

MA 312 Commutative Algebra / January-April 2015

(Int PhD. and Ph. D. Programmes)

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Lectures : Monday and Thursday ; 11:00–12:30

Venue: MA LH-3 (if LH-1 is not free) / LH-1

Midterms :

Quizzes : (Wed-Lect)

Final Examination :

2. Modules and Submodules

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§ 2 Modules and Submodules

2.A Modules

Let A be a ring. Operations of A on abelian groups V which are compatible with the binary operations of A and V play an important roll. We begin with the following general definition :

2.A.1 Definition An operation of an (arbitrary) set M on an (arbitrary) set X is a map $M \times X \rightarrow X$.

An operation $A \times V \rightarrow V$ of the ring A on an abelian group $(V, +)$ is written multiplicatively, i. e., in the form $(a, x) \mapsto a \cdot x = ax, a \in A, x \in V$, since the elements a and x are of different origin there is no confusion of this notation with the multiplication in A ; similarly, the addition in A and in V both are denoted by $+$. Further, the zero element of A as well as in V is denoted by the same symbol 0 . Furthermore, as in ring theory we adopt the bracket-convention that the operation of A on V has the stronger binding that the addition in V . For $a, b \in A$ and $x, y \in V$ for example we write $ax + by$ for $(ax) + (by)$.

2.A.2 Definitions An abelian group $(V, +)$ together with a (multiplicatively written) operation of A on V is called an A -module if the following conditions holds for all $a, b \in A$ and for all $x, y \in V$:

- (1) $1_A \cdot x = x$. (2) $a(bx) = (ab)x$. (3) $a(x + y) = ax + by$. (4) $(a + b)x = ax + bx$.

The operation of A on V is called the scalar multiplication of A on V and we say that it defines an A -module structure on the abelian group $(V, +)$. In any case without any doubt, to address the A -module structure on V it is common to use simply the term “of A -module V ” or even simply “of module V ”. Instead of A -module one can also write module over A . The ring A is called the scalar ring of V ; the elements of A are called scalars. When modules over a fixed ring A are considered, then the ring A is called the ground ring or base ring.

Modules over a division ring K are called K -vector spaces. The elements of a K -vector space are called vectors. A vector space over the field \mathbb{R} of real numbers (respectively, the field \mathbb{C} of complex numbers) is called a real (respectively, complex) vector space.

From the special distributive laws (3) and (4) we can deduce the following rules :

2.A.3 Rules of Scalar multiplication Let V be an A -module. For $a \in A$ and $x \in V$, we have:

- (1) $a \cdot 0 = 0$ and $0 \cdot x = 0$ for all $a \in A$ and all $x \in V$.
- (2) $(-a)x = a(-x) = -ax$ for all $a \in A$ and all $x \in V$.
- (3) $(-a)(-x) = -((-a)x) = -(-ax) = ax$ for all $a \in A$ and all $x \in V$.
- (4) (General distributive law): For arbitrary families $a_i \in A, i \in I, x_j \in V, j \in J$, of elements such that $a_i = 0$ for almost all $i \in I$ (resp. $x_j = 0$ for almost all $j \in J$), we have :

$$\left(\sum_{i \in I} a_i \right) \left(\sum_{j \in J} x_j \right) = \sum_{i, j \in I \times J} a_i x_j$$

Proof: (1) Immediate from $a \cdot 0 = a(0 + 0) = a \cdot 0 + a \cdot 0$ and $0 \cdot x = (0 + 0) \cdot x = 0 \cdot x + 0 \cdot x$. (2) is clear from the equations $0 = 0 \cdot x = (a + (-a))x = ax + (-a)x$ and $0 = a \cdot 0 = a(x + (-x)) = ax + a(-x)$. For the proof of (4) use (1), (2) and induction. \square

