# Lecture 11 - UM 102 (Spring 2021) 

Vamsi Pritham Pingali

IISc

4 $\square>4$ 吕 1 〈

## Recap

- Computed determinants of


## Recap

- Computed determinants of $2 \times 2$ matrices and


## Recap

- Computed determinants of $2 \times 2$ matrices and upper-triangular matrices.
- Computed determinants of $2 \times 2$ matrices and upper-triangular matrices.
- Proved the expansion-along-the-first-column property
- Computed determinants of $2 \times 2$ matrices and upper-triangular matrices.
- Proved the expansion-along-the-first-column property assuming existence.
- Computed determinants of $2 \times 2$ matrices and upper-triangular matrices.
- Proved the expansion-along-the-first-column property assuming existence. Hence expansion-along-any-column.


## Recap

- Computed determinants of $2 \times 2$ matrices and upper-triangular matrices.
- Proved the expansion-along-the-first-column property assuming existence. Hence expansion-along-any-column.
- Proved existence


## Recap

- Computed determinants of $2 \times 2$ matrices and upper-triangular matrices.
- Proved the expansion-along-the-first-column property assuming existence. Hence expansion-along-any-column.
- Proved existence and by construction,


## Recap

- Computed determinants of $2 \times 2$ matrices and upper-triangular matrices.
- Proved the expansion-along-the-first-column property assuming existence. Hence expansion-along-any-column.
- Proved existence and by construction, the expansion-along-any-row-property.


## Determinant of a transpose

## Determinant of a transpose

- For any $n \times n$ matrix $A$


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence,


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant!


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n$.


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n$. $n=1$ is trivial.


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$.


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$,


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along its first row:


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along its first row: $\operatorname{det}(A)=\sum_{j} A_{1 j}(-1)^{1+j} M_{1 j}$.


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along its first row: $\operatorname{det}(A)=\sum_{j} A_{1 j}(-1)^{1+j} M_{1 j}$. Expand $A^{T}$ along


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along its first row: $\operatorname{det}(A)=\sum_{j} A_{1 j}(-1)^{1+j} M_{1 j}$. Expand $A^{T}$ along its first column:


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along its first row: $\operatorname{det}(A)=\sum_{j} A_{1 j}(-1)^{1+j} M_{1 j}$. Expand $A^{T}$ along its first column: $\operatorname{det}\left(A^{T}\right)=\sum_{j}\left(A^{T}\right)_{j 1}(-1)^{1+j} M_{j 1}^{\prime}$.


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along its first row: $\operatorname{det}(A)=\sum_{j} A_{1 j}(-1)^{1+j} M_{1 j}$. Expand $A^{T}$ along its first column: $\operatorname{det}\left(A^{T}\right)=\sum_{j}\left(A^{T}\right)_{j 1}(-1)^{1+j} M_{j 1}^{\prime}$. But $\left(A^{T}\right)_{j 1}=A_{1 j}$ and


## Determinant of a transpose

- For any $n \times n$ matrix $A \operatorname{det}(A)=\operatorname{det}\left(A^{T}\right)$.
- As a consequence, row operations of the form $R_{i} \rightarrow R_{i}+c R_{j}$ keep the determinant invariant! scaling a row scales the determinant and if two rows are equal the determinant vanishes.
- Proof: We prove by induction on $n . n=1$ is trivial. Assume truth for $n-1$. For $n$, expand $A$ along its first row: $\operatorname{det}(A)=\sum_{j} A_{1 j}(-1)^{1+j} M_{1 j}$. Expand $A^{T}$ along its first column: $\operatorname{det}\left(A^{T}\right)=\sum_{j}\left(A^{T}\right)_{j 1}(-1)^{1+j} M_{j 1}^{\prime}$. But $\left(A^{T}\right)_{j 1}=A_{1 j}$ and $M_{j 1}^{\prime}=M_{1 j}$ by the induction hypothesis.


