

MA 229/MA 235 - Lecture 22

IISc

Recap

- Tensor fields and Riemannian metrics.

- Tensor fields and Riemannian metrics.
- Elementary alternating tensors.

Change of top forms under a map

Change of top forms under a map

- If V is an n -dimensional v. space,

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form.

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof:

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V .

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V . We note that $\omega = c\epsilon^{12\dots n}$ for some c .

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V . We note that $\omega = ce^{12\dots n}$ for some c . Since both sides are top forms,

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V . We note that $\omega = c\epsilon^{12\dots n}$ for some c . Since both sides are top forms, we only need to check when $v_j = e_j$.

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V . We note that $\omega = c\epsilon^{12\dots n}$ for some c . Since both sides are top forms, we only need to check when $v_j = e_j$. The RHS is

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V . We note that $\omega = c\epsilon^{12\dots n}$ for some c . Since both sides are top forms, we only need to check when $v_j = e_j$. The RHS is $\det(T)c$.

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V . We note that $\omega = c\epsilon^{12\dots n}$ for some c . Since both sides are top forms, we only need to check when $v_j = e_j$. The RHS is $\det(T)c$. The LHS is

Change of top forms under a map

- If V is an n -dimensional v. space, then elements of $\Lambda^n(V^*)$ are called “top forms” (because there are no forms beyond them).
- Let $T : V \rightarrow V$ be a linear map and ω be a top form. Then $\omega(Tv_1, \dots, Tv_n) = \det(T)\omega(v_1, \dots, v_n)$.
- Proof: Let e_1, \dots, e_n be a basis of V . We note that $\omega = c\epsilon^{12\dots n}$ for some c . Since both sides are top forms, we only need to check when $v_i = e_i$. The RHS is $\det(T)c$. The LHS is $c \det(Te_1, \dots, Te_n) = c \det(T)$ (why?). Hence we are done. □

Wedge product: Motivation

Wedge product: Motivation

- How does one generalise the cross product?

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why:

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions.

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How:

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How: Naively,

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How: Naively, $(a \times b)_{ij} = a_i b_j - a_j b_i$, i.e.,

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How: Naively, $(a \times b)_{ij} = a_i b_j - a_j b_i$, i.e., it is a 2-form!

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How: Naively, $(a \times b)_{ij} = a_i b_j - a_j b_i$, i.e., it is a 2-form! So perhaps we can talk of the

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How: Naively, $(a \times b)_{ij} = a_i b_j - a_j b_i$, i.e., it is a 2-form! So perhaps we can talk of the “cross product” (we shall call it the wedge product)

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How: Naively, $(a \times b)_{ij} = a_i b_j - a_j b_i$, i.e., it is a 2-form! So perhaps we can talk of the “cross product” (we shall call it the wedge product) of a k -form with an l -form

Wedge product: Motivation

- How does one generalise the cross product? Why must one generalise it?
- Why: To talk perhaps of signed volumes in higher dimensions. Possibly to generalise the notion of curl $\nabla \times$ to formulate an FTC.
- How: Naively, $(a \times b)_{ij} = a_i b_j - a_j b_i$, i.e., it is a 2-form! So perhaps we can talk of the “cross product” (we shall call it the wedge product) of a k -form with an l -form to get $\omega \wedge \eta$ - a $(k + l)$ -form.

Wedge product: Definition

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$,

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance,

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}.$

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So
$$\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1.$$

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So
$$\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1.$$
- Why the weird numerical factor?

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then

$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$

- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So $\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1$.