2.A.4 Homothecies Let V be an A -module. Then for each $a \in A$, the map $\vartheta_a : V \rightarrow V$ defined by $x \mapsto ax$ is called the homothecy or stretching by a in V . Therefore we have the map

$$\vartheta : A \rightarrow \text{Maps}(V, V), \quad a \mapsto \vartheta_a : V \rightarrow V.$$

The condition (1) of the definition of an A -module structure says that $\vartheta_1 = \text{id}_V$ i. e., the neutral element of the multiplicative monoid of A operates as the identity on V . (Some authors drop this postulation in the definition of an A -module and say that an A -module is unitary if it holds. However, we will consider only unitary modules.) The condition (3) of the definition of A -module mean that $\vartheta_a : V \rightarrow V$ is an endomorphism of the abelian group $(V, +)$, i. e., $\vartheta_a \in \text{End}(V, +)$. Further, by the conditions (4), (2) and (1) it follows that the map

$$\vartheta : A \rightarrow \text{End}(V, +), \quad a \mapsto \vartheta_a : V \rightarrow V$$

is a ring homomorphism, i. e., $\vartheta_{a+b} = \vartheta_a + \vartheta_b$, $\vartheta_{ab} = \vartheta_a \circ \vartheta_b$ and $\vartheta_1 = \text{id}_V$.

2.A.5 Right Modules Let A be a ring. An A -module in the sense of above Definition 2.A.2 is precisely a left A -module. If the operation of A on V has the properties (1), (3) and (4) with

$$(2') \quad a(bx) = (ba)x \text{ for all } ab \in A \text{ and all } x \in V,$$

then V is called a right A -module. In this case it is convenient to write the operation of A on V on the right side. Then (2') takes the form : $(xb)a = x(ba)$. Left and right modules are interchangeable concepts. If A^{op} denote the opposite ring of A , then the right A -modules (respectively left A -modules) are identical with the left A^{op} -modules (respectively, right A^{op} -modules). Therefore one can restrict to study only one kind of modules. Over a commutative ring the difference between left and right modules is anyway pointless.

2.A.6 Bimodules Sometimes one need to consider many module structures on the same abelian group $(V, +)$. If these module structures are compatible with each other then one use the term multi-module, in particular, bimodule when one considers two compatible module structures.

Suppose that the abelian group $(V, +)$ has a left A -module structure and also a left B -module structure. Then V is called a (A, B) -bimodule if $a(bx) = b(ax)$ for all $a \in A, b \in B, x \in V$ and in this case we use the notation $V =_{A, B} V$.

Suppose that the abelian group $(V, +)$ has a left A -module structure and also a right B -module structure (see a) above). Then V is called a (A, B) -bimodule if $a(xb) = (ax)b$ for all $a \in A, b \in B, x \in V$ and in this case we use the notation $V =_A V_B$.

Analogously, one can define bimodules of the type $V_{A, B}$. — A trivial example of an bimodule structure is supplied on an ordinary module V over a commutative ring A . With a same operation on V it is a (A, A) -bimodule of type ${}_{A, A}V$.

2.A.7 Examples Let A be a ring.

