LECTURES 5 AND 6

1. Lecture 5 (First Chern form, Kähler connection, and curvature)

Suppose \tilde{h} is another Hermitian metric. Note that $\frac{\tilde{h}_{\alpha}}{h_{\alpha}} = \frac{\tilde{h}_{\beta}}{h_{\beta}}$. Hence $\tilde{h} = he^{-\phi}$ where ϕ is some smooth globally defined function. Note that $c_1(\tilde{h}) = c_1(h) + \frac{\sqrt{-1}}{2\pi} \partial \bar{\partial} \phi$. In other words, $[c_1(h)]$ (the De Rham cohomology class) is independent of the metric chosen !! This topological quantity is called the first Chern class of the line bundle *L*.

It seems that the first Chern form almost gives us a Kähler form except for the point that it may not be positive-definite. We define the following : A holomorphic line bundle is said to positive is $c_1(L)(h)$ is positive for some Hermitian metric *h* (likewise, negative). A (1, 1) De Rham cohomology class [ω] is said to be positive if there is a Kähler form in it, i.e., there is a Kähler form ω' such that $\omega' = \omega + d\eta$.

Exercise : Using the $\partial \overline{\partial}$ lemma, show that if $[\omega] = [c_1(L)]$ then there is a smooth Hermitian metric h so that $c_1(h) = \omega$, i.e., every form in the first Chern class can be realised using a Hermitian metric.

By the way,

Theorem 1.1 (Kodaira's embedding theorem). A compact complex manifold can be holomorphically embedded as a submanifold in \mathbb{CP}^n iff it has a positive holomorphic line bundle L.

The Fubini-Study metric (up to a factor) as we defined it is the first Chern form of O(1) equipped with a metric. Before we look at that, here are a couple of points :

- (1) Recall that if *L* is a holomorphic bundle, then there is a dual bundle *L*^{*}. It is defined set theoretically as $\cup_p L_p^*$ and the topology and complex structure are given by local trivialisations, i.e., if s_α are local holomorphic bases for *L*, then s_α^* defined as $s_\alpha^*(s_\alpha) = 1$ are local holomorphic bases of *L*^{*}. (So the transition functions are $\tilde{g}_{\alpha\beta} = 1/g_{\alpha\beta}$. (More generally, if *E* is a holomorphic (or even smooth for that matter) vector bundle, then $E^* = \bigcup_p E_p^*$ set theoretically. The topology and complex structure are given as : If $e_{\alpha,i}$ are local holomorphic bases for *E* then $e_\alpha^{*i}(e_{\alpha,j}) = \delta_j^i$ are holomorphic local bases of *E*^{*}. So the transition functions are $([g_{\alpha\beta}]^{-1})^T$.)
- (2) If *h* is a Hermitian metric on *L*, then there is a natural Hermitian metric *h*^{*} on *L*^{*} defined as *h*^{*}_α = 1/*h*_α. Indeed, *h*^{*}_α = *h*^{*}_β |*ğ*_{αβ}|² and hence *h*^{*} is a well-defined metric. Therefore, *c*₁(*h*^{*}, *L*^{*}) = -*c*₁(*h*, *L*).

There is an obvious Hermitian metric on $O(-1) \subset \mathbb{CP}^n \times \mathbb{C}^{n+1}$ coming from the Euclidean metric on \mathbb{C}^{n+1} . Locally, in the chart U_0 , if $s_0 \in O(-1) = (1, z^1, z^2, ...)$ is a local basis, then $h_\alpha = 1 + |z|^2$. Hence, $c_1(O(-1), h) = -\frac{\sqrt{-1}}{2\pi}\partial\bar{\partial}\ln(1+|z|^2)$ and $c_1(O(1), h^*) = \omega_{FS} = \frac{\sqrt{-1}}{2\pi}\partial\bar{\partial}\ln(1+|z|^2)$. The associated Hermitian metric is $h_{i\bar{j}} = \frac{1}{\pi} \frac{\partial^2}{\partial z^i \partial \bar{z}^j} \ln(1+|z|^2)$. Given the Fubini-Study metric, we can calculate the induced metric on submanifolds. Indeed,