- Why the weird numerical factor?

$$\begin{aligned} (\epsilon^1 \wedge \epsilon^2) \wedge \epsilon^3 &= \frac{3!}{2!1!} \text{Alt}((\epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1) \otimes \epsilon^3) = \\ &= 3 \text{Alt}(\epsilon^1 \otimes \epsilon^2 \otimes \epsilon^3 - \epsilon^2 \otimes \epsilon^1 \otimes \epsilon^3) = \\ &= \sum_{\sigma} \text{sgn}(\sigma) \epsilon^{\sigma(1)} \otimes \epsilon^{\sigma(2)} \otimes \epsilon^{\sigma(3)} = \epsilon^{1,2,3} = \epsilon^1 \wedge (\epsilon^2 \wedge \epsilon^3). \end{aligned}$$

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So
$$\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1.$$
- Why the weird numerical factor?
$$\begin{aligned}(\epsilon^1 \wedge \epsilon^2) \wedge \epsilon^3 &= \frac{3!}{2!1!} \text{Alt}((\epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1) \otimes \epsilon^3) = \\ &= 3 \text{Alt}(\epsilon^1 \otimes \epsilon^2 \otimes \epsilon^3 - \epsilon^2 \otimes \epsilon^1 \otimes \epsilon^3) = \\ &= \sum_{\sigma} \text{sgn}(\sigma) \epsilon^{\sigma(1)} \otimes \epsilon^{\sigma(2)} \otimes \epsilon^{\sigma(3)} = \epsilon^{1,2,3} = \epsilon^1 \wedge (\epsilon^2 \wedge \epsilon^3).\end{aligned}$$
 Bear in mind that some old books don't have this factor.

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So
$$\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1.$$
- Why the weird numerical factor?
$$\begin{aligned}(\epsilon^1 \wedge \epsilon^2) \wedge \epsilon^3 &= \frac{3!}{2!1!} \text{Alt}((\epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1) \otimes \epsilon^3) = \\ &= 3 \text{Alt}(\epsilon^1 \otimes \epsilon^2 \otimes \epsilon^3 - \epsilon^2 \otimes \epsilon^1 \otimes \epsilon^3) = \\ &= \sum_{\sigma} \text{sgn}(\sigma) \epsilon^{\sigma(1)} \otimes \epsilon^{\sigma(2)} \otimes \epsilon^{\sigma(3)} = \epsilon^{1,2,3} = \epsilon^1 \wedge (\epsilon^2 \wedge \epsilon^3).\end{aligned}$$
 Bear in mind that some old books don't have this factor.
- More generally,

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So
$$\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1.$$
- Why the weird numerical factor?
$$\begin{aligned}(\epsilon^1 \wedge \epsilon^2) \wedge \epsilon^3 &= \frac{3!}{2!1!} \text{Alt}((\epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1) \otimes \epsilon^3) = \\ &= 3 \text{Alt}(\epsilon^1 \otimes \epsilon^2 \otimes \epsilon^3 - \epsilon^2 \otimes \epsilon^1 \otimes \epsilon^3) = \\ &= \sum_{\sigma} \text{sgn}(\sigma) \epsilon^{\sigma(1)} \otimes \epsilon^{\sigma(2)} \otimes \epsilon^{\sigma(3)} = \epsilon^{1,2,3} = \epsilon^1 \wedge (\epsilon^2 \wedge \epsilon^3).\end{aligned}$$
 Bear in mind that some old books don't have this factor.
- More generally, Theorem:

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So
$$\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1.$$
- Why the weird numerical factor?
$$\begin{aligned}(\epsilon^1 \wedge \epsilon^2) \wedge \epsilon^3 &= \frac{3!}{2!1!} \text{Alt}((\epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1) \otimes \epsilon^3) = \\ &= 3 \text{Alt}(\epsilon^1 \otimes \epsilon^2 \otimes \epsilon^3 - \epsilon^2 \otimes \epsilon^1 \otimes \epsilon^3) = \\ &= \sum_{\sigma} \text{sgn}(\sigma) \epsilon^{\sigma(1)} \otimes \epsilon^{\sigma(2)} \otimes \epsilon^{\sigma(3)} = \epsilon^{1,2,3} = \epsilon^1 \wedge (\epsilon^2 \wedge \epsilon^3).\end{aligned}$$
 Bear in mind that some old books don't have this factor.
- More generally, Theorem: For any two multi-indices I, J ,

