## NOTES FOR 31 OCT (THURSDAY)

## 1. Recap

- (1) Examples of inner products. Defined norms and gave examples/non-examples.
- (2) Discussed when norms arise out of inner products (polarisation identity). Indeed, for real vector spaces,  $\langle v, w \rangle := \frac{\|v+w\|^2 - \|v-w\|^2}{4}$  is an inner product. It is easy to see that it is positivedefinite and Hermitian. The bilinearity can be proved using the polarisation identity. Indeed, (a)  $\langle v, w_1 + w_2 \rangle = \langle v, w_1 \rangle + \langle v, w_2 \rangle$ : It is easy to prove that  $\langle v, w_1 + w_2 \rangle = 2 \langle v, w_1 \rangle - \langle v, w_1 - w_2 \rangle$ . Indeed,

$$4\langle v, w_1 + w_2 \rangle = ||v + w_1 + w_2||^2 - ||v - w_1 - w_2||^2$$
  
= 2(||v + w\_1||^2 + ||w\_2||^2) - ||v + w\_1 - w\_2||^2 - 2(||v - w\_1||^2 + ||w\_2||^2) + ||v - w\_1 + w\_2||^2  
(1.1)  
= 8\langle v, w\_1 \rangle - 4\langle v, w\_1 - w\_2 \rangle.

Applying it to  $w_2$ , the same expression equals  $2\langle v, w_2 \rangle - \langle v, w_2 - w_1 \rangle$ . Adding the expressions, we get the result.

- (b)  $\langle \lambda v, w \rangle = \lambda \langle v, w \rangle$ : Firstly, we prove that if  $||v_i v|| \to 0$ , then  $||v_i|| \to ||v||$ . Indeed,  $||v|| - ||v_i|| \le ||v - v_i||$  and likewise  $||v_i|| - ||v|| \le ||v_i - v|| = ||v - v_i||$ . Therefore, if  $r \in \mathbb{R}$ and  $q_i \in \mathbb{Q}$  such that  $q_i \to r$ , then  $||v + q_i w - (v + rw)|| = |q_i - r|||w|| \to 0$  and hence  $||v + q_i w||^2 \rightarrow ||v + rw||^2$ . Hence, it is enough to prove this property for rational  $\lambda$ . Firstly, it is trivial to see that  $\langle -v, w \rangle = -\langle v, w \rangle$ . Hence, it is enough to prove it for positive rationals  $\frac{p}{q}$ . Suppose we prove it for natural numbers, then  $\langle q \frac{v}{q}, w \rangle = q \langle \frac{v}{q}, w \rangle$ . Hence,  $\langle \frac{p}{a}v, w \rangle = \frac{\dot{p}}{a} \langle v, w \rangle$ . To prove it for naturals, we can easily induct on  $\lambda$ .
- (3) Looked at inner products in bases. Defined Hermitian and positive-definite matrices.

## 2. INNER PRODUCTS

(1) The matrix  $A = \begin{bmatrix} -2 & \sqrt{-1} \\ -\sqrt{-1} & 1 \end{bmatrix}$  is not positive-definite. (Why?) More generally, if  $A = \begin{bmatrix} a & b \\ \bar{b} & c \end{bmatrix}$  is positive-definite (where *a*, *c* are real), then  $\alpha = a|v_1|^2 + c|v_2|^2 + \bar{v}_1bv_2 + \bar{v}_2\bar{b}v_1 \ge bv_1$  $0 \forall v \neq 0$ . Thus, a, c > 0. Moreover,  $\alpha = |\sqrt{av_1} + \frac{b}{\sqrt{a}}v_2|^2 + |v_2|^2(-\frac{|b|^2}{a} + c) \ge 0$  iff  $ac - b^2 > 0$ . That is, tr(A) > 0, det(A) > 0. Actually these two conditions are sufficient. (Why ?)

A related definition is this : An operator  $T: V \to V$  is called Hermitian if  $\langle v, Tw \rangle = \langle Tv, w \rangle$ . Let  $e_i$  be a basis and *T* be the matrix of *T*. Then,  $(Tw)^{\dagger}Hv = w^{\dagger}HTv$ . Thus,  $w^{\dagger}T^{\dagger}Hv = w^{\dagger}HTv$ . So, for instance, if  $V = \mathbb{C}^n$  and  $\langle \rangle$  is the standard inner product, then  $T^{\dagger} = T$  as a matrix.

We have a beautiful theorem at this point (the uncertainty principle).

**Theorem 2.1.** Let V be a finite-dimensional complex vector space endowed with an inner product  $\langle , \rangle$ . Let  $A,B: V \rightarrow V$  be Hermitian operators and let  $[A,B] = AB - BA: V \rightarrow V$  be their commutator. For any Hermitian operator T and a vector  $\psi \in V$ , define the expectation value  $E_{\psi}(T) = (\psi, T\psi)$  and the standard deviation  $\Delta_{\psi}T = \sqrt{E((T - E(T)I)^2)}$ . Then,  $\Delta_{\psi}A\Delta_{\psi}B \ge \frac{1}{2}|E([A, B])|$ .

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This theorem is much more subtle in infinite-dimensions (and not true in general !) A particular infinite-dimensional version (where *A* corresponds to multiplication by *x* and *B* to  $\frac{d}{dx}$ ) is called Heisenberg's uncertainty principle in quantum mechanics. The proof of Theorem 2.1 is as follows.

