$

11.D.4 Remark One can deduce Theorem 11.D.2 on the Jordan Normal form very elegantly and in a more general form (any field K), from the Elementary divisor theorem 10.A.31 for polynomials in $K[X]$. At the same time these ~~methods~~ ^{important} methods supply an algorithmic process to transform a matrix to the Jordan-normal form.

Let $f: V \rightarrow V$ be a K -linear operator on the n -dimensional K -vector space V . Using the primary decomposition theorem 11.C.5, we may assume that the characteristic polynomial χ_f of f is the power P^α , $\alpha \geq 1$, of a monic prime polynomial $P \in K[X]$ of degree m .¹ Then $n = m\alpha$ and the minimal polynomial μ_f of f is P^β , $1 \leq \beta \leq \alpha$.

Let $\underline{v} = \{v_1, \dots, v_n\}$ be a basis of V and $\mathcal{M}_{\underline{v}}(f) = (a_{ij})$ be the matrix of f with respect to \underline{v} (For $j \in I$, $f(v_j) = \sum_{i \in I} a_{ij} v_i$, $I = \{1, \dots, n\}$). We consider the surjective K -linear map $\varepsilon: K[X]^n \rightarrow V$ with

¹ This reduction is often unnecessary. The following process supply a basis of V such that the matrix of f is a diagonal-block matrix $\text{Diag}(\mathcal{M}_{E_1}, \dots, \mathcal{M}_{E_n})$, where the polynomials E_1, \dots, E_n are the elementary divisors of the matrix $X E_n - \mathcal{M} \in M_n(K[X])$ and $\mathcal{M}_{E_1}, \dots, \mathcal{M}_{E_n}$ are their companion matrices. This representation of f (resp. \mathcal{M}) is known as the first normal-form or the rational canonical form of the operator f (resp. the matrix \mathcal{M}).

$\varepsilon(F_1, \dots, F_n) := \sum_{j=1}^n F_j(f)(v_j)$. The characteristic

matrix $\mathfrak{X} := X E_n - \alpha \in M_n(K[X])$

and its determinant $\text{Det } \mathfrak{X} = \chi_f$ is the characteristic polynomial of f which is $\chi_f = P^a$ by assumption. The matrix \mathfrak{X} defines the K -linear map $K[X]^n \xrightarrow{\mathfrak{X}} K[X]^n$ with $F = {}^t(F_1, \dots, F_n) \mapsto \mathfrak{X} F$ defined by the matrix multiplication. Then the following sequence is exact:

$$0 \longrightarrow K[X]^n \xrightarrow{\mathfrak{X}} K[X]^n \xrightarrow{\varepsilon} V \longrightarrow 0$$

Proof First we shall prove that $\text{Im } \mathfrak{X} \subseteq \text{Ker } \varepsilon$: i.e. $\varepsilon \circ \mathfrak{X} = 0$. Let $F = {}^t(F_1, \dots, F_n) \in K[X]^n$. Then

$$\begin{aligned} \varepsilon(\mathfrak{X} F) &= \varepsilon(X F - \alpha F) = \sum_{j=1}^n f F_j(f)(v_j) - \\ &\sum_{i=1}^n \sum_{j=1}^n a_{ij} F_j(v_i) = \sum_{j=1}^n F_j(f)(f(v_j)) - \sum_{j=1}^n F_j(f)(f(v_j)) \\ &\quad \text{(remember } f(v_j) = \sum_{i=1}^n a_{ij} v_i \text{ for every } j=1, \dots, n) \end{aligned}$$

From the Theorem 10.A.34, we have

$\text{Dim}_K \text{Coker } \mathfrak{X} = \deg(\text{Det } \mathfrak{X}) = \deg \chi_f = n = \text{Dim}_K V$. Therefore $\text{Im } \mathfrak{X} = \text{Ker } \varepsilon$. Moreover, since $\text{Det } \mathfrak{X} \neq 0$, $\text{Rank } \mathfrak{X} = n$ and hence multiplication by \mathfrak{X} is injective. ■

By the Elementary divisor theorem 10.A.31, there exists elementary matrices

$\in M_{d_i, m}(K)$. This is an $d_i \times d_i$ ^{block-}matrix with entries in $M_m(K)$, where

$$D_{L_P} = \begin{pmatrix} 0 & 0 & \dots & 0 & -a_0 \\ 1 & 0 & \dots & 0 & -a_1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 0 & -a_{m-2} \\ 0 & 0 & \dots & 1 & -a_{m-1} \end{pmatrix} \in M_m(K)$$

is the companion

matrix of the polynomial P and

$$E_{1m} = \begin{pmatrix} 0 & 0 & \dots & 0 & 1 \\ 0 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & & \vdots & \vdots \\ 0 & 0 & \dots & 0 & 0 \end{pmatrix} \in M_m(K)$$

In the special case $P = X - a$, the (standard) Jordan-matrix $\mathcal{J}^{(d_i)}(X - a)$ is simply denoted by $\mathcal{J}^{(d_i)}(a)$. Altogether, we have proved that:

11.D.5 Theorem Let $f: V \rightarrow V$ be a K -linear operator on the finite dimensional K -vector space V . Then there exist a decomposition $V = V_1 \oplus \dots \oplus V_r$ of V into f -invariant subspaces V_1, \dots, V_r of V such that there is a basis of V_i such that the matrix of $f|_{V_i}: V_i \rightarrow V_i$ is of the form $\mathcal{J}^{(d_i)}(P_i)$ with a prime polynomial $P_i \in K[X]$ and $d_i \in \mathbb{N}^*$.