Given the Fubini-Study metric, we can calculate the induced metric on submanifolds. Indeed, let $F(X^i)$ be a degree *d* homogeneous polynomial such that $\nabla F \neq 0$ on $S = F^{-1}(0)$. As we saw earlier, *S* is a compact complex submanifold of \mathbb{CP}^n . Assume without loss of generality that $\frac{\partial F}{\partial X^1} \neq 0$

near a point on *S* where $X^0 \neq 0$. Therefore, locally, $z^1 = f(z^2, \dots, z^n)$ and $F(1, f, z^2, \dots) = 0$. Now $\omega_{FS}|_S = \frac{\sqrt{-1}}{2\pi} \partial \bar{\partial} \ln(1+|f|^2 + \sum_{i=2} |z^i|^2)$, which equals

$$(1.1) \qquad \frac{1}{1+|f|^2+\sum_{i=2}|z^i|^2}\frac{\sqrt{-1}}{2\pi}\left(\partial f \wedge \bar{\partial}f + \sum_{i=2}dz^i \wedge d\bar{z}^i - \frac{\sum_{i,j}(\bar{f}\frac{\partial f}{\partial z^i} + \bar{z}^i)(f\frac{\partial f}{\partial \bar{z}^j} + z^j)dz^i \wedge d\bar{z}^j)}{1+|f|^2+\sum_{i=2}|z^i|^2}\right) = \frac{1}{1+|f|^2+\sum_{i=2}|z^i|^2}\frac{\sqrt{-1}}{2\pi}\left(\delta_{i\bar{j}} + a_i\bar{a}_j - c_i\bar{c}_j\right)dz^i \wedge d\bar{z}^j$$

Noting that $\omega^n = \det(h_{i\bar{i}})n! \frac{\sqrt{-1}}{2} dz^1 \wedge d\bar{z}^1 \dots$, we can calculate the volume form by computing the determinant of the above matrix.

Exercise : Calculate the determinant of the matrix above.

Before we go on further, we need another notion from vector bundles. If E is a rank-r vector bundle, then $\Lambda^r E$ is also a vector bundle where $\Lambda^r_p E_p = E_p \wedge E_p \wedge \dots$ If $e_{\alpha,i}$ is a local basis of E, then $\eta_{\alpha} = e_{\alpha,1} \wedge e_{\alpha,2} \dots e_{\alpha,r}$ is a local basis for $\Lambda^{r}E$. If $e_{\beta,i} = [g_{\alpha\beta}]_{i}^{j}e_{\alpha,j}$, then

Exercise : *Prove that* $\eta_{\beta} = \det(g_{\alpha\beta})\eta_{\alpha}$

Therefore, if *H* is a Hermitian metric on *E*, then det(H) is a Hermitian metric on det(E). In particular, det($T^{*1,0}M$) = K_M is called the canonical bundle of M and if ω is a Kähler form on M, then det(h)⁻¹ (which is basically $(\frac{\omega^n}{n!})^{-1}$) is a Hermitian metric on K_M . Thus, $c_1(K_M, \det(h)) = \frac{\sqrt{-1}}{2\pi} \partial \bar{\partial} \ln(\det(h))$.

Exercise : Compute $c_1(K_{\mathbb{CP}^n})$ with the metric induced from the Fubini-Study metric. A harder exercise is to compute $c_1(K_S)$ with the metric above. If you do the calculations correctly, you should get something like $c_1(K_{\mathbb{CP}}^n) = -(n+1)\omega_{FS}$, and $c_1(K_S) = (d-n-1)\omega_{FS} + \sqrt{-1}\partial\bar{\partial}\psi$ for some smooth globally defined function ψ.

The above exercises show that $K_{\mathbb{CP}^n}$ is a negative line bundle, and if *d* is large, then K_S is a positive line bundle (and hence K_S^* is negative). When d = n + 1, $[c_1(K_S)] = [0]$. Such an S (for example $(X^0)^5 + \dots + (X^4)^5 = 0$ called the Fermat quintic) is called a Calabi-Yau manifold. These manifolds are important in String theory. They have nice Kähler metrics with good curvature properties.

