

• SECOND FUNDAMENTAL FORM: Let  $(M^n, g)$  be a Riemannian sub-manifold of  $(\tilde{M}^m, \tilde{g})$ .

Def<sup>n</sup>: For any  $p \in M$ , we define the normal sp. to  $M$  at  $p$  by

$$N_p M := \{v \in T_p \tilde{M} \mid \tilde{g}(v, u) = 0 \forall u \in T_p M\}.$$

Then  $NM = \bigsqcup_p N_p M$  can be given the structure of a vector bundle over  $M$ , called the normal bundle. We obtain 2 orthogonal projections since  $T\tilde{M} = NM \oplus TM$ .

(1) Tangential projection:  $\pi^T: T\tilde{M} \rightarrow TM$

(2) Normal projection:  $\pi^\perp: T\tilde{M} \rightarrow NM$

We also denote

$$\mathcal{T}(M|_M) := \Gamma(M, T\tilde{M}|_M).$$

$$\mathcal{N}(M) := \Gamma(M, NM).$$

$\tilde{\nabla}, \nabla$ : Levi-Civita connection on  $(\tilde{M}, \tilde{g})$  &  $(M, g)$  resp.

Recall:  $\nabla_X Y = (\tilde{\nabla}_{\tilde{X}} \tilde{Y})^\perp$ , where  $\tilde{X}$  &  $\tilde{Y}$  are arbitrary extension of  $X$  &  $Y$  to  $\tilde{M}$ .

Def<sup>n</sup>: The second fundamental form of  $M$  is defined to be a map  $\mathbb{II}: \mathcal{T}(M) \times \mathcal{T}(M) \rightarrow \mathcal{N}(M)$

$$\mathbb{II}(X, Y) = (\tilde{\nabla}_{\tilde{X}} \tilde{Y})^\perp$$

where  $\tilde{X}, \tilde{Y}$  are arbitrary extensions of  $X$  &  $Y$  to  $\tilde{M}$ . (2)

Prop 17-1:  $\mathbb{I}(X, Y)$  is

- (a) well defined i.e independent of extension
- (b) bi-linear over  $C^\infty(M)$ .
- (c) Symmetric in  $X, Y$ .

Rk: These follow from the fact that

$$\boxed{\mathbb{I}(X, Y) = \tilde{\nabla}_X \tilde{Y} - \nabla_X Y} \quad \text{Gauss formula.}$$

Prop 17-2 (a) (Weingarten eq): If  $X, Y \in \mathcal{T}(M)$ ,

$N \in \mathcal{N}(M)$ , then

$$\langle \tilde{\nabla}_X N, Y \rangle = - \langle N, \mathbb{I}(X, Y) \rangle$$

Here  $\langle, \rangle = \tilde{g}$ .

b) (Gauss eq<sup>n</sup>):  $\forall X, Y, Z, W \in T_p M$ .

$$\begin{aligned} \tilde{R}_m(X, Y, Z, W) &= R_m(X, Y, Z, W) - \langle \mathbb{I}(X, W), \mathbb{I}(Y, Z) \rangle \\ &\quad + \langle \mathbb{I}(X, Z), \mathbb{I}(Y, W) \rangle \end{aligned}$$

Pf (a)  $0 = X \langle N, Y \rangle = \langle \tilde{\nabla}_X N, Y \rangle + \langle N, \tilde{\nabla}_X Y \rangle$   
 $= \langle \tilde{\nabla}_X N, Y \rangle + \langle N, \nabla_X Y \rangle$   
 $\quad + \langle N, \mathbb{I}(X, Y) \rangle$

$$\nabla_X Y \in \mathcal{T}(M) \Rightarrow \langle N, \nabla_X Y \rangle = 0$$

$$(b) \tilde{R}_m(X, Y, Z, W) = \langle \tilde{\nabla}_X \tilde{\nabla}_Y \tilde{Z} - \tilde{\nabla}_Y \tilde{\nabla}_X \tilde{Z} - \tilde{\nabla}_{[X, Y]} \tilde{Z}, \tilde{W} \rangle$$

$$\langle \tilde{\nabla}_X \tilde{\nabla}_Y \tilde{Z}, \tilde{W} \rangle = \langle \tilde{\nabla}_X (\nabla_Y Z + \text{II}(Y, Z)), \tilde{W} \rangle$$

$$\stackrel{\text{Weingarten}}{\cong} \langle \tilde{\nabla}_X \nabla_Y Z, \tilde{W} \rangle - \langle \text{II}(Y, Z), \text{II}(X, \tilde{W}) \rangle$$