## Computing determinants using the Gauss-Jordan technique

## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?),


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations to bring it to such a form,


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations to bring it to such a form, we can compute the determinant of the matrix easily.


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations to bring it to such a form, we can compute the determinant of the matrix easily.
- Each time


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations to bring it to such a form, we can compute the determinant of the matrix easily.
- Each time we scale a row by a constant $c_{i}$


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations to bring it to such a form, we can compute the determinant of the matrix easily.
- Each time we scale a row by a constant $c_{i}$ the determinant scales


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations to bring it to such a form, we can compute the determinant of the matrix easily.
- Each time we scale a row by a constant $c_{i}$ the determinant scales and each row-exchange leads to a -1 .


## Computing determinants using the Gauss-Jordan technique

- Since the RREF $U$ of a square matrix $A$ is upper-triangular (why?), and we can use Gauss-Jordan row operations to bring it to such a form, we can compute the determinant of the matrix easily.
- Each time we scale a row by a constant $c_{i}$ the determinant scales and each row-exchange leads to a -1 .
- So $\operatorname{det}(A)=\frac{(-1)^{p} \operatorname{det}(U)}{c_{1} c_{2} \ldots}$.


## An example

## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|($


## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)


## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$


## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant and yield


## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant

$$
\text { and yield }\left|\begin{array}{ccc}
1 & x & x^{2} \\
0 & y-x & y^{2}-x^{2} \\
0 & z-x & z^{2}-x^{2}
\end{array}\right|
$$

## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant
and yield $\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & y-x & y^{2}-x^{2} \\ 0 & z-x & z^{2}-x^{2}\end{array}\right|$
- Scaling gives


## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant and yield $\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & y-x & y^{2}-x^{2} \\ 0 & z-x & z^{2}-x^{2}\end{array}\right|$
- Scaling gives $(y-x)(z-x)\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & 1 & x+y \\ 0 & 1 & x+z\end{array}\right|$


## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant
and yield $\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & y-x & y^{2}-x^{2} \\ 0 & z-x & z^{2}-x^{2}\end{array}\right|$
- Scaling gives $(y-x)(z-x)\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & 1 & x+y \\ 0 & 1 & x+z\end{array}\right|$ which is (after

$$
\left.R_{3} \rightarrow R_{3}-R_{2}\right)
$$

## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant and yield $\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & y-x & y^{2}-x^{2} \\ 0 & z-x & z^{2}-x^{2}\end{array}\right|$
- Scaling gives $(y-x)(z-x)\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & 1 & x+y \\ 0 & 1 & x+z\end{array}\right|$ which is (after

$$
\left.R_{3} \rightarrow R_{3}-R_{2}\right)(y-x)(z-x)\left|\begin{array}{ccc}
1 & x & x^{2} \\
0 & 1 & x+y \\
0 & 0 & z-y
\end{array}\right|
$$

## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant and yield $\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & y-x & y^{2}-x^{2} \\ 0 & z-x & z^{2}-x^{2}\end{array}\right|$
- Scaling gives $(y-x)(z-x)\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & 1 & x+y \\ 0 & 1 & x+z\end{array}\right|$ which is (after
$\left.R_{3} \rightarrow R_{3}-R_{2}\right)(y-x)(z-x)\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & 1 & x+y \\ 0 & 0 & z-y\end{array}\right|$ which is
upper-triangular and hence equal to


## An example

- Compute $\left|\begin{array}{lll}1 & x & x^{2} \\ 1 & y & y^{2} \\ 1 & z & z^{2}\end{array}\right|$ (a Vandermonde determinant)
- $R_{2} \rightarrow R_{2}-R_{1}, R_{3} \rightarrow R_{3}-R_{1}$ do not change the determinant and yield $\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & y-x & y^{2}-x^{2} \\ 0 & z-x & z^{2}-x^{2}\end{array}\right|$
- Scaling gives $(y-x)(z-x)\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & 1 & x+y \\ 0 & 1 & x+z\end{array}\right|$ which is (after
$\left.R_{3} \rightarrow R_{3}-R_{2}\right)(y-x)(z-x)\left|\begin{array}{ccc}1 & x & x^{2} \\ 0 & 1 & x+y \\ 0 & 0 & z-y\end{array}\right|$ which is upper-triangular and hence equal to $(y-x)(z-x)(z-y)$.