2. LECTURE 6 (KÄHLER CONNECTION AND CURVATURE)

Now we shall study the curvature of the Levi-Civita connection of Kähler manifolds. Recall that the Levi-Civita connection ∇ gives us a way to find the directional derivative of vector fields. $\nabla_X Y$ is the derivative of Y along X. It is uniquely determined by a few properties. More generally, given a smooth vector bundle E on a smooth manifold M, a connection is way to find the directional derivative of sections. It is defined as a map :

 ∇ : Smooth sections of E × Smooth vector fields on M \rightarrow Smooth sections of E

satisfying

- (1) $\nabla_{f_1X_1+f_2X_2}s = f_1\nabla_{X_1}s + f_2\nabla_{X_2}s$ where f_1, f_2 are smooth functions on *M*. (2) $\nabla_X(s_1 + s_2) = \nabla_X s_1 + \nabla_X s_2$.

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(3)
$$\nabla_X(fs) = X(f)s + f\nabla_X s.$$

If there is a Hermitian metric *H* on *E*, then ∇ is said to be metric compatible if $X(H(s_1, s_2)) = H(\nabla_X s_1, s_2) + H(s_1, \nabla_X s_2)$.

The Levi-Civita connection can be used to differentiate not just vector fields, but also induces a connection on T^*M by $X(\omega(Y)) = \nabla_X \omega(Y) + \omega(\nabla_X Y)$. The Christoffel symbols are defined as $\nabla_{\partial_k} \partial_j = \Gamma^i_{jk} \partial_i$. For the Levi-Civita connection there is a nasty formula for these beasts. But it is much simpler for calculations to note that the Christoffel symbols at *p* vanish in normal coordinates near *p*. For one-forms, $\nabla_{\partial_k} dx^j(\partial_i) = \partial_k (\delta^j_i) - \delta^j_l \Gamma^l_{ki}$ and hence $\nabla_{\partial_k} dx^j = -\Gamma^j_{ki} dx^i$. Using these two connections, we can talk about differentiating other tensors. For instance if $J = J^i_j dx^j \otimes \partial_i$, then $\nabla_X J$ is defined to be $\nabla_X J = X(J^i_i) dx^j \otimes \partial_i - J^i_i \Gamma^j_{ki} X^k dx^l \otimes \partial_i + J^i_i dx^j \otimes \Gamma^k_{il} X^l \partial_k$.

The Levi-Civita connection ∇ on a complex manifold can be extended complex linearly to a connection on $\mathbb{C}TM$. On a Kähler manifold, since there are holomorphic normal coordinates at every point p, $\nabla J = 0$ (because *J* has constant coefficients). We can define the Christoffel symbols in the z, \bar{z} basis as follows.

(2.1)
$$\nabla_{\partial_{z^k}} \partial_{z^j} = \Gamma^i_{jk} \partial_{z^i} + \Gamma^i_{jk} \partial_{\bar{z}^i}$$

and so on. Since $J\partial_{z^i} = \sqrt{-1}\partial_{z^i}$ and $\nabla J = 0$, we see that $J\nabla\partial_{z^i} = \sqrt{-1}\nabla\partial_{z^i}$. Therefore, $\nabla_{\partial_{z^k}}\partial_{z^i} \in T^{1,0}$ and hence $\Gamma^{\bar{i}}_{jk} = 0$. Now the torsion-free ness forces $\nabla_{\bar{i}}\partial_k = \nabla_k\partial_{\bar{i}}$ and hence both of them vanish. So the only surviving symbols are $\Gamma^i_{jk} = \Gamma^i_{kj}$ and $\Gamma^{\bar{i}}_{j\bar{k}} = \overline{\Gamma^i_{jk}}$. One can now calculate the Christoffel symbols. The Levi-Civita connection satisfies $\nabla g = 0$. Since $\nabla J = 0$, $\nabla h = 0$.

The upper indices indicate the inverse. So the matrix of 1-forms $\Gamma_k^{j} = [\partial h h^{-1}]_k^{j}$. The Riemann curvature tensor (extended C-linearly) is

(2.3)
$$(\nabla_k \nabla_{\bar{l}} - \nabla_{\bar{l}} \nabla_k) \partial_i = R_{i,k\bar{l}}^{-j-} \partial_j.$$

Exercise : *Prove that the other covariant derivatives commute.*

Upon computing

(2.4)
$$(\nabla_k \nabla_{\bar{l}} - \nabla_{\bar{l}} \nabla_k) \partial_i = -\nabla_{\bar{l}} \Gamma'_{ki} \partial_j$$
$$= -\partial_{\bar{l}} (\Gamma^j_{ki}) \partial_j = -\partial_{\bar{l}} (h^{j\bar{l}} \partial_k h_{i\bar{l}}).$$

