# Lecture 9 - UM 102 (Spring 2021) 

Vamsi Pritham Pingali

IISc

## Recap

- Proved an important criterion


## Recap

- Proved an important criterion for invertibility, i.e.,


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full.
- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if
- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution
- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution for every $b$.


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution for every $b$. If $A x=b$ has


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution for every $b$. If $A x=b$ has more than one solution,


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution for every $b$. If $A x=b$ has more than one solution, then it has infinitely many.


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution for every $b$. If $A x=b$ has more than one solution, then it has infinitely many.
- Discussed the Gauss-Jordan method


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution for every $b$. If $A x=b$ has more than one solution, then it has infinitely many.
- Discussed the Gauss-Jordan method to compute inverses and


## Recap

- Proved an important criterion for invertibility, i.e., a square matrix $A$ is invertible if and only if its rank is full. $A$ is invertible if and only if $A x=0$ has a trivial solution if and only if $A x=b$ has a solution for every $b$. If $A x=b$ has more than one solution, then it has infinitely many.
- Discussed the Gauss-Jordan method to compute inverses and illustrated it with an example.


## A general simple linear system

## A general simple linear system

- Suppose we consider


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$.


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$ then unless $e d-b f=0, a f-c e=0$,


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$ then unless $e d-b f=0, a f-c e=0$, we cannot solve the equations.


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$ then unless ed $-b f=0, a f-c e=0$, we cannot solve the equations. If $a d-b c \neq 0$,


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$ then unless $e d-b f=0, a f-c e=0$, we cannot solve the equations. If $a d-b c \neq 0$, we have a unique solution.


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$ then unless $e d-b f=0, a f-c e=0$, we cannot solve the equations. If $a d-b c \neq 0$, we have a unique solution.
- By our criterion for invertibility,


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$ then unless $e d-b f=0, a f-c e=0$, we cannot solve the equations. If $a d-b c \neq 0$, we have a unique solution.
- By our criterion for invertibility, the coefficient matrix is invertible


## A general simple linear system

- Suppose we consider $a x+b y=e, c x+d y=f$. We can easily solve to get $(a d-b c) x=e d-b f,(a d-b c) y=a f-c e$.
- Thus if $a d-b c=0$ then unless $e d-b f=0, a f-c e=0$, we cannot solve the equations. If $a d-b c \neq 0$, we have a unique solution.
- By our criterion for invertibility, the coefficient matrix is invertible if and only if $a d-b c \neq 0$.


## A geometric viewpoint

## A geometric viewpoint

- Solving the above linear system is


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or they intersect in a line or


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or they intersect in a line or they are all of $\mathbb{R}^{2}$.


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or they intersect in a line or they are all of $\mathbb{R}^{2}$.
- Indeed, if $a d-b c=0, e d-b f=0, a f-c e=0$,


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or they intersect in a line or they are all of $\mathbb{R}^{2}$.
- Indeed, if $a d-b c=0, e d-b f=0, a f-c e=0$, they coincide.


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or they intersect in a line or they are all of $\mathbb{R}^{2}$.
- Indeed, if $a d-b c=0, e d-b f=0, a f-c e=0$, they coincide.
- If they intersect non-trivially


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or they intersect in a line or they are all of $\mathbb{R}^{2}$.
- Indeed, if $a d-b c=0, e d-b f=0, a f-c e=0$, they coincide.
- If they intersect non-trivially the area of the "obvious" parallelogram is not zero.


## A geometric viewpoint

- Solving the above linear system is equivalent to finding the intersection set of two lines (Actually, if $a=b=e=0$, then it is just one line and if $a=b=e=c=d=f=0$, it is all of $\mathbb{R}^{2}$ !)
- Either they intersect at a single point or they are parallel and do not intersect or they intersect in a line or they are all of $\mathbb{R}^{2}$.
- Indeed, if $a d-b c=0, e d-b f=0, a f-c e=0$, they coincide.
- If they intersect non-trivially the area of the "obvious" parallelogram is not zero.
- The (signed) area is $\vec{v} \times \vec{w}=(a d-b c) \hat{k}$.