Wedge product: Definition

- Suppose $\omega \in \Lambda^k(V^*)$ and $\eta \in \Lambda^l(V^*)$, then
$$\omega \wedge \eta := \frac{(k+l)!}{k!l!} \text{Alt}(\omega \otimes \eta).$$
- So for instance, $\epsilon^1 \wedge \epsilon^2 = \epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1 = \epsilon^{1,2}$. So
$$\epsilon^1 \wedge \epsilon^2(v, w) = v^1 w^2 - v^2 w^1.$$
- Why the weird numerical factor?
$$\begin{aligned}(\epsilon^1 \wedge \epsilon^2) \wedge \epsilon^3 &= \frac{3!}{2!1!} \text{Alt}((\epsilon^1 \otimes \epsilon^2 - \epsilon^2 \otimes \epsilon^1) \otimes \epsilon^3) = \\ &= 3 \text{Alt}(\epsilon^1 \otimes \epsilon^2 \otimes \epsilon^3 - \epsilon^2 \otimes \epsilon^1 \otimes \epsilon^3) = \\ &= \sum_{\sigma} \text{sgn}(\sigma) \epsilon^{\sigma(1)} \otimes \epsilon^{\sigma(2)} \otimes \epsilon^{\sigma(3)} = \epsilon^{1,2,3} = \epsilon^1 \wedge (\epsilon^2 \wedge \epsilon^3).\end{aligned}$$
 Bear in mind that some old books don't have this factor.
- More generally, Theorem: For any two multi-indices I, J ,
$$\epsilon^I \wedge \epsilon^J = \epsilon^{IJ}.$$

Proof of Theorem

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$.

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices,

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J ,

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices,

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (any permutation of it does not need to be checked),

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (any permutation of it does not need to be checked), then $\epsilon^{IJ}(e_P) = 1$.

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (any permutation of it does not need to be checked), then $\epsilon^{IJ}(e_P) = 1$. For the LHS,

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (any permutation of it does not need to be checked), then $\epsilon^{IJ}(e_P) = 1$. For the LHS,
$$\epsilon^I \wedge \epsilon^J(e_P) = \frac{1}{k!l!} \sum_{\sigma} \text{sgn}(\sigma) \epsilon^I(e_{p_{\sigma(1)}}, \dots, e_{p_{\sigma(k)}}) \epsilon^J(e_{p_{\sigma(k+1)}}, \dots).$$

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (any permutation of it does not need to be checked), then $\epsilon^{IJ}(e_P) = 1$. For the LHS,
$$\epsilon^I \wedge \epsilon^J(e_P) = \frac{1}{k!l!} \sum_{\sigma} \text{sgn}(\sigma) \epsilon^I(e_{p_{\sigma(1)}}, \dots, e_{p_{\sigma(k)}}) \epsilon^J(e_{p_{\sigma(k+1)}}, \dots).$$
The only surviving terms

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (any permutation of it does not need to be checked), then $\epsilon^{IJ}(e_P) = 1$. For the LHS,
$$\epsilon^I \wedge \epsilon^J(e_P) = \frac{1}{k!l!} \sum_{\sigma} \text{sgn}(\sigma) \epsilon^I(e_{p_{\sigma(1)}}, \dots, e_{p_{\sigma(k)}}) \epsilon^J(e_{p_{\sigma(k+1)}}, \dots).$$
The only surviving terms are of the type $\sigma = \tau\psi$.