In the situation of Theorem 11.D.5 the characteristic polynomial of $f|_{V_i}$ (and the minimal

Note that: since $\sum_{i=1}^n \alpha_i = d \leq n$, many of the α_i 's are 0. When exactly all $\alpha_i \neq 0$?

Let $h_i: K[X]/K[X]P^{\alpha_i} \xrightarrow{\cong} V_i$ be defined by using the isomorphism $h: \text{Coker } \sigma \xrightarrow{\cong} V$ and let $u_i = h_i(\bar{1})$. Clearly $h_i(H) = H(f)(u_i)$ for all $H \in K[X]$. We put $x := \bar{x} \in K[X]/K[X]P^{\alpha_i}$.

Then the K -basis (of $K[X]/K[X]P^{\alpha_i}$)

$$1, x, \dots, x^{m-1}, P(x), xP(x), \dots, x^{m-1}P(x), \dots \\ P^{\alpha_i-1}(x), xP^{\alpha_i-1}(x), \dots, x^{m-1}P^{\alpha_i-1}(x)$$

of $K[X]/K[X]P^{\alpha_i}$ correspond to the K -basis

$$u_i, f(u_i), \dots, f^{m-1}(u_i), P(f)(u_i), fP(f)(u_i), \dots, f^{m-1}P(f)(u_i), \dots \\ P^{\alpha_i-1}(f)(u_i), fP^{\alpha_i-1}(f)(u_i), \dots, f^{m-1}P^{\alpha_i-1}(f)(u_i)$$

of V_i .

If $P = X^m + a_{m-1}X^{m-1} + \dots + a_1X + a_0$, then the matrix of $f|_{V_i}: V_i \rightarrow V_i$ with respect to this basis is the generalised Jordan-matrix $\mathcal{J}^{(\alpha_i)}(P)$:

$$\mathcal{J}^{(\alpha_i)}(P) = \begin{pmatrix} \mathcal{D}_P & 0 & 0 & \dots & 0 & 0 \\ \mathcal{E}_{1m} & \mathcal{D}_P & 0 & \dots & 0 & 0 \\ 0 & \mathcal{E}_{1m} & \mathcal{D}_P & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \dots & \mathcal{D}_P & 0 \\ 0 & 0 & 0 & \dots & \mathcal{E}_{1m} & \mathcal{D}_P \end{pmatrix}$$

$$\mathcal{L}_1, \dots, \mathcal{L}_p; \tau_1, \dots, \tau_q \in GL_n(K[X])$$

such that

$\mathcal{L}_1 \dots \mathcal{L}_p \mathcal{E} \tau_1 \dots \tau_q = \mathcal{D} = \text{Diag}(E_1, \dots, E_n)$
is the diagonal matrix.

Since $\text{Det } \mathcal{L}_1 = \dots = \text{Det } \mathcal{L}_p = \text{Det } \tau_1 = \dots = \text{Det } \tau_q = 1$,
we have $E_1 \dots E_n = \text{Det } \mathcal{D} = \text{Det } \mathcal{E} = P^\alpha$ (by assumption).

Now, since P is prime in $K[X]$, there exist elements $\varepsilon_i \in K^\times$ and $\alpha_i \in \mathbb{N}$ with $E_i = \varepsilon_i P^{\alpha_i}$ for $i=1, \dots, n$. Using the invertibility of matrices $\mathcal{L} := \mathcal{L}_1 \dots \mathcal{L}_p$ and $\tau := \tau_1 \dots \tau_q$ in $M_n(K[X])$

the following diagram is commutative:

$$\begin{array}{ccc} K[X]^n & \xrightarrow{\mathcal{D}} & K[X]^n \\ \tau \downarrow \cong & & \cong \downarrow \mathcal{L}^{-1} \\ K[X]^n & \xrightarrow{\mathcal{E}} & K[X]^n \end{array}$$

Therefore \mathcal{L}^{-1} induces an isomorphism h on the cokernels: $h: \text{Coker } \mathcal{D} \xrightarrow{\cong} \text{Coker } \mathcal{E} (= V)$.
But the cokernel $\text{Coker } \mathcal{D}$ of \mathcal{D} is the direct sum

$$\text{Coker } \mathcal{D} = \bigoplus_{i=1}^n K[X] / K[X] E_i = \bigoplus_{i=1}^n K[X] / K[X] P^{\alpha_i}$$

This direct sum decomposition of $\text{Coker } \mathcal{D}$ corresponds to the direct sum decomposition of V :

$$V = V_1 \oplus V_2 \oplus \dots \oplus V_n \text{ with } \dim_K V_i = \alpha_i m, \quad i=1, \dots, n.$$