Again writing  $\tilde{\nabla}_X = \nabla_X + \text{II}(X, \cdot)$ , since  $\text{II}(X, \cdot)$  is  $\perp W$ , we have

$$\langle \tilde{\nabla}_X \tilde{\nabla}_Y \tilde{Z}, \tilde{W} \rangle = \langle \nabla_X \nabla_Y Z, \tilde{W} \rangle - \langle \text{II}(Y, Z), \text{II}(X, \tilde{W}) \rangle$$

||| by

$$\langle \tilde{\nabla}_Y \tilde{\nabla}_X \tilde{Z}, \tilde{W} \rangle = \langle \nabla_Y \nabla_X Z, \tilde{W} \rangle - \langle \text{II}(X, Z), \text{II}(Y, \tilde{W}) \rangle$$

$$\text{Also, } \langle \tilde{\nabla}_{[X, Y]} \tilde{Z}, \tilde{W} \rangle = \langle \nabla_{[X, Y]} Z, \tilde{W} \rangle$$

This completes the proof.

HYPERSURFACES. From now on we assume.

$(M^n, g) \subset (\tilde{M}^{n+1}, \tilde{g})$  &  $\tilde{M}$  is oriented.

Lemma 17.3:  $M^n$  is oriented  $\iff \exists$  smooth section

$\nu \in \mathcal{N}(M)$  s.t.  $|\nu| = 1$ .

Def<sup>n</sup>: Given a unit normal section  $\nu \in \mathcal{N}(M)$ , the scalar second fundamental form is defined to

be  $h: \mathcal{T}(M) \times \mathcal{T}(M) \rightarrow \mathbb{R}$ ,

$$h(X, Y) = \langle \text{II}(X, Y), \nu \rangle$$

Since  $|\nu| = 1$ , equivalently  $\text{II}(X, Y) = h(X, Y) \nu$ .

Note: Sign of  $h$  depends on the choice of  $\nu$ . <sup>(4)</sup>

Def<sup>n</sup>: Given  $\nu$ , the shape operator is defined as  $s \in \mathcal{T}'_1(M)$  by.

$$\langle X, sY \rangle = h(X, Y).$$

Rk: 1)  $h(X, Y)$  is symmetric & hence  $s$  is self adjoint i.e.

$$\langle s(X), Y \rangle = \langle X, sY \rangle.$$

2) The Gauss formula & Weingarten & Gauss equation take form.

$$\tilde{\nabla}_X \tilde{Y} = \nabla_X Y + h(X, Y) \nu$$

$$\langle \tilde{\nabla}_X N, \tilde{Y} \rangle = -h(X, Y) = -\langle X, sY \rangle.$$

$$\begin{aligned} \hat{R}_m(X, Y, Z, W) &= R_m(X, Y, Z, W) \\ &\quad - h(X, W)h(Y, Z) + h(X, Z)h(Y, W) \end{aligned}$$

3) Since  $\langle \nabla_X \nu, \nu \rangle = \frac{1}{2} \tilde{X} |\nu|^2 = 0$ , Weingarten

$$\iff \boxed{\tilde{\nabla}_X \nu = -sX}$$

4) If  $(\tilde{M}, \tilde{g}) = (\mathbb{R}^{n+1}, g_{\mathbb{R}^{n+1}})$ , then

$$R_m(X, Y, Z, W) = h(X, W)h(Y, Z) - h(X, Z)h(Y, W)$$

• GAUSS CURVATURE: Since  $S: T_p M \rightarrow T_p M$  is a self adjoint operator,  $\exists$  an o.n.b  $\{E_i\}$  of eigenvectors of  $S$ , i.e.  $SE_i = K_i E_i \forall i$ .

Def<sup>n</sup> 1) The eigenvalues  $\{K_i\}$  are called the principle curvatures of  $(M, g)$  & the corresponding eigen-spaces are called principle directions.

2) The Gaussian curvature of  $M$  is defined to be  $K(M) = \det S = K_1 K_2 \dots K_n$ .

The mean curvature of  $M$  is defined to be

$$H(M) = \frac{\sum K_i}{n}$$

Rk 1)  $K_i$  change by a sign if  $\nu \leftrightarrow -\nu$ . This also changes  $H(M) \leftrightarrow -H(M)$ . A more intrinsic object is mean-curvature vector  $\vec{H}(M) := H(M) \cdot \vec{\nu}$ .