- (1) The trivial group 0 is an A -module in a unique way. In fact the only scalar multiplication is $(a, 0) \mapsto 0$ for all $a \in A$. This A -module is called the **zero module** and is also denoted by 0 .
- (2) Let G be an abelian group. For $x \in G$ and $m \in \mathbb{Z}$, we have $mx := x + \cdots + x$ (m -times). Then the operation $\mathbb{Z} \times G \rightarrow G$ defines a \mathbb{Z} -module structure on G . Conversely, on every \mathbb{Z} -module V the scalar multiplication is given by $(m, x) \mapsto mx := x + \cdots + x$ (m -times) in the abelian group $(V, +)$. Therefore \mathbb{Z} -modules are precisely abelian groups.
- (3) Let A be a ring. The left multiplication $\lambda_a : A \rightarrow A, x \mapsto ax$ by elements $a \in A$ defines an A -module structure on A (whereas the right multiplication $\rho_a : A \rightarrow A, x \mapsto xa$ defines a right A -module structure on A). Then with these operations A is a bimodule ${}_A A_A$.
- (4) Let $R \subseteq A$ be a subring. The restriction of the multiplication $A \times A \rightarrow A$ in the ring A to the subring R , i. e., restriction to $R \times A$ (respectively, to $A \times R$) defines a left R -module (respectively, right R -module) structure on A . For example, the chain $\mathbb{Q} \subseteq \mathbb{R} \subseteq \mathbb{C}$ of fields define a natural \mathbb{R} -vector space structure on \mathbb{C} and natural \mathbb{Q} -vector space structures on \mathbb{R} and on \mathbb{C} . More generally, the restriction of the scalar multiplication $A \times V \rightarrow V$ of the A -module V to $R \times V$ defines an R -module structure on V . In future an A -module V will be considered as an R -module with this natural R -module structure, unless otherwise specified.
- (5) (**Direct products and Direct sums**) Let $V_i, i \in I$, be a family of A -modules. On the abelian groups direct product $\prod_{i \in I} V_i$ and the direct sum $\bigoplus_{i \in I} V_i$ we define the scalar multiplication of an element $a \in A$ on the I -tuple $(x_i)_{i \in I}$ by $a(x_i)_{i \in I} := (ax_i)_{i \in I}$ (componentwise scalar multiplication). These A -modules are called the **direct product** and the **direct sum** of the family $V_i, i \in I$. If all V_i are equal to the same A -module V , then the I -fold direct product of V is the set V^I of all maps from I into V . The common notation $V^{(I)}$ is used for the I -fold direct sum of V . If I is a finite set then $V^I = V^{(I)}$. Moreover, if $I = \{1, \dots, n\}$, then we just denote $V^I = V^{(I)}$ by V^n . Note that $V^0 = 0$ is the zero module.

2.B Submodules

Let A be a ring and let V be an A -module. A subset $W \subseteq V$ is called an **A -submodule** of V (or simply a **submodule** of V) if W is a subgroup of the abelian group V and if the scalar multiplication $A \times V \rightarrow V$ of A on V restricts to a scalar multiplication $A \times W \rightarrow W$ on W , i. e., for all $a \in A$ and $x \in W$ we have $ax \in W$.

An A -submodule W of an A -module V is therefore closed under the multiplication of all scalars $a \in A$. The restriction of the A -module structure on V to W defines an A -module structure on W . In this sense every A -submodule itself is an A -module. In case of vector spaces over a division ring K , K -submodules are also called **K -subvector spaces** or just **K -subspaces**.

2.B.1 Examples Let A be a ring.

- (1) In every A -module V , the zero module 0 and V itself are A -submodules of V ; these are called **trivial submodules** of V .
- (2) In an abelian group, the \mathbb{Z} -modules are precisely the subgroups.
- (3) In any ring A , the A -submodule of the left A -module A (respectively, the right A -module A) are precisely the **left-ideals** (respectively, **right-ideals**) in A .
- (4) Let $V_i, i \in I$ be a family of A -modules. Then the direct sum $\bigoplus_{i \in I} V_i$ is an A -submodule of the direct product $\prod_{i \in I} V_i$. In particular, the I -fold direct sum $V^{(I)}$ of V is an A -submodule of the I -fold direct product V^I of V . Moreover, if I is infinite then $V^{(I)}$ is a proper submodule of V^I .

2.B.2 Criterion for submodule Let A be a ring and let V be an A -module. A subset $W \subseteq V$ is an A -submodule of V if and only if the following three conditions are satisfied: (1) $W \neq \emptyset$.

- (2) For all $x \in W$ and all $y \in W$ we have $x + y \in W$.
- (3) For all $a \in A$ and all $x \in W$ we have $ax \in W$.

Proof: □

We can combine the conditions (2) and (3) in the above criterion in the following condition : for all $a, b \in A$ and for all $x, y \in V$, $ax + by \in W$.