Proof of Theorem

- Let $P = (p_1, \dots, p_{k+l})$. We need to show that $\epsilon^I \wedge \epsilon^J(e_{p_1}, \dots) = \epsilon^{IJ}(e_{p_1}, \dots)$ for all P .
- If P has repeated indices, by alternating-ness, both sides are zero.
- If P has an index that does not occur in I and J , then both sides are zero (why?)
- If P has no repeated indices, and $P = IJ$ (any permutation of it does not need to be checked), then $\epsilon^{IJ}(e_P) = 1$. For the LHS,

$$\epsilon^I \wedge \epsilon^J(e_P) = \frac{1}{k!l!} \sum_{\sigma} \text{sgn}(\sigma) \epsilon^I(e_{p_{\sigma(1)}}, \dots, e_{p_{\sigma(k)}}) \epsilon^J(e_{p_{\sigma(k+1)}}, \dots).$$

The only surviving terms are of the type $\sigma = \tau\psi$. Thus

$$\epsilon^I \wedge \epsilon^J(e_P) = \frac{1}{k!l!} \sum_{\tau} \text{sgn}(\tau) \epsilon^I(e_{\tau(I)}) \sum_{\psi} \text{sgn}(\psi) \epsilon^J(e_{\psi(J)}) = 1$$

(why?)

Properties of the wedge product

Properties of the wedge product

- Bilinearity (Proof:

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof:

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof:

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof:

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof:

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution:

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form is a wedge of 1-forms (

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form is a wedge of 1-forms (such forms are called decomposable).

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form is a wedge of 1-forms (such forms are called decomposable).
- In \mathbb{R}^3 there is

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form is a wedge of 1-forms (such forms are called decomposable).
- In \mathbb{R}^3 there is an identification of 2-forms with \mathbb{R}^3 itself

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form is a wedge of 1-forms (such forms are called decomposable).
- In \mathbb{R}^3 there is an identification of 2-forms with \mathbb{R}^3 itself and hence the cross product makes sense (

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form is a wedge of 1-forms (such forms are called decomposable).
- In \mathbb{R}^3 there is an identification of 2-forms with \mathbb{R}^3 itself and hence the cross product makes sense (but the choice of this identification

Properties of the wedge product

- Bilinearity (Proof: Checking the definition).
- Associativity (Proof: Check for basis vectors).
- $\omega \wedge \eta = (-1)^{kl} \eta \wedge \omega$ (Proof: Check for basis vectors).
- $\epsilon^{i_1} \wedge \epsilon^{i_2} \dots = \epsilon^I$ (Proof: Inductively follows from associativity and the above theorem)
- $\omega^1 \wedge \omega^2 \dots \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ (Proof: Induction and checking for the elementary ones).
- It turns out that the wedge product is the unique such map satisfying the above properties.
- Caution: Not every form is a wedge of 1-forms (such forms are called decomposable).
- In \mathbb{R}^3 there is an identification of 2-forms with \mathbb{R}^3 itself and hence the cross product makes sense (but the choice of this identification matters. Sometimes $\vec{a} \times \vec{b}$ is called a pseudovector).

Differential forms on manifolds

- We can take the disjoint union

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart.

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M ,

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index,

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases.

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases. A smooth section of this bundle of differential k -forms

Differential forms on manifolds

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases. A smooth section of this bundle of differential k -forms is called a k -form field (or simply a k -form).

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases. A smooth section of this bundle of differential k -forms is called a k -form field (or simply a k -form). Such an object is a smooth linear combination

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases. A smooth section of this bundle of differential k -forms is called a k -form field (or simply a k -form). Such an object is a smooth linear combination of dx^I .

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases. A smooth section of this bundle of differential k -forms is called a k -form field (or simply a k -form). Such an object is a smooth linear combination of dx^I .
- We can define the wedge product of forms.

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases. A smooth section of this bundle of differential k -forms is called a k -form field (or simply a k -form). Such an object is a smooth linear combination of dx^I .
- We can define the wedge product of forms. Moreover, functions are treated as 0-forms.

- We can take the disjoint union $\Lambda^k T^*M = \cup_{p \in M} \Lambda^k T_p^*M$.
- Suppose (U, x) is a chart. Since $\epsilon^i = dx^i$ is a basis for T_p^*M , whenever I is an increasing multi-index, $\epsilon^I = dx^{i_1} \wedge dx^{i_2} \dots$ is a basis for $\Lambda^k T_p^*M$.
- We can give $\Lambda^k T^*M$ a vector bundle structure using these coordinate bases. A smooth section of this bundle of differential k -forms is called a k -form field (or simply a k -form). Such an object is a smooth linear combination of dx^I .
- We can define the wedge product of forms. Moreover, functions are treated as 0-forms. $f \wedge \eta = f\eta$ if f is a function.