The product formula

The product formula

- If $A, B$ are two $n \times n$ matrices,

The product formula

- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of of $B$ by $B_{i}$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e.,
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{\text {th }}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear:
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{t h}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$ which is $t \operatorname{det}\left(\ldots, A B_{i}, \ldots\right)+s \operatorname{det}(\ldots, A v, \ldots)$
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$ which is $t \operatorname{det}\left(\ldots, A B_{i}, \ldots\right)+s \operatorname{det}(\ldots, A v, \ldots)$ and hence $F\left(\ldots, t B_{i}+s v, \ldots\right)=t F\left(\ldots, B_{i}, \ldots\right)+s F(\ldots, v, \ldots)$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$ which is $t \operatorname{det}\left(\ldots, A B_{i}, \ldots\right)+s \operatorname{det}(\ldots, A v, \ldots)$ and hence $F\left(\ldots, t B_{i}+s v, \ldots\right)=t F\left(\ldots, B_{i}, \ldots\right)+s F(\ldots, v, \ldots)$.
(2) alternating:
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$ which is $t \operatorname{det}\left(\ldots, A B_{i}, \ldots\right)+s \operatorname{det}(\ldots, A v, \ldots)$ and hence $F\left(\ldots, t B_{i}+s v, \ldots\right)=t F\left(\ldots, B_{i}, \ldots\right)+s F(\ldots, v, \ldots)$.
(2) alternating: $F\left(\ldots, B_{i}=v, \ldots, B_{j}=v, \ldots\right)=$ $\operatorname{det}(\ldots, A v, \ldots, A v, \ldots)=0$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of of $B$ by $B_{i}$. Recall that the $i^{t h}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$ which is $t \operatorname{det}\left(\ldots, A B_{i}, \ldots\right)+s \operatorname{det}(\ldots, A v, \ldots)$ and hence $F\left(\ldots, t B_{i}+s v, \ldots\right)=t F\left(\ldots, B_{i}, \ldots\right)+s F(\ldots, v, \ldots)$.
(2) alternating: $F\left(\ldots, B_{i}=v, \ldots, B_{j}=v, \ldots\right)=$ $\operatorname{det}(\ldots, A v, \ldots, A v, \ldots)=0$.
- Hence by uniqueness,
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of of $B$ by $B_{i}$. Recall that the $i^{\text {th }}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$ which is $t \operatorname{det}\left(\ldots, A B_{i}, \ldots\right)+s \operatorname{det}(\ldots, A v, \ldots)$ and hence $F\left(\ldots, t B_{i}+s v, \ldots\right)=t F\left(\ldots, B_{i}, \ldots\right)+s F(\ldots, v, \ldots)$.
(2) alternating: $F\left(\ldots, B_{i}=v, \ldots, B_{j}=v, \ldots\right)=$ $\operatorname{det}(\ldots, A v, \ldots, A v, \ldots)=0$.
- Hence by uniqueness, $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(B_{1}, \ldots, B_{n}\right) F\left(e_{1}, \ldots, e_{n}\right)$.
- If $A, B$ are two $n \times n$ matrices, then $\operatorname{det}(A B)=\operatorname{det}(A) \operatorname{det}(B)$. This formula is extremely important.
- Denote the $i^{\text {th }}$ column of of $B$ by $B_{i}$. Recall that the $i^{\text {th }}$ column of $(A B)$, i.e., $(A B)_{i}$ is $A B_{i}$.
- Thus $\operatorname{det}\left((A B)_{1},(A B)_{2},(A B)_{3}, \ldots\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$.
- Fix $A$ and define $F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(A B_{1}, A B_{2}, \ldots\right)$. Note that $F$ is
(1) multilinear: $F\left(\ldots, t B_{i}+s v, \ldots\right)=\operatorname{det}\left(\ldots, A\left(t B_{i}+s v\right), \ldots\right)=$ $\operatorname{det}\left(\ldots, t A B_{i}+s A v, \ldots\right)$ which is $t \operatorname{det}\left(\ldots, A B_{i}, \ldots\right)+s \operatorname{det}(\ldots, A v, \ldots)$ and hence $F\left(\ldots, t B_{i}+s v, \ldots\right)=t F\left(\ldots, B_{i}, \ldots\right)+s F(\ldots, v, \ldots)$.
(2) alternating: $F\left(\ldots, B_{i}=v, \ldots, B_{j}=v, \ldots\right)=$ $\operatorname{det}(\ldots, A v, \ldots, A v, \ldots)=0$.
- Hence by uniqueness,
$F\left(B_{1}, \ldots, B_{n}\right)=\operatorname{det}\left(B_{1}, \ldots, B_{n}\right) F\left(e_{1}, \ldots, e_{n}\right)$. Thus $\operatorname{det}(A B)=\operatorname{det}(B) \operatorname{det}(A)$.