2.B.3 Example (Torsion modules) Let A be a commutative ring and let V be an A -module. An element $x \in V$ is called **torsion** if there exists a non-zero divisor $a \in A$ with $ax = 0$. The zero element $0 \in V$ is a torsion element, since $1 \cdot 0 = 0$. If $x \in V$ is a torsion element and if $c \in A$ is arbitrary, then cx is also torsion element (since $ax = 0$ for some non-zero divisor in A , we also have $a(cx) = c(ax) = 0$). Further, if $y \in V$ is another torsion element, i. e., if $by = 0$ for some non-zero divisor in $b \in A$, then ab is a non-zero divisor in A with $ab(x+y) = bax + aby = 0$ and so $x+y$ is also a torsion element. Therefore by the above criterion *the set of all torsion elements in V* $t(V) = t_A(V) = \{x \in V \mid x \text{ is a torsion element}\}$ is an A -submodule of V . This submodule is called the **torsion-submodule** of V . An A -module V is called **torsion-free** if $t(V) = 0$. If every element of V is torsion, i.e., if $t(V) = V$ then V is called **torsion-module**.

(a) Direct sum of torsion-modules is again a torsion-module. A submodule of a torsion-module is a torsion-module.

(b) Direct product of torsion-free modules is again a torsion-free module. A submodule of a torsion-free module is a torsion-free module.

(c) The A -module A is always torsion-free. In an abelian group (in any \mathbb{Z} -module) torsion-elements are precisely the set of elements of positive order. The \mathbb{Z} -module \mathbb{Q} is torsion-free. Every finite abelian group is a \mathbb{Z} -torsion module. For $n \in \mathbb{N}^*$, let Z_n denote a cyclic group of order n . Then the direct product $\prod_{n \in \mathbb{N}^*} Z_n$ of the \mathbb{Z} -torsion modules Z_n , $n \in \mathbb{N}^*$, is not \mathbb{Z} -torsion module.

2.B.4 Intersection of submodules Let A be a ring, V be an A -module and let $W_i, i \in I$, be a family of A -submodules of V . Then the intersection $\bigcap_{i \in I} W_i$ is also an A -submodule of V .

Proof: Follows immediately from 2.B.2. □

If $x_i, i \in I$, is a family of element in an A -module V , then by 2.B.4 there exists a smallest (with respect to the inclusion) submodule of V which contain all the elements $x_i, i \in I$, namely, the intersection of the family of all submodules which contain $x_i, i \in I$ and this family is non-empty, since V is one of them.

2.B.5 Definition Let A be a ring and let V be an A -module. For a family $x_i, i \in I$, of elements of V , the smallest A -submodule of V containing $x_i, i \in I$, is precisely the subset $\{\sum_{i \in I} a_i x_i \mid (a_i)_{i \in I} \in A^{(I)}\}$ of V . Therefore this A -submodule is denoted by $\sum_{i \in I} Ax_i$ and we say that it is the A -submodule of V generated by the family $x_i, i \in I$. If W is an A -submodule of V and if $W = \sum_{i \in I} Ax_i$ for some family $x_i, i \in I$ in V , then we say that $x_i, i \in I$ is a **generating system** for W . If $X \subseteq V$, then A -submodule of V generated by X is denoted by AX .

For example, the zero A -submodule of V is generated by the $\emptyset \subseteq V$, but it is also generated by $\{0\} \subseteq V$. Every A -module has a generating system, for example the set of all of its elements. An A -submodule with generating system consisting of a single element x is called a **cyclic A -submodule** generated by x and is denoted by Ax . Every element of Ax is of the form ax with $a \in A$, but a need not be unique, i. e., $ax = bx$ for some $a, b \in A$, but $a \neq b$. — The cyclic \mathbb{Z} -modules are precisely the cyclic groups.