Pullback and wedge product

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth.

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows:

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N ,

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions,

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.
- Recall that $F^*df = dF^*f$.

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.
- Recall that $F^*df = dF^*f$. Moreover, if $\omega = \omega_i dx^i$, then $F^*\omega = \omega_i \circ F dF^i$.

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.
- Recall that $F^*df = dF^*f$. Moreover, if $\omega = \omega_i dx^i$, then $F^*\omega = \omega_i \circ F dF^i$.
- For k -forms,

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.
- Recall that $F^*df = dF^*f$. Moreover, if $\omega = \omega_i dx^i$, then $F^*\omega = \omega_i \circ F dF^i$.
- For k -forms, the pullback is \mathbb{R} -linear (why?).

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.
- Recall that $F^*df = dF^*f$. Moreover, if $\omega = \omega_i dx^i$, then $F^*\omega = \omega_i \circ F dF^i$.
- For k -forms, the pullback is \mathbb{R} -linear (why?).
- $F^*(\omega \wedge \eta) = F^*\omega \wedge F^*\eta$ (why?)

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.
- Recall that $F^*df = dF^*f$. Moreover, if $\omega = \omega_i dx^i$, then $F^*\omega = \omega_i \circ F dF^i$.
- For k -forms, the pullback is \mathbb{R} -linear (why?).
- $F^*(\omega \wedge \eta) = F^*\omega \wedge F^*\eta$ (why?)
- Using this property,

Pullback and wedge product

- Suppose $F : M \rightarrow N$ is smooth. We can define the pullback as follows: If ω is a k -form field on N , $F^*\omega$ is a k -form field on M such that $(F^*\omega)_p(v_1, \dots) = \omega_{F(p)}((F_*)_p(v_1), \dots)$.
- For functions, by definition, $F^*f(p) = f(F(p)) = f \circ F(p)$.
- Recall that $F^*df = dF^*f$. Moreover, if $\omega = \omega_i dx^i$, then $F^*\omega = \omega_i \circ F dF^i$.
- For k -forms, the pullback is \mathbb{R} -linear (why?).
- $F^*(\omega \wedge \eta) = F^*\omega \wedge F^*\eta$ (why?)
- Using this property, we can calculate pullbacks for several examples.

Pullback for top-forms

Pullback for top-forms

- Suppose $\omega = f dy^1 \dots dy^n$,

Pullback for top-forms

- Suppose $\omega = fdy^1 \dots dy^n$, then $F^*\omega = F^* f dF^1 \dots dF^n$, which

- Suppose $\omega = f dy^1 \dots dy^n$, then $F^*\omega = F^* f dF^1 \dots dF^n$, which when acted on $\frac{\partial}{\partial x^1}, \dots$ is

- Suppose $\omega = f dy^1 \dots dy^n$, then $F^*\omega = F^* f dF^1 \dots dF^n$, which when acted on $\frac{\partial}{\partial x^1}, \dots$ is $F^* f \det\left(\frac{\partial F^i}{\partial x^j}\right) dx^1 \dots dx^n$.

Pullback for top-forms

- Suppose $\omega = f dy^1 \dots dy^n$, then $F^*\omega = F^* f dF^1 \dots dF^n$, which when acted on $\frac{\partial}{\partial x^1}, \dots$ is $F^* f \det\left(\frac{\partial F^i}{\partial x^j}\right) dx^1 \dots dx^n$.
- In particular, $d\tilde{x}^1 \wedge \dots = \det\left(\frac{\partial \tilde{x}^i}{\partial x^j}\right) dx^1 \wedge \dots$