## Invertibility and determinants

## Invertibility and determinants

- If an $n \times n$ matrix $A$


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$.


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent,


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$,


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full.


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full. Thus $A$ is invertible.


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full. Thus $A$ is invertible.
- Therefore,


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full. Thus $A$ is invertible.
- Therefore, $A$ is invertible if and only if $\operatorname{det}(A) \neq 0$.


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full. Thus $A$ is invertible.
- Therefore, $A$ is invertible if and only if $\operatorname{det}(A) \neq 0$.
- Equivalently,


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full. Thus $A$ is invertible.
- Therefore, $A$ is invertible if and only if $\operatorname{det}(A) \neq 0$.
- Equivalently, the set $v_{1}, \ldots, v_{n}$


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full. Thus $A$ is invertible.
- Therefore, $A$ is invertible if and only if $\operatorname{det}(A) \neq 0$.
- Equivalently, the set $v_{1}, \ldots, v_{n}$ is independent if and only if


## Invertibility and determinants

- If an $n \times n$ matrix $A$ is invertible then $A A^{-1}=I$. Thus $\operatorname{det}(A) \operatorname{det}\left(A^{-1}\right)=1$ and hence $\operatorname{det}(A) \neq 0$.
- Recall that if a set of $n$ vectors $v_{1}, \ldots, v_{n}$ from $\mathbb{F}^{n}$ is linearly dependent, then $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right)=0$.
- Thus, if $\operatorname{det}(A) \neq 0$, its columns are linearly independent and hence its column rank is full. Thus $A$ is invertible.
- Therefore, $A$ is invertible if and only if $\operatorname{det}(A) \neq 0$.
- Equivalently, the set $v_{1}, \ldots, v_{n}$ is independent if and only if $\operatorname{det}\left(v_{1}, \ldots, v_{n}\right) \neq 0$.


## Block-diagonal matrices

## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$.


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]$


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{cc}A & 0 \\ 0 & I\end{array}\right]$ satisfies all the


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{cc}A & 0 \\ 0 & I\end{array}\right]$ satisfies all the axioms of multilinear


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{cc}A & 0 \\ 0 & I\end{array}\right]$ satisfies all the axioms of multilinear alternating functions and


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{cc}A & 0 \\ 0 & I\end{array}\right]$ satisfies all the axioms of multilinear alternating functions and hence by uniqueness,


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{cc}A & 0 \\ 0 & I\end{array}\right]$ satisfies all the axioms of multilinear alternating functions and hence by uniqueness, $F\left(A_{1}, \ldots\right)=\operatorname{det}(A) F\left(e_{1}, \ldots\right)=\operatorname{det}(A)$.