## In three dimensions

## In three dimensions

- For $3 \times 3$ systems,


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)
- By analogy,


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)
- By analogy, the (signed) volume in $n$-dimensions


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)
- By analogy, the (signed) volume in n-dimensions ought to be some complicated polynomial expression in


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)
- By analogy, the (signed) volume in n-dimensions ought to be some complicated polynomial expression in the components.


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)
- By analogy, the (signed) volume in n-dimensions ought to be some complicated polynomial expression in the components.
- This quantity shall be called


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)
- By analogy, the (signed) volume in n-dimensions ought to be some complicated polynomial expression in the components.
- This quantity shall be called the determinant of


## In three dimensions

- For $3 \times 3$ systems, clearly a unique solution implies that the (signed) volume of a parallelopiped is non-zero.
- This volume is $(\vec{u} \times \vec{v}) \cdot \vec{w}$. (The "scalar triple product".)
- By analogy, the (signed) volume in n-dimensions ought to be some complicated polynomial expression in the components.
- This quantity shall be called the determinant of the square matrix formed by the $n$ vectors.
- Note that the (signed) volume of
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations,
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2,3-dimensional volumes behave.
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2,3-dimensional volumes behave. $\left(\overrightarrow{v_{1}}+\overrightarrow{v_{2}}\right) \times \vec{w}=\overrightarrow{v_{1}} \times \vec{w}+\overrightarrow{v_{2}} \times \vec{w}$ and
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2, 3-dimensional volumes behave. $\left(\vec{v}_{1}+\vec{v}_{2}\right) \times \vec{w}=\vec{v}_{1} \times \vec{w}+\vec{v}_{2} \times \vec{w}$ and likewise for the triple product.
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2, 3-dimensional volumes behave. $\left(\vec{v}_{1}+\vec{v}_{2}\right) \times \vec{w}=\vec{v}_{1} \times \vec{w}+\vec{v}_{2} \times \vec{w}$ and likewise for the triple product. So we hope that
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2,3-dimensional volumes behave. $\left(\overrightarrow{v_{1}}+\overrightarrow{v_{2}}\right) \times \vec{w}=\overrightarrow{v_{1}} \times \vec{w}+\vec{v}_{2} \times \vec{w}$ and likewise for the triple product. So we hope that the signed volume in higher dimensions obeys this
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2,3-dimensional volumes behave. $\left(\overrightarrow{v_{1}}+\overrightarrow{v_{2}}\right) \times \vec{w}=\overrightarrow{v_{1}} \times \vec{w}+\vec{v}_{2} \times \vec{w}$ and likewise for the triple product. So we hope that the signed volume in higher dimensions obeys this multi-linearity property as well.
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2,3-dimensional volumes behave. $\left(\vec{v}_{1}+\vec{v}_{2}\right) \times \vec{w}=\overrightarrow{v_{1}} \times \vec{w}+\vec{v}_{2} \times \vec{w}$ and likewise for the triple product. So we hope that the signed volume in higher dimensions obeys this multi-linearity property as well. To prove such a statement,
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2,3-dimensional volumes behave. $\left(\vec{v}_{1}+\vec{v}_{2}\right) \times \vec{w}=\overrightarrow{v_{1}} \times \vec{w}+\vec{v}_{2} \times \vec{w}$ and likewise for the triple product. So we hope that the signed volume in higher dimensions obeys this multi-linearity property as well. To prove such a statement, we can use
- Note that the (signed) volume of $n$-vectors in $\mathbb{R}^{n}, v_{1}, \ldots, v_{n}$ must
- scale with each vector,
- be 1 for the standard basis,
- vanish if two vectors are equal, and
- Since the only operations in a general vector space are linear combinations, we must check how the 2,3-dimensional volumes behave. $\left(\vec{v}_{1}+\vec{v}_{2}\right) \times \vec{w}=\overrightarrow{v_{1}} \times \vec{w}+\vec{v}_{2} \times \vec{w}$ and likewise for the triple product. So we hope that the signed volume in higher dimensions obeys this multi-linearity property as well. To prove such a statement, we can use the Fubini theorem (to be stated much later).