*Proof.* Note that if *T* is Hermitian, so is T - cI where *c* is a real number. Also note that,  $E_{\psi}(T) = \overline{(\psi, T\psi)} = (T\psi, \psi) = (\psi, T\psi) = E_{\psi}(T)$ . So the expectation value is always real. Moreover, if *T* is Hermitian, so is  $T^2$ . (So the standard deviation is always real too.) Moreover, if *A*, *B* are Hermitian, then  $\sqrt{-1}[A, B]$  is also Hermitian. (Why?)

$$\langle \Delta A \Delta B \rangle^2 = \langle \psi, (A - E(A)I)^2 \psi \rangle \langle \psi, (B - E(B)I)^2 \psi \rangle = \langle \psi(A - E(A)I), (A - E(A)I)\psi \rangle \langle \psi(B - E(B)I), (B - E(B)I)\psi \rangle$$
(2.1)

after simplification.

Here is an important definition : If  $v, w \in V$ , they are said to be orthogonal if  $\langle v, w \rangle = 0$ . If *S* is a set of vectors, *S* is said to be orthogonal if any pair of vectors is orthogonal. An orthonormal set *S* is an orthogonal set where ||v|| = 1 for all  $v \in S$ .

Lemma 2.2. An orthogonal set of non-zero vectors is linearly independent.

*Proof.* Suppose  $v_1, \ldots, v_k$  are orthogonal and  $\sum_i c_i v_i = 0$ . Then  $\sum_i \langle c_i v_i, v_j \rangle = 0$ . Thus,  $c_j ||v_j||^2 = 0$  and hence  $c_j = 0 \forall j$ .

As a corollary of the proof (rather than the statement), if  $\beta$  is a linear combination of some orthogonal vectors  $v_i$ , then  $\beta = \sum_k \frac{\langle \beta, v_k \rangle}{\|v_k\|^2} v_k$ . Here are examples and non-examples. Also, the maximum number of orthogonal vectors is the dimension of *V*.

- (1) The standard bases in  $\mathbb{R}^n$  and  $\mathbb{C}^n$  with respect to the standard inner products are orthonormal.
- (2) The vector (x, y) is orthogonal to (y, -x). (Rotation by 90 degrees.)
- (3) The matrices  $(E^{pq})_{ij} = \delta_{ip}\delta_{jq}$  form an orthonormal basis.
- (4) The vectors *x*,  $x^2$  are not orthogonal under the  $L^2$  inner product. However,  $\sqrt{2}\cos(2\pi nx)$ ,  $\sqrt{2}\sin(2\pi nx)$  are orthonormal.

The following fundamental result shows that the maximum number of orthogonal vectors is actually equal to the dimension : Let *V* be a finite-dimensional inner product space, and let  $w_1, \ldots, w_n$  be a linearly independent set. Then there exists an orthonormal basis  $v_1, \ldots, v_n$  of the subspace spanned by  $w_1, \ldots, w_n$ . (As a corollary, evert finite-dimensional inner product space has an orthonormal basis.)

The proof is called "Gram-Schmidt orthogonalisation". Let  $v_1 = \frac{w_1}{\|w_1\|}$ . Assume that we have defined  $v_1, \ldots, v_k$ . Then define  $\tilde{v}_{k+1} = w_{k+1} - \sum_{i=1}^k \langle w_{k+1}, v_i \rangle v_i$  and  $v_{k+1} = \frac{\tilde{v}_{k+1}}{\|\tilde{v}_{k+1}\|}$ . Note that  $\langle v_{k+1}, v_j \rangle = 0$  for all  $1 \le j \le k$ . Thus,  $v_i$  are orthonormal (and hence linearly independent). Also,  $w_{k+1}$  is a linear combination of the  $v_i$ . We are done by induction.

The point of orthonormal bases is that in such a basis,  $H_{ij} = \langle e_i, e_j \rangle = \delta_{ij}$  and hence  $\langle v, w \rangle = v^T \bar{w}$ : exactly the Euclidean expression ! What does this mean for Hermitian positive-definite matrices. For that, how does  $H_{ij}$  change if one changes the basis ? That is,  $H_{new,ij} = \langle e_{new,i}, e_{new,j} \rangle =$ 

 $\langle (P^{-1})_{ki}e_{old,k}, (\bar{P}^{-1})_{lj}e_{old,l} \rangle = P_{ki}^{-1}\bar{P}_{lj}^{-1}H_{old,kl}$ , implying that  $P^{T}H_{new}\bar{P} = H_{old}$  where  $\vec{v}_{new} = P\vec{v}_{old}$ . In other words, given a Hermitian positive-definite matrix H, Gram-Schmidt produces an invertible matrix P such that  $H = P^{T}\bar{P} = Q^{\dagger}Q$  (where  $Q = \bar{P}$ ). Moreover, P, Q are actually upper triangular with positive diagonal entries ! (Why ?) This decomposition is called the Cholesky decomposition. It is unique ! Indeed, if  $H = Q^{\dagger}Q = L^{\dagger}L$ , then  $Q^{\dagger} = L^{\dagger}LQ^{-1}$ , i.e.,  $(L^{\dagger})^{-1}Q^{\dagger} = LQ^{-1}$ , i.e., *Lower* = *Upper*. Hence, both are diagonal. Hence L = DQ where D is diagonal (with positive diagonal entries). So  $Q^{\dagger}Q = Q^{\dagger}D^{2}Q$  and hence D = I because Q has positive diagonal entries (and is hence invertible). Note that if there is an efficient way to compute the Cholesky decomposition, then we can solve linear equations Hx = b quickly. Indeed, solve  $Q^{\dagger}y = b$  and then Qx = y quickly (they are triangular matrices and hence back/forward substitution does the job).