

# 1 Recap

1. Bendixon, Poincaré-Bendixon, Leinard's theorems.
2. Started the proof of the stable manifold theorem.

## 2 Stable manifold theorem - Proof

To go a little further into detail, note that  $y' = By + G(y)$  where because  $F$  is  $C^1$ , for any  $\epsilon > 0$ , there exists a  $\delta > 0$  such that if  $\|x\| \leq \delta$ ,  $\|y\| \leq \delta$ ,  $\|G(y) - G(x)\| \leq \epsilon\|x - y\|$ . We shall choose  $\epsilon$  later. Let  $U(t)$  be block diagonal with the upper block being  $e^{Pt}$  and everything else being zero. Likewise  $V(t)$  has  $e^{Qt}$  on the lower block. Note that  $e^{Bt} = U + V$ . The Duhamel principle states that

$$y(t) = U(t)y(0) + \int_0^t U(t-s)G(y(s))ds + V(t)y(0) + \int_0^t V(t-s)G(y(s))ds$$

which (for ease of grouping the stable and unstable terms) is

$$y(t) = U(t)y(0) + \int_0^t U(t-s)G(y(s))ds + V(t)(y(0) + \int_0^\infty V(-s)G(y(s))ds) - \int_t^\infty V(t-s)G(y(s))ds.$$

Note that the integral from 0 to  $\infty$  is expected to exist (why?) All the terms except for  $V(t)(y(0) + \int_0^\infty V(-s)G(y(s))ds)$  are expected to go to 0 as  $t \rightarrow \infty$ . Thus for stability to hold, we better require  $(y(0) + \int_0^\infty V(-s)G(y(s))ds)$  to be constant and have the last few components as 0. Indeed, we turn this around and state our mission as solving the integral equation

$$y(t, a) = U(t)a + \int_0^t U(t-s)G(y(s, a))ds - \int_t^\infty V(t-s)G(y(s, a))ds$$

with  $a_{k+1} = a_{k+2} = \dots = 0$ . (We want to choose

$y_i(0) = \psi_i(a_1, \dots, a_k) = -\int_0^\infty V(-s)G(y(s, a_1, \dots, a_k, 0, \dots))ds$  when  $i \geq k+1$ .) In other words, the initial values of  $y_i$  (for  $i \geq k+1$ ) are hopefully graphs of functions of  $y_1(0), \dots$ . Thus if we manage to solve the equation on  $\|(y_1, \dots, y_k)(0)\| < \delta'$  for some  $\delta'$ , then on this set, we have a manifold of dimension  $k$  given as a graph. We shall prove that this manifold is invariant and that it is indeed the stable manifold.

To solve the integral equation for small values of  $(y_1(0), \dots, y_k(0))$ , we use an iteration with  $y^{(0)} = 0$ . Then define

$$y^{(j+1)}(t, a) = U(t)a + \int_0^t U(t-s)G(y^{(j)}(s, a))ds - \int_t^\infty V(t-s)G(y^{(j)}(s, a))ds.$$

As in the usual proof of existence (Picard's theorem), we want to prove that successive iterates get close to each other. Note that

$$\begin{aligned} \|y^{(j+1)}(t, a) - y^{(j)}(t, a)\| &\leq \int_0^t \|U(t-s)\| \|G(y^{(j)}(s, a)) - G(y^{(j-1)}(s, a))\| ds \\ &\quad + \int_t^\infty \|V(t-s)\| \|G(y^{(j)}(s, a)) - G(y^{(j-1)}(s, a))\| ds. \end{aligned} \tag{1}$$

At this point note that  $\|U(t)\| \leq Ke^{-(\alpha+\sigma)t} \forall t \geq 0$  and  $\|V(t)\| \leq Ke^{\sigma t} \forall t \leq 0$  for some constants  $K, \alpha, \sigma > 0$ . (By the HW exercise.) Thus

$$\begin{aligned} \|y^{(j+1)}(t, a) - y^{(j)}(t, a)\| &\leq K \int_0^t e^{-(\alpha+\sigma)(t-s)} \|G(y^{(j)}(s, a)) - G(y^{(j-1)}(s, a))\| ds \\ &\quad + \int_t^\infty Ke^{\sigma(t-s)} \|G(y^{(j)}(s, a)) - G(y^{(j-1)}(s, a))\| ds. \end{aligned} \quad (2)$$

This is one more reason to have the limits from  $t$  to  $\infty$  in the second integral. We assume inductively that  $\|y^{(j)} - y^{(j-1)}\| \leq C_j e^{-\mu t}$  for appropriately chosen  $C_j$  and  $\mu$ . Upon substitution, we see that the induction step can be completed (for instance) if we assume that  $C_j = \frac{C}{2^{j-1}}$  (for some  $C$  to be chosen later) and  $\mu = \alpha$  if  $\epsilon < \frac{\sigma}{4K}$  and  $\|y^{(j)}\| < \delta$  for all  $j$ . Since the induction hypothesis must be met for  $j = 1$ , we see that  $C = K\|a\|$  works. The condition involving  $\delta$  can be met (inductively) if  $\|a\| < \frac{\delta}{2K}$ . We see that we get a Cauchy sequence that converges uniformly in  $t$  (for all  $t \geq 0$ ) to a continuous function  $y$ . By uniform convergence (how), we see that the integral equation is met for all  $t$  and hence by the fundamental theorem of calculus,  $y$  is  $C^1$ . It also satisfies  $\|y\| \leq 2K\|a\|e^{-\sigma t}$  for  $\|a\| < \delta' = \frac{\delta}{2K}$ .

From the integral equation and the initial data, we see that the ODE is satisfied. Moreover,  $y_i(t) = -\int_t^\infty V(t-s)G(y(s, a_1, \dots, a_k, 0, \dots))ds$  for  $i \geq k+1$ . The graph  $S$  given by  $(a_1, \dots, a_k, \psi(a_1, \dots, a_k) = -\int_0^\infty V(-s)G(y(s, a_1, \dots, a_k, 0, \dots))ds)$  turns out to be  $C^1$ . Indeed, it is not hard to prove that  $y$  depends on  $a_1, \dots$  in a  $C^0$  manner by using the successive approximations and induction. To prove that it is  $C^1$  requires more work (and the idea is similar to the proof of differentiable dependence on parameters). One can also show that  $S$  is tangent to the stable subspace at the origin.

For  $\|a\| < \delta'$ , we show that a solution of the integral equation above satisfying  $\|y\| < \delta'$  is unique and hence the one we constructed is *the* solution: Suppose  $\tilde{y}$  is another such solution. Then  $\|\tilde{y} - y\| \leq 2\frac{K}{\sigma}\epsilon M$  where  $M$  is the supremum of  $\|\tilde{y} - y\|$ . Thus we have a contradiction unless  $M = 0$ .

We see using the estimates that as  $t \rightarrow \infty$ ,  $y \rightarrow 0$  if the initial data lies on  $S$ . We need to now prove that if we start with a point close to the origin and not on  $S$ , then  $\|y\|$  cannot be  $\leq \delta$  for all  $t \geq 0$ . This also proves that  $S$  is invariant (why?). Indeed we now prove that if  $y(0) \notin S$  and is small, then  $\|y(t)\| \leq \delta$  cannot be met for all  $t \geq 0$ : Simply use the Duhamel formula to get a contradiction as  $t \rightarrow \infty$ .