

MA333: Assignment-2

(due 09/09/19)

Note. Please submit solutions to problems 3(b), (e), (f), 4(c), 5(e), 6(c), (d).

1. (Hyperbolic spaces comparison) Recall that in lecture, we defined the Riemannian metrics $g_{\mathbb{B}_R^n}$ and $g_{\mathbb{U}_R^n}$ on the open unit ball $\mathbb{B}_R^n \subset \mathbb{R}^n$ and the upper half space $\mathbb{U}_R^n \subset \mathbb{R}^{n+1}$ respectively.

- (a) Let \mathbb{R}^{n+1} be equipped with the quadratic form $Q(x) = -(x^0)^2 + (x^1)^2 + \dots + (x^n)^2$, and let $\mathbb{H}_R^n := \{x = (x^0, \dots, x^n) \mid Q(x) = -R^2, x^0 > 0\}$. Show that the bi-linear form

$$-d(x^0)^2 + d(x^1)^2 + \dots + d(x^n)^2$$

induces a Riemannian metric on \mathbb{H}_R^n . We denote this metric by $g_{\mathbb{H}_R^n}$.

- (b) Prove that $(\mathbb{B}_R^n, g_{\mathbb{B}_R^n})$ and $(\mathbb{H}_R^n, g_{\mathbb{H}_R^n})$ are isometric. **Hint.** For $n = 2$, this is simply the Cayley transform from complex analysis. Writing down its real and imaginary parts, should suggest a higher dimensional generalization. For simplicity, first you can assume $R = 1$, and then do the general case by a scaling argument.
- (c) Find an isometry from $(\mathbb{H}_R^n, g_{\mathbb{H}_R^n})$ to $(\mathbb{B}_R^n, g_{\mathbb{B}_R^n})$. **Hint.** Take the stereographic projection from \mathbb{H}_R^n to $(-R, 0, \dots, 0)$.
2. (a) Let C_α be the cone of angle 2α with vertex at the origin. More precisely, C_α is the cone $x^2 + y^2 = z^2 \tan^2 \alpha$, $z > 0$. Endow $C_\alpha \setminus \{0\}$ with the Riemannian metric g_α which is the restriction of the Euclidean metric. Then prove that (C_α, g_α) is isometric to a sector in \mathbb{R}^2 of angle $2\pi \sin \alpha$ by exhibiting an explicit map.
- (b) Let $\gamma : [0, 1] \rightarrow C_\alpha$ be any circle $z = c$ on the cone, and let $X(t)$ be any parallel unit vector field along γ . Calculate the angle between $X(0)$ and $X(1)$.
- (c) Calculate the Christoffel symbols of the Levi-Civita connection of the round metric on \mathbb{S}^2 in spherical coordinates.
- (d) Let $\gamma : [0, 1] \rightarrow \mathbb{S}^2$ be the curve $\varphi = \varphi_0$ and $\theta = 2\pi t$ (in spherical coordinates), and let v be any tangent vector to \mathbb{S}^2 at $\gamma(0)$. Calculate the angle between v and $P_{\gamma, 0, 1}(v)$ in terms of φ_0 , where P_γ is the parallel transport with respect to the Levi-Civita connection of the round metric on \mathbb{S}^2 .

3. Let (\tilde{M}, \tilde{g}) be a Riemannian manifold, and let $M \subset \tilde{M}$ be a smooth hypersurface (ie. a submanifold of codimension one) with the induced Riemannian metric g_M . Denote the respective Levi-Civita connections by $\tilde{\nabla}$ and ∇ . Set $N_p M := (T_p M)^\perp$, the orthogonal complement of $T_p M$ with respect to \tilde{g} .

- (a) Show that $NM := \coprod_{p \in M} N_p M$ can be given the structure of a rank one vector bundle such that $T\tilde{M}|_M \cong TM \oplus NM$ as vector bundles. Moreover, prove that the orthogonal projections $\pi^\top : T\tilde{M}|_M \rightarrow TM$ and $\pi^\perp : T\tilde{M}|_M \rightarrow NM$ are smooth. We denote the set of smooth sections of NM by $\mathcal{N}(M)$.

