Lecture 32 - UM 102 (Spring 2021)

Vamsi Pritham Pingali

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Recap

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- Def: Let $\vec{\alpha}(t)$ be a piecewise C^1 path on J = [a, b] in \mathbb{R}^n . Let \vec{F} be a vector field defined on the image of $\vec{\alpha}$ and is bounded. The line integral of \vec{F} along $\vec{\alpha}$ is defined as $\int \langle \vec{F}, d\vec{\alpha} \rangle = \int_a^b \langle \vec{F}(\vec{\alpha}(t)), \frac{d\vec{\alpha}}{dt} \rangle dt$ whenever the integral exists.
- In \mathbb{R}^3 it is also denoted as $\int_{\vec{\alpha}} (F_1 dx + F_2 dy + F_3 dz)$.
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- Let u(t): [a, b] → [c, d] be a C¹ function such that u'(t) ≠ 0 for all t ∈ [a, b]. u is 1 − 1 because either u'(t) > 0 for all t or u'(t) < 0 for all t. So t is a function of u and it turns out that t is C¹ in u. Such a u is called a change of parameter. If u' > 0 for all t, u is said to preserve orientation

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| Vamsi Pritham | Pingali | Lecture 32 |
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