2.B.6 Sum of submodules Let A be a ring, V be an A -module and let $W_i, i \in I$ be a family of A -submodules of V . Then the A -submodule W of V generated by the union $\bigcup_{i \in I} W_i$ is precisely

$$\left\{ \sum_{i \in I} x_i \mid x_i \in W_i \text{ for all } i \in I \text{ and } x_i = 0 \text{ for almost all } i \in I \right\}$$

Proof: □

The A -submodule of V constructed in 2.B.6 is called the **sum of submodules** $W_i, i \in I$, and is denoted by $\sum_{i \in I} W_i$. For $I = \{1, \dots, n\}$ it is also denoted by $W_1 + \dots + W_n$ or $\sum_{i=1}^n W_i$. It is

$$W_1 + \dots + W_n = \{x_1 + \dots + x_n \mid x_i \in W_i, i = 1, \dots, n\}$$

2.B.7 Definition An element $x \in V$ is called a linear combination of the family $x_i \in V$, $i \in I$ (with coefficients in A), if there is family a_i , $i \in I$, of elements in A , such that almost all a_i are zero, i. e., there exists an element $(a_i)_{i \in I} \in A^{(I)}$ such that $x = \sum_{i \in I} a_i x_i$; in this case the elements a_i , $i \in I$ are called the coefficients of the linear combination. In general these coefficients are not uniquely determined by the element x .

For calculation with linear combinations we note the two rules : two linear combinations can also be added by adding the coefficients and a linear combination can be multiplied by a scalar $a \in A$ by multiplying the coefficients by a , i. e, if $x_i \in V$, $(a_i)_{i \in I}$, $(b_i)_{i \in I} \in A^{(I)}$ and $a \in A$, then :

$$\sum_{i \in I} a_i x_i + \sum_{i \in I} b_i x_i = \sum_{i \in I} (a_i + b_i) x_i \quad \text{and} \quad a \sum_{i \in I} a_i x_i = \sum_{i \in I} (aa_i) x_i.$$

With this definition : *The A -submodule generated by the system x_i , $i \in I$ is precisely the set of all linear combinations of the family x_i , $i \in I$.*

2.B.8 Definition An A -module V is called finitely generated or a finite A -module if there is generating system for V consisting finitely many elements.

2.B.9 Remark Note that a finite module V need not mean that V has only finitely many elements. For example, the \mathbb{Z} -module \mathbb{Z} has infinitely many elements but it is a finite \mathbb{Z} -module, in fact a cyclic \mathbb{Z} -module (generated by the element 1). Note also the contrast: in group theory finite group mean group with finitely many elements. The abelian group \mathbb{Z} is not a finite group but it is a finite \mathbb{Z} -module.

2.B.10 Proposition *Let A be a ring and let V be an A -module. If V is a finitely generated A -module, then every generating system of V contains a finite generating system.*

Proof: Let $y_1, \dots, y_n \in V$ be a given finite generating system for V , i. e., $V = Ay_1 + \dots + Ay_n$ and let x_i , $i \in I$ be a generating system for V . Then for each $j = 1, \dots, n$, $y_j = \sum_{i \in E(j)} a_{ij} x_i$ with $a_{ij} \in A$ and finite subsets $E(j) \subseteq I$. Then $E := \cup_{j=1}^n E(j)$ is a finite subset of I and the submodule generated by x_i , $i \in E$ contain all the elements y_1, \dots, y_n and hence $V = Ay_1 + \dots + Ay_n \subseteq \sum_{i \in E} Ax_i \subseteq V$. Therefore $V = \sum_{i \in E} Ax_i$, i. e., V is generated by the finite subfamily x_i , $i \in E$. \square

2.B.11 Definition Let A be a ring and let V be an A -module. A generating system X of an A -module V is called minimal generating system for V if it is minimal (with respect to the natural inclusion) in the set $\{Y \mid Y \subseteq V \text{ is a generating system for } V\}$. — If V is finite A -module, then

$$\mu_A(V) := \min\{|X| \mid X \subseteq V \text{ is a generating system for } V\}$$

is called the minimal number of generators for V .