## Definition

## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$.


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact),


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.
- Additivity:

$$
F\left(\ldots, v_{k}+w, \ldots\right)=F\left(\ldots, v_{k}, \ldots\right)+F(\ldots, w, \ldots) .
$$

## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.
- Additivity:
$F\left(\ldots, v_{k}+w, \ldots\right)=F\left(\ldots, v_{k}, \ldots\right)+F(\ldots, w, \ldots) . A$
function that satisfies


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.
- Additivity:
$F\left(\ldots, v_{k}+w, \ldots\right)=F\left(\ldots, v_{k}, \ldots\right)+F(\ldots, w, \ldots) . A$
function that satisfies the first two properties


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.
- Additivity:
$F\left(\ldots, v_{k}+w, \ldots\right)=F\left(\ldots, v_{k}, \ldots\right)+F(\ldots, w, \ldots) . A$
function that satisfies the first two properties is said to be


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.
- Additivity:
$F\left(\ldots, v_{k}+w, \ldots\right)=F\left(\ldots, v_{k}, \ldots\right)+F(\ldots, w, \ldots) . A$
function that satisfies the first two properties is said to be multilinear.


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.
- Additivity:
$F\left(\ldots, v_{k}+w, \ldots\right)=F\left(\ldots, v_{k}, \ldots\right)+F(\ldots, w, \ldots) . A$
function that satisfies the first two properties is said to be multilinear.
- Alternating: $F(\ldots, v, \ldots, v, \ldots)=0$.


## Definition

- Let $v_{1}, v_{2}, \ldots, v_{n}$ be an ordered collection of $n$ vectors in $\mathbb{F}^{n}$. A function $F$ that takes this tuple to $\mathbb{F}$ is called a determinant function if it satisfies the following axioms.
- Scaling: If $v_{k}$ is replaced with $t v_{k}$ (and the other $v_{i} s$ are left intact), then $F$ gets scaled by $t$.
- Additivity:
$F\left(\ldots, v_{k}+w, \ldots\right)=F\left(\ldots, v_{k}, \ldots\right)+F(\ldots, w, \ldots) . A$
function that satisfies the first two properties is said to be multilinear.
- Alternating: $F(\ldots, v, \ldots, v, \ldots)=0$.
- Normalisation: $F\left(e_{1}, \ldots, e_{n}\right)=1$.

Properties of an alternating (not necessarily normalised) multilinear function

# Properties of an alternating (not necessarily normalised) multilinear function 

- Linearity with more than one vector:


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

# Properties of an alternating (not necessarily normalised) multilinear function 

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if


# Properties of an alternating (not necessarily normalised) multilinear function 

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :
$F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0$.


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :
$F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0$.
- (Antisymmetry) If $v_{i} \leftrightarrow v_{j}$


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :
$F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0$.
- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :
$F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0$.
- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign: $F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :

$$
F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0
$$

- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:
$F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence
$F\left(\ldots, v_{i}, \ldots, v_{i}+v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)$.


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW})
\end{aligned}
$$

- It vanishes if some vector is 0 :

$$
F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0
$$

- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:
$F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence
$F\left(\ldots, v_{i}, \ldots, v_{i}+v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)$. Thus
$0+F\left(\ldots, v_{i}, \ldots v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}, \ldots\right)+0$.


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW})
\end{aligned}
$$

- It vanishes if some vector is 0 :

$$
F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0
$$

- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:
$F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence
$F\left(\ldots, v_{i}, \ldots, v_{i}+v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)$. Thus
$0+F\left(\ldots, v_{i}, \ldots v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}, \ldots\right)+0$.
- If the vectors are linearly dependent


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW})
\end{aligned}
$$

- It vanishes if some vector is 0 :

$$
F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0
$$

- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:
$F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence
$F\left(\ldots, v_{i}, \ldots, v_{i}+v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)$. Thus
$0+F\left(\ldots, v_{i}, \ldots v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}, \ldots\right)+0$.
- If the vectors are linearly dependent then $F$ vanishes:


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :

$$
F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0
$$

- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:
$F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence
$F\left(\ldots, v_{i}, \ldots, v_{i}+v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)$. Thus
$0+F\left(\ldots, v_{i}, \ldots v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}, \ldots\right)+0$.
- If the vectors are linearly dependent then $F$ vanishes: Suppose $\sum_{i} c_{i} v_{i}=0$ with $c_{k} \neq 0$.