- (b) The *second fundamental form* $II(X, Y) : \mathcal{T}^1(M) \times \mathcal{T}(M) \rightarrow \mathcal{N}(M)$ is defined by

$$II(X, Y) := (\tilde{\nabla}_X \tilde{Y})^\perp,$$

where \tilde{X} and \tilde{Y} are smooth extensions of X and Y to $\mathcal{T}^1(\tilde{M})$. Prove that $II(X, Y)$ is independent of the extensions and defines a smooth, symmetric, $C^\infty(M)$ bilinear map. Moreover,

$$\tilde{\nabla}_{\tilde{X}}\tilde{Y} = \nabla_X Y + II(X, Y).$$

- (c) (**Weingarten equation.**) Suppose $X, Y \in \mathcal{T}^1(M)$ and $N \in \mathcal{N}(M)$, and let \tilde{X}, \tilde{Y} and \tilde{N} be arbitrary extensions to \tilde{M} , prove that

$$\tilde{g}(\tilde{\nabla}_{\tilde{X}}\tilde{N}, \tilde{Y}) = -g(N, II(X, Y)).$$

- (d) For the problems to follow, we specialise to the case when $\tilde{M} = \mathbb{R}^{n+1}$ with the Euclidean metric, and assume that M is orientable. We denote the inner product on \mathbb{R}^{n+1} by $\langle \cdot, \cdot \rangle$. Prove that there exists a nowhere vanishing smooth section $\vec{N} \in \mathcal{N}(M)$. In particular, NM is a trivial line bundle.
- (e) We normalize so that $\langle \vec{N}, \vec{N} \rangle = 1$. The *scalar second fundamental form* is defined by $h(X, Y) = \langle II(X, Y), \vec{N} \rangle$. If $\gamma : (-\varepsilon, \varepsilon) \rightarrow M$ is any smooth curve, show that

$$\ddot{\gamma}(t) = \mathcal{D}_t \dot{\gamma}(t) + h(\dot{\gamma}, \dot{\gamma})(t) \vec{N}(\gamma(t)),$$

and hence γ is a geodesic if and only if $\ddot{\gamma}$ is everywhere normal to M .

- (f) Let $\Omega \rightarrow \mathbb{R}^{n+1}$ be an open set, $F : \Omega \rightarrow \mathbb{R}$ be a smooth submersion (ie. $\nabla F \neq 0$ on all of Ω), and $M = F^{-1}(0)$ be non-empty. Show that the scalar second fundamental form with respect to the unit normal $\vec{N} = \nabla F / |\nabla F|$ is given by

$$h(V, W) = -\frac{V^i W^j \partial_i \partial_j F}{|\nabla F|^2}.$$

4. Let $c : [0, 1] \rightarrow \mathbb{R}^2$ be a plane curve parametrised by arc length such that c is injective, and set $c(t) = (r(u), z(u))$ with $r > 0$. The surface S obtained by rotating the image of c can be parametrized by

$$(r(u) \cos \theta, r(u) \sin \theta, z(u)),$$

where θ is the rotation angle.

- (a) Show that the metric induced on S from \mathbb{R}^3 is given by $g = du^2 + r^2(u)d\theta$.
- (b) Calculate the Christoffel symbols with respect to the coordinates (u, θ) .
- (c) Show that the geodesics are
1. Meridians obtained by intersecting the surface by planes containing the axis of revolution.
 2. Parallels ($u = \text{const}$) for which $r'(u) = 0$.
 3. The curves $(u(t), \theta(t))$ which when parametrized by arc-length satisfy

$$\left(\frac{du}{dt}\right)^2 + r^2(u(t))\left(\frac{d\theta}{dt}\right)^2 = 0, \text{ and, } r^2(u(t))\frac{d\theta}{dt} = C,$$

where C is some constant associated to the geodesic.

5. (**Divergence of a vector field.**) Let (M, g) be a Riemannian manifold. The *divergence* of a vector field X is defined to be $\text{div}(X) := \text{tr}(\nabla X) = \nabla_i X^i$. The *Hessian* is defined by $\text{Hess}(f)(X, Y) := \nabla_X \nabla_Y f$. The *Laplacian* of a function f is defined to be $\Delta f = \text{tr}(\text{Hess} f) = \nabla_i \nabla^i f$.