By Proposition 2.B.10 every minimal generating system of a finite A -module is finite. More generally, a generating system x_i , $i \in I$ of an A -module V is called minimal if there is no proper subset $J \neq I$ of I such that x_j , $j \in J$, generate V .

For a minimal system of generators x_i , $i \in I$ of V , the index map $I \rightarrow V$, $i \mapsto x_i$, is injective. Therefore this definition is not essentially more general than the previous one. A minimal generating system never contains the zero element. If V is finitely generated, then by Proposition 2.B.10 every generating system contains a finite generating system and hence also contain a minimal generating system.

An arbitrary module need not have a minimal generating system. For example, the \mathbb{Z} -module \mathbb{Q} does not have minimal generating system, see Exercise 2.2.

2.B.12 Example A minimal generating system of a finite A -module V has at least $\mu_A(V)$ elements and need not have the cardinality $\mu_A(V)$. For example, $\{1\}$, $\{2, 3\}$, $\{p, q \mid \gcd(p, q) = 1\}$ are minimal generating systems for the \mathbb{Z} -module \mathbb{Z} and $\mu_{\mathbb{Z}}(\mathbb{Z}) = 1$. Moreover, for every natural number $m \in \mathbb{N}^*$, there is a minimal generating system for the \mathbb{Z} -module \mathbb{Z} with cardinality m , namely, x_1, \dots, x_m , where $x_i := \prod_{j=1, j \neq i}^m p_j$ and p_1, \dots, p_m are distinct prime numbers.

2.B.13 Theorem *Let A be a ring, V be an A -module and let $Y \subseteq V$ be an infinite generating system for V . Then every generating system $x_i, i \in I$, of V contains a generating system $x_j, j \in J, J \subseteq I$ with $|J| \leq |Y|$.*

Proof: For every $y \in Y$, there exists a finite subset $E(y)$ of I such that $y \in \sum_{i \in E(y)} Ax_i$. Then $x_j, j \in J := \cup_{y \in Y} E(y)$ is a generating system for V , since $V = \sum_{y \in Y} Ay \subseteq \sum_{j \in J} Ax_j \subseteq V$. Note that since Y is infinite, for $I = Y$ and $E_y = E(y), y \in Y$, the assumptions in Corollary 2 below are satisfied and hence $|J| = |\cup_{y \in Y} E(y)| \leq |Y|$ by Corollary 2¹. \square

2.B.14 Corollary *Let A be a ring and let V be an A -module. If V has a countable generating system, then every generating system of V contains a countable generating system.*

Proof: If V is a finite A -module, then the assertion follows directly from Proposition 2.B.10 and if V is not finite, then it follows from Theorem 2.B.13. Moreover, the cardinality argument in the proof of 2.B.13 in this special case is simple: A countable union of countable sets is again countable. \square

2.B.15 Let A be a ring, \mathfrak{a} be a left-ideal in A and let V be an A -module. The set of linear combinations of elements of V with coefficients from the ideal \mathfrak{a} form a submodule of V . This submodule is generated by $ax, a \in \mathfrak{a}, x \in V$ and is denoted by $\mathfrak{a}V$.

The following rules are easy to verify: For left-ideals $\mathfrak{a}, \mathfrak{b}$ in A and A -submodules W, U of V we have: (a) $(\mathfrak{a} + \mathfrak{b})V = \mathfrak{a}V + \mathfrak{b}V$. (b) $\mathfrak{a}(\mathfrak{b}V) = (\mathfrak{a}\mathfrak{b})V$. (c) $\mathfrak{a}(W + U) = \mathfrak{a}W + \mathfrak{a}U$.