The Gauss curv. does not change if  $n \in 2\mathbb{N}$ .

2)  $M$  is called minimal if  $H(M) = 0$ . These are critical points of the "area functional"

$$M \rightarrow A(M) = \int_M dV_g$$

Th<sup>m</sup> 17.4 (Gauss' th<sup>m</sup> egregium) let  $M \subset \mathbb{R}^3$  be a hypersurface &  $g$  the induced metric. For any  $p \in M$  & any l.i  $X, Y \in T_p M$ ,

$$K(M) = \frac{Rm(X, Y, Y, X)}{|X \wedge Y|^2} =: K(T_p M)$$

So Gauss Curv is an isometry invariant.

Pf: We have already proved that R.H.S is independent of the basis. Let  $X = E_1, Y = E_2$  s.t.  $\{E_1, E_2\}$  o.n.b of  $T_p M$  of eigenvectors. i.e.  $SE_i = K_i E_i, i=1, 2$ . In particular  $h(E_i, E_j) = K_i \delta_{ij}$ . Gauss eq<sup>n</sup>  $\Rightarrow$

$$\begin{aligned} Rm(E_1, E_2, E_2, E_1) &= h(E_1, E_1) h(E_2, E_2) \\ &\quad - h(E_1, E_2)^2 \\ &= K_1 K_2 = K(M). \end{aligned}$$

Th<sup>m</sup> 17.5: let  $(M, g)$  be an abstract Riem. mfd. &  $\Pi \subset T_p M$  be a 2-plane. If  $\tilde{U}_p \subset T_p M$  is a normal, we let  $S_\Pi = \exp_p(\tilde{U}_p \cap \Pi)$ . Then

$$K(\Pi) = K(S_\Pi).$$

where  $K(S_\Pi)$  is the Gauss-curvature of  $S_\Pi$  w/ induced metric  $\tilde{g}$ .

Pf: let  $X, Y$  o.n.basis for  $\Pi$ . Then

$$K(\Pi) = Rm(X, Y, Y, X).$$

$$K(S_\Pi) = \tilde{Rm}(X, Y, Y, X).$$

Claim:  $\text{II}(X, Y) = 0 = \text{II}(X, X) = \text{II}(Y, Y)$ .

If so, then Gauss eq  $\Rightarrow R_m(X, Y, Y, X) = \widetilde{R}_m(X, Y, Y, X)$

So Done!

Pf of Claim: let  $\gamma_x(t) = \exp_p(tX) \subset S_\pi$ . Then Gauss

formula  $\Rightarrow$

$$\mathcal{D}_t \dot{\gamma} = \widetilde{\mathcal{D}}_t \dot{\gamma} + \text{II}(\dot{\gamma}, \dot{\gamma})$$

$\mathcal{D}_t \dot{\gamma} = 0$  since  $\gamma$  is a geodesic in  $M$ . Since on the right we have an orthogonal decomp.

Hence  $\text{II}(\dot{\gamma}, \dot{\gamma}) \equiv 0$ . In particular,  $\text{II}(X, X) = 0$ .

||ly  $\text{II}(Y, Y) = 0$ . Polarization  $\Rightarrow \text{II}(X, Y) = 0$ .

• CURVATURE OF CURVES. Let  $(M^n, g) \subset (\widetilde{M}^m, \widetilde{g})$ .

Prop 17.6: let  $\gamma$  be a curve in  $M$ . For any  $V(t) \in T_{\gamma(t)} M$ , we have

$$\widetilde{\mathcal{D}}_t V = \mathcal{D}_t V + \text{II}(\dot{\gamma}, V)$$

Pf: let  $\{E_i\}$  be a II-v.f along  $\gamma$ .  $\perp V(t) = V^i(t) E_i$ .

Then Gauss formula  $\Rightarrow$

$$\begin{aligned} \widetilde{\mathcal{D}}_t V &= \dot{V}^i E_i + V^i \widetilde{\nabla}_{\dot{\gamma}} E_i \\ &= \dot{V}^i E_i + V^i \nabla_{\dot{\gamma}} E_i + V^i \text{II}(\dot{\gamma}, E_i) \\ &= \mathcal{D}_t V + \text{II}(\dot{\gamma}, V) \end{aligned}$$

Cor 17.7: 1) If  $\gamma$  is a geodesic in  $M$ , then

$$\tilde{D}_t \dot{\gamma} = \underline{\text{II}}(\dot{\gamma}, \dot{\gamma})$$

2) If  $n=2$ ,  $\tilde{M} = \mathbb{R}^3$ , then the

$$K_1^p = \min_{v \in T_p M} \frac{\langle \ddot{\gamma}_v(0), v \rangle}{|v|^2}, \quad K_2 = \max_{v \in T_p M} \frac{\langle \ddot{\gamma}_v(0), v \rangle}{|v|^2}$$

where  $\gamma_v(t) = \exp_p(tv)$ .