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{cc}A & 0 \\ 0 & I\end{array}\right]$ satisfies all the axioms of multilinear alternating functions and hence by uniqueness, $F\left(A_{1}, \ldots\right)=\operatorname{det}(A) F\left(e_{1}, \ldots\right)=\operatorname{det}(A)$. Likewise for $D$.


## Block-diagonal matrices

- Let $A$ be an $n \times n$ matrix and $D$ be an $m \times m$ matrix.
- Then the matrix $M=\left[\begin{array}{cc}A & 0 \\ 0 & D\end{array}\right]$ is an $(n+m) \times(n+m)$ "block diagonal" matrix.
- Note that $M=\left[\begin{array}{ll}A & 0 \\ 0 & I\end{array}\right]\left[\begin{array}{ll}I & 0 \\ 0 & D\end{array}\right]$. So $\operatorname{det}(M)$ is a product of two other determinants.
- The function $F\left(A_{1}, \ldots, A_{n}\right)=\operatorname{det}\left[\begin{array}{cc}A & 0 \\ 0 & I\end{array}\right]$ satisfies all the axioms of multilinear alternating functions and hence by uniqueness, $F\left(A_{1}, \ldots\right)=\operatorname{det}(A) F\left(e_{1}, \ldots\right)=\operatorname{det}(A)$. Likewise for $D$. Thus $\operatorname{det}(M)=\operatorname{det}(A) \operatorname{det}(D)$.


## Change of basis

## Change of basis

- Given a linear map


## Change of basis

- Given a linear map $T: V \rightarrow V$


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always,


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space,


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target.


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ].


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$.


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis.


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$.


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$. Also recall that


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$. Also recall that in an ordered basis


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$. Also recall that in an ordered basis the first column of the matrix


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$. Also recall that in an ordered basis the first column of the matrix associated to $T$


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$. Also recall that in an ordered basis the first column of the matrix associated to $T$ is simply the component vector of $T\left(e_{1}^{\prime}\right)$


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$. Also recall that in an ordered basis the first column of the matrix associated to $T$ is simply the component vector of $T\left(e_{1}^{\prime}\right)$ and likewise


## Change of basis

- Given a linear map $T: V \rightarrow V$ where as always, $V$ is a f.d vector space, how can we define its determinant?
- One naive thing to do is to consider an ordered basis $e_{1}, \ldots, e_{n}$ for both, the domain and the target. Then $T$ is represented by a matrix [ $T$ ]. We can attempt to define $\operatorname{det}(T)$ as $\operatorname{det}([T])$. However, what happens when we change the ordered basis?
- Let $e_{1}^{\prime}, e_{2}^{\prime}, \ldots$ be a new ordered basis. Recall that $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$ for some $P_{j i} \in \mathbb{F}$. Also recall that in an ordered basis the first column of the matrix associated to $T$ is simply the component vector of $T\left(e_{1}^{\prime}\right)$ and likewise for the other columns.


## Change of basis

## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the $e^{\prime}$ s using


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the $e^{\prime}$ s using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$.


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime} s$ as variables


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors"


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication!


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent.


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a non-trivial linear relationship


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the $e^{\prime}$ s using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a non-trivial linear relationship between the basis vectors $e_{i}$.


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the $e^{\prime}$ s using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a non-trivial linear relationship between the basis vectors $e_{i}$. Therefore, $[P]$ is invertible.


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the $e^{\prime}$ s using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{lll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime}\end{array}\right.$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a non-trivial linear relationship between the basis vectors $e_{i}$.
Therefore, $[P]$ is invertible.
- Thus $e^{\prime}[P]^{-1}=e$.