2.B.16 Example For a left ideal \mathfrak{a} in a ring A and a natural number $n \in \mathbb{N}$ recursively define the powers of \mathfrak{a} by: $\mathfrak{a}^0 := A, \mathfrak{a}^{n+1} := \mathfrak{a}\mathfrak{a}^n$. Then we have a descending chain of left ideals in A :

$$A = \mathfrak{a}^0 \supseteq \mathfrak{a} \supseteq \mathfrak{a}^2 \supseteq \dots \supseteq \mathfrak{a}^n \supseteq \mathfrak{a}^{n+1} \supseteq \dots$$

— The elements of the power \mathfrak{a}^n of a left-ideal \mathfrak{a} are precisely the finite sums of products $a_1 \cdots a_n$ with $a_i \in \mathfrak{a}, i = 1, \dots, n$. Further, $\mathfrak{a}^m \mathfrak{a}^n = \mathfrak{a}^{m+n}$ for all $m, n \in \mathbb{N}$.

A left-, right-, or two-sided ideal \mathfrak{a} is called **nilpotent** if there exists $m \in \mathbb{N}$ such that $\mathfrak{a}^m = 0$. Clearly, if $\mathfrak{a}^m = 0$, then $a_1 \cdots a_m = 0$ for all $a_1, \dots, a_m \in \mathfrak{a}$. Moreover, we have the following very useful special case of Nakayama's lemma:

2.B.17 Lemma *Let A be a ring and let \mathfrak{a} be a nilpotent left-ideal in A . Let V be an A -module and let $W \subseteq V$ be an A -submodule of V . If $W + \mathfrak{a}V = V$, then $W = V$.*

Proof: It is enough to prove that $W = W + \mathfrak{a}^n V$ for every $n \in \mathbb{N}$. We show this by induction on n . For $n = 0$ the assertion is trivial. By induction hypothesis we have the equalities: $V = W + \mathfrak{a}^n V = W + \mathfrak{a}^n(W + \mathfrak{a}V) = W + \mathfrak{a}^n W + \mathfrak{a}^{n+1} V = W + \mathfrak{a}^{n+1} V$. \square

¹ The Corollary 2 is an easy consequence of the following theorem from set theory:

Theorem *For any infinite set Y , we have $|Y \times Y| = |Y|$. (For the proof of this one need to use Zorn's Lemma.) From this we deduce:*

Corollary 1 *For any two non-empty sets I, Y with one of them infinite, we have $|I \times Y| = \sup\{|I|, |Y|\}$. (We may assume that $|I| \leq |Y|$. Then Y is infinite and $|Y| \leq |I \times Y| \leq |Y \times Y| = |Y|$ by the above theorem and hence $|I \times Y| = |Y|$ by Schröder-Berstein theorem.)*

Corollary 2 *Let Y be an infinite set and let $E_i, i \in I$, be a family of sets with $|I| \leq |Y|$ and $|E_i| \leq |Y|$ for all $i \in I$. Then $|\cup_{i \in I} E_i| \leq |Y|$. (We may assume that $E_i \neq \emptyset$ for all $i \in I$. Since $|E_i| \leq |Y|$, there is a surjective map $g_i: Y \rightarrow E_i$ for each $i \in I$. Then the map $I \times Y \rightarrow \cup_{i \in I} E_i$ with $(i, y) \mapsto g_i(y)$ is also surjective and hence $|\cup_{i \in I} E_i| \leq |I \times Y| = \sup\{|I|, |Y|\} = |Y|$ by Corollary 1.)*

2.B.18 Maximal ideals Let A be a ring. The set of left-ideals in A is ordered by the natural inclusion \subseteq . Its biggest element is the unit ideal A . A maximal element in the set of left-ideal different from A is called a maximal left-ideal. Analogously one can define maximal right-ideals. In commutative ring one simply calls them maximal ideals. Therefore : *A ring is a division ring if and only if its zero ideal is a maximal left-ideal.*