In holomorphic normal coordinates, $R_{i,k\bar{l}}^{-l-}(p) = -\partial_{\bar{l}}\partial_k h_{i\bar{j}}(p)$. By the local $\partial\bar{\partial}$ lemma, since $h_{i\bar{j}} = \partial_{\bar{j}}\partial_i\phi$ for some smooth ϕ , we can interchange the derivatives to get many symmetries of the holomorphic Riemann curvature tensor. Recall that the Ricci curvature in usual Riemannian geometry is defined as $Ricc(Y, Z) = tr(X \to R(X, Y)Z)$. The Ricci tensor is symmetric.

In holomorphic normal coordinates, the Ricci tensor can be computed (extended C-linearly) as

$$Ricc_{i\bar{l}} = R_{i_{-}j\bar{l}}^{-J--}(p) = -\sum_{j} \partial_{\bar{l}}\partial_{j}h_{i\bar{j}}(p)$$
$$= -\sum_{j} \partial_{\bar{l}}\partial_{j}\partial_{i}\partial_{\bar{j}}\phi(p) = -\sum_{j} \partial_{\bar{j}}\partial_{j}\partial_{i}\partial_{\bar{l}}\phi(p) = -\sum_{j} \partial_{\bar{l}}\partial_{i}h_{j\bar{j}}(p)$$
$$= -\partial_{\bar{l}}\partial_{i}\ln(\det(h))(p).$$

The above calculation shows that Ricc(JY, JZ) = Ricc(Y, Z). Akin to ω , we define a Ricci form on a Kähler manifold as Ricc(JX, Y). It is clear that this form is a (1, 1)-form that is real (we will abuse notation and call this Ricci form also as the Ricci curvature sometimes). So the Ricci form is $\sqrt{-1}\overline{\partial}\partial \ln(\det(h))$. In other words it is simply $2\pi c_1(K_M^*)$.

Let us now connect the Ricci tensor in these complex coordinates (that is acting in a Hermitian manner on $T^{1,0}M$) to real coordinates. In almost the same way as h is related to g, the tensor $T(u, v) = Re(Ricc(Lu, Lv)) = Re(Ricc(\frac{u-\sqrt{-1}Ju}{2}, \frac{v+\sqrt{-1}Jv}{2}))$ is equal to $\frac{1}{2}Ricc(u, v)$. So the isomorphism gives a slightly different (by a factor of 2) Ricci tensor than the one we use in Riemannian geometry. The scalar curvature in Riemannian geometry is defined as the trace of the Ricci tensor.

Exercise : *Prove that the scalar curvature in the complex setting above differs from the usual one by a factor of* **4***.*

The Riemannian sectional curvatures are g(R(u, v)v, u). In the Kähler case, calculations above show that R(x, y, z, w) = R(x, y, Jz, Jw). For a unit vector x, we define the holomorphic sectional curvature as H(x) = R(x, Jx, Jx, x) and for two orthonormal unit vectors, x, y, the bisectional curvature is R(x, Jx, Jy, y).

Exercise : Show that the bisectional curvature is R(x, Jx, Jy, y) = R(x, y, y, x) + R(x, Jy, Jy, x) (thus justifying its name).

Note that $R_{j,i\bar{i}}^{-j,-} = R(\partial_i, \partial_{\bar{i}}, \partial_j, \partial_{\bar{j}})$ is the following using the usual isomorphism between $T^{1,0}$ and TM (and symmetries of the Riemann tensor).

(2.6)
$$R_{j,i\bar{i}}^{-j--} = \frac{1}{4}R(\partial_{x^i}, J\partial_{x^j}, J\partial_{x^j}, \partial_{x^j}).$$

Exercise : Show that all holomorphic sectional curvatures of \mathbb{C}^n , \mathbb{CP}^n , and \mathbb{D} are 0, positive constants, and negative constants respectively.

In the Riemannian case, when all the sectional curvatures are constant, the manifold is isometric to a quotient of Euclidean space, the Sphere, or Hyperbolic space. Akin to that, if all the holomorphic sectional curvatures are constant, the manifold is biholomorphically isometric to a quotient of \mathbb{C}^n , \mathbb{CP}^n , or \mathbb{D} .

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