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the $e^{\prime}$ s using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{lll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime}\end{array}\right.$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a non-trivial linear relationship between the basis vectors $e_{i}$.
Therefore, $[P]$ is invertible.
- Thus $e^{\prime}[P]^{-1}=e$. In terms of matrices,


## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} s$ (as opposed to es).
- So we want to "solve" for the es in terms of the e's using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{llll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime} & \ldots\end{array}\right]$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a non-trivial linear relationship between the basis vectors $e_{i}$. Therefore, $[P]$ is invertible.
- Thus $e^{\prime}[P]^{-1}=e$. In terms of matrices,

$$
\left.T\left(e^{\prime}\right)=\left[T\left(e_{1}^{\prime}\right) T\left(e_{2}^{\prime}\right) \ldots\right]\right]=e[T][P]
$$

## Change of basis

- Now $T\left(e_{i}^{\prime}\right)=\sum_{j} P_{j i} T\left(e_{j}\right)$ which is $\sum_{j, k} P_{j i}[T]_{k j} e_{k}$.
- We wish to express $T\left(e_{i}^{\prime}\right)$ in terms of the $e^{\prime} \mathrm{s}$ (as opposed to es).
- So we want to "solve" for the es in terms of the $e^{\prime}$ s using $e_{i}^{\prime}=\sum_{j} P_{j i} e_{j}$. These are simply linear equations!
- Formally treating the es and $e^{\prime}$ s as variables we can form "row vectors" $e=\left[\begin{array}{llll}e_{1} & e_{2} & e_{3} & \ldots\end{array}\right]$ and $e^{\prime}=\left[\begin{array}{lll}e_{1}^{\prime} & e_{2}^{\prime} & e_{3}^{\prime}\end{array}\right.$.
- Now $e^{\prime}=e[P]$ as matrix multiplication! If $[P]$ is not invertible then its rows must be linearly dependent. That would mean a non-trivial linear relationship between the basis vectors $e_{i}$.
Therefore, $[P]$ is invertible.
- Thus $e^{\prime}[P]^{-1}=e$. In terms of matrices, $\left.T\left(e^{\prime}\right)=\left[T\left(e_{1}^{\prime}\right) T\left(e_{2}^{\prime}\right) \ldots\right]\right]=e[T][P]$. Thus $T\left(e^{\prime}\right)=e^{\prime}[P]^{-1}[T][P]$.


## Similar matrices

## Similar matrices

- In other words,


## Similar matrices

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$.


## Similar matrices

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$


## Similar matrices

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be


## Similar matrices

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if


## Similar matrices

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$.
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if


## Similar matrices

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases


## Similar matrices

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis)
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- One can prove
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- One can prove the converse too (HW).
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- One can prove the converse too (HW).
- Now one can see that
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- One can prove the converse too (HW).
- Now one can see that

$$
\operatorname{det}\left([T]^{\prime}\right)=\operatorname{det}\left([P]^{-1}\right) \operatorname{det}([T]) \operatorname{det}([P])=\operatorname{det}([T])
$$

- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- One can prove the converse too (HW).
- Now one can see that $\operatorname{det}\left([T]^{\prime}\right)=\operatorname{det}\left([P]^{-1}\right) \operatorname{det}([T]) \operatorname{det}([P])=\operatorname{det}([T])$. Hence the determinant of
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- One can prove the converse too (HW).
- Now one can see that $\operatorname{det}\left([T]^{\prime}\right)=\operatorname{det}\left([P]^{-1}\right) \operatorname{det}([T]) \operatorname{det}([P])=\operatorname{det}([T])$. Hence the determinant of a linear map can be defined
- In other words, $[T]^{\prime}=[P]^{-1}[T][P]$. Two $n \times n$ matrices $A, B$ are said to be similar if there is an invertible matrix $P$ such that $B=P^{-1} A P$. We just proved that if we change ordered bases using an invertible matrix $P$ (whose columns represent the new basis) then $[T]$ and $[T]^{\prime}$ are similar.
- One can prove the converse too (HW).
- Now one can see that $\operatorname{det}\left([T]^{\prime}\right)=\operatorname{det}\left([P]^{-1}\right) \operatorname{det}([T]) \operatorname{det}([P])=\operatorname{det}([T])$. Hence the determinant of a linear map can be defined by choosing any ordered basis.