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :

$$
F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0
$$

- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:
$F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence
$F\left(\ldots, v_{i}, \ldots, v_{i}+v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)$. Thus
$0+F\left(\ldots, v_{i}, \ldots v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}, \ldots\right)+0$.
- If the vectors are linearly dependent then $F$ vanishes: Suppose $\sum_{i} c_{i} v_{i}=0$ with $c_{k} \neq 0$. Then $F=\frac{1}{c_{k}} F\left(\ldots, c_{k} v_{k}, \ldots\right)$ which is


## Properties of an alternating (not necessarily normalised) multilinear function

- Linearity with more than one vector:

$$
\begin{aligned}
& F\left(\ldots, v_{k}+c_{1} w_{1}+c_{2} w_{2}+\ldots+c_{m} w_{m}, \ldots\right)= \\
& F\left(\ldots, v_{k}, \ldots\right)+c_{1} F\left(\ldots, w_{1}, \ldots\right)+\ldots(\mathrm{HW}) .
\end{aligned}
$$

- It vanishes if some vector is 0 :

$$
F(\ldots, 0, \ldots)=0 F(\ldots, 0, \ldots)=0
$$

- (Antisymmetry) If $v_{i} \leftrightarrow v_{j} F$ changes sign:
$F\left(\ldots, v_{i}+v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)=0$ and hence
$F\left(\ldots, v_{i}, \ldots, v_{i}+v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}+v_{j}, \ldots\right)$. Thus
$0+F\left(\ldots, v_{i}, \ldots v_{j}, \ldots\right)=-F\left(\ldots, v_{j}, \ldots, v_{i}, \ldots\right)+0$.
- If the vectors are linearly dependent then $F$ vanishes: Suppose $\sum_{i} c_{i} v_{i}=0$ with $c_{k} \neq 0$. Then $F=\frac{1}{c_{k}} F\left(\ldots, c_{k} v_{k}, \ldots\right)$ which is

$$
\frac{1}{c_{k}} F\left(\ldots,-\sum_{i \neq k} c_{i} v_{i}\right)=\sum_{i \neq k} \frac{-c_{i}}{c_{k}} F\left(\ldots, v_{i}, \ldots, v_{i}, \ldots\right)=0
$$

## Uniqueness theorem

## Uniqueness theorem

- Suppose $d$ is a


## Uniqueness theorem

- Suppose $d$ is a determinant function


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function.


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$.


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function,


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof:


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$.


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then
$f\left(\sum_{j_{1}} c_{j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then $f\left(\sum_{j_{1}} c_{1 j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then
$f\left(\sum_{j_{1}} c_{1 j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide,


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then
$f\left(\sum_{j_{1}} c_{1 j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide, that term will be 0 .


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then $f\left(\sum_{j_{1}} c_{j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide, that term will be 0 . So we may assume that


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then $f\left(\sum_{j_{1}} c_{j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide, that term will be 0 . So we may assume that all the $j_{i}$ are


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then $f\left(\sum_{j_{1}} c_{j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide, that term will be 0 . So we may assume that all the $j_{i}$ are different, i.e.,


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then $f\left(\sum_{j_{1}} c_{j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide, that term will be 0 . So we may assume that all the $j_{i}$ are different, i.e., $j_{1}, j_{2}, \ldots, j_{n}$ is a


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then $f\left(\sum_{j_{1}} c_{j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide, that term will be 0 . So we may assume that all the $j_{i}$ are different, i.e., $j_{1}, j_{2}, \ldots, j_{n}$ is a permutation of