- (a) If dV_g is the volume form of g , prove that $L_X dV_g = (\text{div} X) dV_g$, and hence prove that in local coordinates,

$$\text{div} X = \frac{1}{\det g} \partial_i (\sqrt{\det g} X^i).$$

- (b) Calculate the divergence of the vector field

- (c) Show that the Hessian is a section of S^2T^*M , and that $\text{Hess}(f)(X, Y) = g(\nabla_X \nabla f, Y)$.
 (d) Prove that for any function u , and any vector field X , we have,

$$\text{div}(uX) = \langle \nabla u, X \rangle + u \text{div}(X).$$

- (e) Prove that on $\mathbb{R}^n \setminus \{0\}$,

$$\Delta_{\mathbb{R}^n} = \frac{\partial^2}{\partial r^2} + \frac{n-1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \Delta_{\mathbb{S}^{n-1}},$$

where $\Delta_{\mathbb{S}^{n-1}}$ is the Laplacian of the round metric on \mathbb{S}^{n-1} . Use this to prove that the restriction of the coordinate functions x , y and z to \mathbb{S}^2 define eigenfunctions of $\Delta_{\mathbb{S}^2}$. What are the corresponding eigenvalues?

6. (**Analysis on manifolds with boundary.**) Let M be a manifold with boundary ∂M . Note that ∂M is a submanifold of M , and for each $p \in \partial M$, there exists a coordinate chart (U, φ) such that $\varphi(U) = \mathbb{B}_+^n := \{(x^1, \dots, x^n) \mid \sum |x^i|^2 < 1, x^n \geq 0\}$ with $\varphi(p) = 0$. We have the tangent spaces $T_p \partial M = \text{sp}(\partial_1, \dots, \partial_{n-1}) \subset T_p M := \text{sp}(\partial_1, \dots, \partial_n)$. A metric g on M (defined in the same way as in the case of manifolds without boundary) restricts to a metric \tilde{g} on ∂M . We say that $\vec{N} \in \mathcal{N}(\partial M)$ is *inward pointing* at $p \in \partial M$ if there exists a curve $\gamma : [0, \varepsilon] \rightarrow M$ such that $\gamma(0) = p$ and $\gamma'(0) = \vec{N}$.

- (a) Show that a normal field \vec{N} is inward pointing if and only if in every chart (U, φ) as above, \vec{N} has a strictly positive $\partial/\partial x^n$ component.
 (b) Prove that there exists a unique *outward pointing* unit normal field \vec{N} along ∂M (ie. $-\vec{N}$ is inward pointing along ∂M). Moreover, if M is oriented with the corresponding nowhere vanishing form Ω , then $i_{\vec{N}}\Omega$ induces an orientation on ∂M . We call this the positive orientation for ∂M .
 (c) Prove that

$$dV_{\tilde{g}} = i_{\vec{N}} dV_g,$$

where we have used the positive orientation on ∂M to write down the volume form. **Sanity check.** If M is the unit disc in \mathbb{R}^2 and $\partial M = \mathbb{S}^1$ is the boundary circle, then $dV_g = r dr \wedge d\theta$. The outward unit normal is $\vec{N} = \partial/\partial r$, and $i_{\vec{N}} dV_g = d\theta$ is the standard length element on \mathbb{S}^1 , and integration along the circle will be anti-clockwise.

- (d) Let (M, g) be a compact oriented manifold with boundary $(\partial M, \tilde{g})$, and outward normal vector field \vec{N} . If X is any vector field on M , prove that

$$\int_M \text{div} X dV_g = \int_{\partial M} \langle X, \vec{N} \rangle dV_{\tilde{g}}.$$

- (e) Prove the following *Green's identities*:

$$\int_M u \Delta v dV + \int_M \nabla u \cdot \nabla v dV = \int_{\partial M} u \nabla v \cdot \vec{N} d\tilde{V} \quad (1)$$

$$\int_M (u \Delta v - v \Delta u) dV_g = \int_{\partial M} (u \nabla v \cdot \vec{N} - v \nabla u \cdot \vec{N}) d\tilde{V}. \quad (2)$$

- (f) Hence prove that if u is *harmonic*, that is if $\Delta u = 0$, and M is *closed* (that is, without boundary), then u is a constant.