

MA 235 - Lecture 25

1 Recap

1. Sketch of proof of change of variables.
2. Example.
3. Definition of orientability using charts for $\dim(M) > 1$ or $\partial M = \emptyset$.
4. Equivalence with the presence of nowhere vanishing top-forms.
5. Equivalence relations of orientations and presence of only two equivalence classes on connected manifolds.
6. Definition using nowhere vanishing top-forms for $\dim(M) = 1$ and $\partial M \neq \emptyset$.

2 Orientability

Examples of orientable manifolds:

- \mathbb{R}^n is orientable.
- A codimension-0 submanifold $D \subset M$ is orientable if M is so: Suppose ω is an orientation form on M , then $i^*\omega$ is one on D .
- If M, N are orientable, then so is $M \times N$ with the “product orientation”: Take $\pi_1^*\omega_1 \wedge \pi_2^*\omega_2$ as the orientation form.
- Suppose $F : M \rightarrow N$ (where M, N are connected with $\dim > 0$) is a smooth map such that F_* is invertible at all points. If $(F_*)_p$ is orientation-preserving at all points, then F is said to be orientation-preserving. Otherwise it is said to be orientation-reversing. Given an orientation $[\omega]$ on N , there is a unique orientation (called the pullback orientation) such that F is orientation-preserving: $[F^*\omega]$ does the job (why?). If $[\eta]$ is any other such orientation, then $\omega(F_*e_1, F_*e_2, \dots)/\eta(e_1, \dots) > 0$ (why?). Thus $[\eta] = [F^*\omega]$.
- Hypersurfaces in M : Suppose $(M, [\omega])$ is an oriented smooth manifold with or without boundary, and $S \subset M$ is a smooth hypersurface (without boundary that does not intersect ∂M). Suppose \vec{N} is a section of TM restricted to S such that \vec{N} is nowhere tangent to S . Then S is orientable with the orientation given by

the form $(e_1, \dots, e_{n-1}) \rightarrow \omega(\vec{N}, e_1, \dots)$ (Indeed, \vec{N}, e_1, \dots are linearly independent and hence $\omega(\vec{N}, \dots) \neq 0$.) For instance, S^n can be oriented this way.

Induced orientation on ∂M : Proposition: Let M be an oriented smooth n -fold with boundary ($n \geq 1$). Then ∂M is orientable, and all "outward pointing" vector fields (Smooth sections X of TM -restricted-to- ∂M such that $X = c_n \frac{\partial}{\partial x^n} + \dots$ where $c_n < 0$ whenever (x^1, \dots) is a boundary chart) along ∂M determine the same orientation.

Proof: Firstly, ∂M is a smooth hypersurface: Cover it with boundary charts for M . Now the first $n - 1$ coordinates provide charts for ∂M (why?). Secondly, there is a smooth outward pointing vector field on ∂M : Take a partition-of-unity and define $X = \sum \rho_\alpha \frac{\partial}{\partial x_\alpha^n}$. Thirdly, use the induced orientation $\omega(X_{outward}, \dots)$. Fourthly, suppose X_1, X_2 are two such outward fields, then $\omega(X_1, \frac{\partial}{\partial x^1}, \dots) = c_n \omega(\frac{\partial}{\partial x^n}, \dots)$ which is a positive multiple of $\omega(X_2, \dots)$ (why?) \square

As an example, the orientation on \mathbb{H}^n is the same orientation as that of \mathbb{R}^{n-1} only when n is even (why?).

Non-examples:

- It turns out that $\mathbb{R}P^n$ is orientable iff n is odd. For instance, $\mathbb{R}P^2$ is not orientable.
- The Möbius line bundle is not orientable.

3 Orientation and integration of top forms

Proposition: Suppose D, E are domains of integration in \mathbb{R}^n or \mathbb{H}^n and $G : \bar{D} \rightarrow \bar{E}$ is a smooth map that is a diffeo from D to E . If ω is a smooth top form on \bar{E} , then $\int_D G^* \omega = \int_E \omega$ if G is orientation-preserving and $-\int_E \omega$ if G otherwise.

Proof: Follows from the change of variables formula (how?) \square

Proposition: Suppose U, V are open subsets in \mathbb{R}^n or \mathbb{H}^n and $G : U \rightarrow V$ is a diffeo. If ω is a smooth top form with compact support in V , then $\int_U G^* \omega = \int_V \omega$ if G is orientation-preserving and $-\int_V \omega$ if G otherwise.

Proof: Let $E \subset \bar{E} \subset V$ be a domain of integration containing the support of ω . (Why does it exist?) Now $G^{-1}(E)$ is a domain of integration too (why?) Hence we are done (why?) \square