## Uniqueness theorem

- Suppose $d$ is a determinant function and $f$ is an alternatng multilinear function. Then $f\left(v_{1}, \ldots, v_{n}\right)=d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$. So if $f$ is also a determinant function, then $f=d$.
- Proof: Let $v_{i}=\sum_{j} c_{i j} e_{j}$. Then $f\left(\sum_{j_{1}} c_{j_{1}} e_{j_{1}}, \sum_{j_{2}} c_{2 j_{2}} e_{j_{2}}, \ldots\right)=\sum c_{1 j_{1}} c_{2 j_{2}} \ldots f\left(e_{j_{1}}, e_{j_{2}}, \ldots\right)$.
- If any of the $j_{i}$ coincide, that term will be 0 . So we may assume that all the $j_{i}$ are different, i.e., $j_{1}, j_{2}, \ldots, j_{n}$ is a permutation of $1,2, \ldots, n$.


## Uniqueness theorem

## Uniqueness theorem

- We can prove


## Uniqueness theorem

- We can prove by induction on $n$


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges.


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$.


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$.


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things.


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis,


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges.


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way.


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way. Now interchange $j_{k}$ with $j_{n}$ to get


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way. Now interchange $j_{k}$ with $j_{n}$ to get the desired permutation.


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way. Now interchange $j_{k}$ with $j_{n}$ to get the desired permutation.
- Using the above result


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way. Now interchange $j_{k}$ with $j_{n}$ to get the desired permutation.
- Using the above result we see that


## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way. Now interchange $j_{k}$ with $j_{n}$ to get the desired permutation.
- Using the above result we see that

$$
d\left(e_{j_{1}}, \ldots, e_{j_{n}}\right)=(-1)^{K} d\left(e_{1}, \ldots, e_{n}\right)=(-1)^{K} \text { and }
$$

## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way. Now interchange $j_{k}$ with $j_{n}$ to get the desired permutation.
- Using the above result we see that

$$
\begin{aligned}
& d\left(e_{j_{1}}, \ldots, e_{j_{n}}\right)=(-1)^{K} d\left(e_{1}, \ldots, e_{n}\right)=(-1)^{K} \text { and } \\
& f\left(e_{j_{1}}, \ldots, e_{j_{n}}\right)=(-1)^{K} f\left(e_{1}, \ldots, e_{n}\right)= \\
& d\left(e_{j_{1}}, \ldots, e_{j_{n}}\right) f\left(e_{1}, \ldots, e_{n}\right)
\end{aligned}
$$

## Uniqueness theorem

- We can prove by induction on $n$ that any permutation can be obtained by a finite number of interchanges. Indeed, it is trivial for $n=1$. One of $j_{i}$ corresponds to $n$. Suppose it is $j_{k}$. Now $[1,2, \ldots, n-1] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}\right]$ is a permutation of $n-1$ things. By the induction hypothesis, it can be obtained using a finite number of interchanges. That is, $[1,2 \ldots, n] \rightarrow\left[j_{1}, \ldots, j_{k-1}, j_{n}, j_{k+1}, \ldots, j_{n-1}, j_{k}=n\right]$ can be obtained that way. Now interchange $j_{k}$ with $j_{n}$ to get the desired permutation.
- Using the above result we see that

$$
\begin{aligned}
& d\left(e_{j_{1}}, \ldots, e_{j_{n}}\right)=(-1)^{K} d\left(e_{1}, \ldots, e_{n}\right)=(-1)^{K} \text { and } \\
& f\left(e_{j_{1}}, \ldots, e_{j_{n}}\right)=(-1)^{K} f\left(e_{1}, \ldots, e_{n}\right)= \\
& d\left(e_{j_{1}}, \ldots, e_{j_{n}}\right) f\left(e_{1}, \ldots, e_{n}\right) .
\end{aligned}
$$

- Thus $f\left(v_{1}, \ldots, v_{n}\right)=\sum c_{j_{1}} \ldots d\left(e_{j_{1}}, \ldots, e_{j_{n}}\right) f\left(e_{1}, \ldots, e_{n}\right)=$ $d\left(v_{1}, \ldots, v_{n}\right) f\left(e_{1}, \ldots, e_{n}\right)$.