2.B.19 Example In the ring \mathbb{Z} every ideal is of the form $\mathbb{Z}a$ with a uniquely determined natural number $a \in \mathbb{N}$. For $ab \in \mathbb{N}$ the inclusion $\mathbb{Z}a \subseteq \mathbb{Z}b$ is equivalent with $a \in \mathbb{Z}b$ or with an existence of $c \in \mathbb{N}$ such that $a = cb$ and so with the divisibility condition “ b divides a ”. Therefore $\mathbb{Z}a$ is maximal ideal in \mathbb{Z} if and only if $a \neq 1$ and a has no divisors other than 1 and a . But this condition exactly characterize the prime numbers. Therefore it shows that : *$\mathbb{Z}a$ for $a \in \mathbb{N}$ is a maximal ideal in the ring \mathbb{Z} if and only if a is a prime number.* If $a \in \mathbb{N}, a \neq 1$, then a has a prime divisor.

In the zero ring there are no maximal ideals. On the contrary if $A \neq 0$, then it has enough maximal left- and right-ideals by Krull’s theorem. Below we will prove more general result than this.

2.B.20 Maximal submodules Let V be an A -module. Then maximal elements (with respect to the natural inclusion) in the set $\mathcal{S}_A(V)$ of all A -submodules of V are called maximal A -submodules of V . Maximal A -submodules of the A -module A are precisely are maximal ideals in A . Let W be a maximal A -submodule of V and let $x \in V, x \notin W$. Then $W \neq W + Ax$ and by the maximality of W , we have the equality $W + Ax = V$. Therefore W is a cofinite A -submodule in the sense of the following definition.

2.B.21 Definition An A -submodule W of V is called cofinite if there exists finitely many elements $x_1, \dots, x_n \in V$ such that $V = W + Ax_1 + \dots + Ax_n$. Equivalently, the quotient A -module V/W is finitely generated.

If W is a cofinite A -submodule of V , then every A -submodule W' with $W \subseteq W' \subseteq V$ is also cofinite. Every A -submodule of a finite A -module is cofinite.

Below we prove the converse of the above remark that *in any A -module V cofinite A -submodules different from V exists if V has maximal submodules.*

2.B.22 Theorem *Let W be a cofinite A -submodule of an A -module V with $W \neq V$. Then there exists a maximal A -submodule of V which contain W . In particular, in a finite non-zero A -module V there are maximal A -submodules.*

Proof: Let $V = W + Ax_1 + \dots + Ax_n$. Let r be the number such that $W_r := W + Ax_1 + \dots + Ax_{r-1} \neq V$, but $W_r + Ax_r = V$. Then it is enough to prove the theorem for W_r instead of W . We may therefore assume that $W \neq V$ and $W + Ax = V$ for some $x \in V$. Let $\mathfrak{M} := \{W' \mid W' \text{ is a submodule of } V \text{ with } W \subseteq W' \subseteq V\}$. Then $W \in \mathfrak{M}$ and \mathfrak{m} is a non-empty set ordered by the natural inclusion. We note that \mathfrak{M} is inductively ordered. For, if $\mathcal{C} \subseteq \mathfrak{M}$ is a non-empty chain in \mathfrak{M} , then $U' := \cup_{U \in \mathcal{C}} U$ is an upper bound of \mathcal{C} in \mathfrak{M} : Clearly U' is a submodule of V , $W \subseteq U'$, since $\mathcal{C} \neq \emptyset$. Further, since $x \notin U$ for all $U \in \mathcal{C}$, we have $x \notin U'$ and so $U' \neq V$. Now by Zorn’s Lemma there exists a maximal element in \mathfrak{M} and this is a maximal submodule of V which contain W . \square

2.B.23 Corollary *In a finite module $V, V \neq 0$, there are maximal submodules.*

By specializing the above corollary to the finite module $V = A = A \cdot 1$, we note the following:

2.B.24 Corollary (Krull’s Theorem) *Let A be a ring and let \mathfrak{a} be an ideal in A with $\mathfrak{a} \neq A$. Then there exists a maximal ideal \mathfrak{m} in A with $\mathfrak{a} \subseteq \mathfrak{m} \subsetneq A$. In particular, in every non-zero ring, there are maximal left-ideals.*