Example: 1)  $M = S_R^2 \subset \mathbb{R}^3$ . Let  $p = N$ ,  $v_0 = (1, 0, 0) \in T_N S_R^2$ . Then  $v = (0, 0, 1)$ .

$$\gamma_v(t) = (R \sin(t/R), 0, R \cos(t/R))$$

$$\dot{\gamma}_v = (\sin t/R, 0, \cos t/R)$$

$$\ddot{\gamma}_v(0) = (1/R, 0, 0)$$

$$\text{So } \frac{\langle \ddot{\gamma}_v(0), v \rangle}{|v|^2} = \frac{1}{R}$$

By symmetry  $\forall v \in T_N S_R^2$ ,  $\frac{\langle \ddot{\gamma}_v(0), v \rangle}{|v|^2} = \frac{1}{R}$ .

$$\text{So } K_1 = K_2 = 1/R. \quad K(S_R^2) \equiv 1/R^2$$

More generally if  $M = S_R^n \subset \mathbb{R}^{n+1}$ , if  $\Pi_N = \text{span}\{e_1, e_2\}$  where  $N = (0, 0, \dots, 1)$ . Then for any  $v \in \Pi_N$ ,  $\gamma_v$  is a great circle in  $(x^1, x^2, x^{n+1})$  space. So

$$S_\Pi \cong S_R^2 \quad \& \quad \text{so } K(\Pi) = K(S_\Pi) = 1/R^2$$



By symmetry,  $\forall p \in S_R^n, \forall \Pi \subset T_p S_R^n,$

$$K_p(\Pi) = 1/R^2.$$

(9)

$$\textcircled{2} M^n = \mathbb{H}_R^n := \{(x^0, \dots, x^n) \in \mathbb{R}^{n+1} \mid \langle x, x \rangle = -x_0^2 + \dots + x_n^2\}$$

Assignment problem  $\Rightarrow K_p(\Pi) = -1/R^2 \forall p \in \mathbb{H}_R^n$

& all  $\Pi \subset T_p \mathbb{H}_R^n$ .

Def<sup>n</sup>: We say  $(M, g)$  has constant sectional curvature  $K$  if  $K_p(\Pi) = K \forall p \in M, \forall \Pi \subset T_p M$ .

Prop 17.8: If  $(M, g)$  has constant sectional curvature  $K$ , then

$$Rm(X, Y, Z, W) = K(\langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle)$$

Pf: Let  $F(X, Y, Z, W) = K(\langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle)$ .

$$\begin{aligned} \text{Then } F(X, Y, Y, X) &= K(|X|^2 |Y|^2 - \langle X, Y \rangle^2) \\ &= Rm(X, Y, Y, X). \end{aligned}$$

Moreover  $F$  is curvature like. So.

$$F(X, Y, Z, W) = Rm(X, Y, Z, W).$$

Rk: Locally,  $\left. \begin{aligned} R_{ijkl} &= K g_{ie} g_{jk} - g_{ik} g_{je} \\ R_{jk} &= K(n-1) g_{jk} \\ R &= Kn(n-1) \end{aligned} \right\} \textcircled{10}$

Prop 17.9 (Schur). Let  $n \geq 3$ . If  $\exists K \in C^\infty(M)$ .  
 s.t.  $\forall p \in M, \forall \Pi \subset T_p M, K_p(\Pi) = K(p)$ . Then  
 $K(p) \equiv \text{const}$ .

Pf: Again if  $F(X, Y, Z, W) = \langle X, W \rangle \langle Y, Z \rangle - \langle X, Z \rangle \langle Y, W \rangle$

Then  $Rm_p(X, Y, Z, W) = K(p) \cdot F_p$ .

By Rk,  $R_{ij} = K(p)(n-1) g_{ij}$ .

$n \geq 3 \xrightarrow{\text{Cor 16.9}} K \equiv \text{const}$ .